# APRIL-ANN - A Pattern Recognizer in Lua (with ANNs) - 


v0.4.1

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## Chapter 1

## Introduction

APRIL-ANN (A Pattern Recognizer In Lua with Artificial Neural Networks) is more than an ANNs toolkit. It is pattern recognizer project.

Simple Lua scripts could be implemented to run ANNs experiments. Some examples are below.

### 1.1 Inline help

Take note that APRIL-ANN offers an inline help with two basic commands:

```
april_help(...)
april_dir(...)
april_list(...)
```

The april_help(object) function takes an object (Lua table, function, userdata, ...) as a parameter and shows the corresponding help via standard output.
The april_dir (object) function takes an object as a parameter and shows the corresponding help via standard output. It is the same as april_help but a lot less verbose.
The april_list (table) function takes a table and shows its content using pairs function. It has nothing to do with inline help, but is useful in a lot of circumstances when developing scripts.

Play a little with it, so execute april_help(ann.components) and after april_help(ann.components.base) and see what happens ;)

If you want to access instance methods documentation, you have two ways:

- Use the operator . . (that is, __concat metamethod) with a class table plus method name string:

```
> april_help(ann.components.base .. "forward")
method Computes forward step with the given token
description: Computes forward step with the given token
parameters:
```

```
            1 An input token (usually a matrix)
```

            1 An input token (usually a matrix)
            2 A boolean indicating if the forward is
            2 A boolean indicating if the forward is
                during_training or not. This information is used by
    ```
                during_training or not. This information is used by
```

```
ann.components.actf objects to apply dropout
during training, and to halve the activation during
validation (or test). It is [optional], by default
is false.
```

outputs:
1 An output token (usually a matrix)

- Declare an instance of the class and execute april_help(obj):

```
> c = ann.components.base()
> april_help(c.forward)
method Computes forward step with the given token
description: Computes forward step with the given token
parameters:
    1 An input token (usually a matrix)
    2 A boolean indicating if the forward is
        during_training or not. This information is used by
        ann.components.actf objects to apply dropout
        during training, and to halve the activation during
        validation (or test). It is [optional], by default
        is false.
```

outputs:
1 An output token (usually a matrix)

### 1.2 Auto-completion

APRIL-ANN incorporates an adaptation of https://github.com/rrthomas/lua-rlcompleter for Lua 5.2, and for the APRIL-ANN object oriented implementation. It allows to auto-complete pathnames, global names, table fields, and object methods, by using the <tab> key.

```
> matrix.<tab><tab>
\begin{tabular}{llll} 
_NAME & dict & fromString & \(\ldots\) \\
_VERSION & fromFilename & fromTabFilename & \(\ldots\) \\
__sliding_window__- & fromHEX & join & \(\ldots\) \\
as & fromMMap & loadImage & \(\ldots\) \\
\(\ldots\) & \(\ldots\) & \(\ldots\) &
\end{tabular}
> matrix.fromTab<tab>
> matrix.fromTabFilename<tab><tab>
fromTabFilename
> matrix.fromTabFilename
```


### 1.3 Serialization

Almost any object can be serialized to a disk file, string or a stream using the function util.serialize(). Similarly, it can be deserialized using util.deserialize() function.

### 1.4 XOR problem

The code described here is at the repo path EXAMPLES/xor.lua. First, we need to create an ANN component object which will be trained:

```
thenet = ann.mlp.all_all.generate("2 inputs 2 logistic 1 logistic")
```

The object thenet is a Multilayer Perceptron (MLP) with 2 inputs, a hidden layer with 2 neurons with logistic activation function, and 1 output neuron with logistic activation function. Some activation functions are available: logistic, tanh, linear, softmax, log_logistic, sin, softsign, softplus, .... (see april_help(ann.components.actf)).

Now, in order to do easy and fast development of scripts, a trainer helper wrapper can be used:

```
bunch_size=4
trainer = trainable.supervised_trainer(thenet, ann.loss.mse(1), bunch_size)
```

The trainer needs the ANN component, the loss function, and the bunch_size. Bunch size is the same as mini-batch size, it is used to train several patterns at the same time, increasing the speed of the experiment. Values between 32 and 64 are tipically used, but in this example onlt 4 is possible, so the XOR problem is composed by 4 patterns.

The next step is to build the component and randomize its weights:

```
trainer:build()
trainer:randomize_weights{
    random = random(1234),
    inf = -0.1,
    sup = 0.1}
```

The weights will be initialized uniformly in the range [inf, sup], using the given random object with 1234 as random seed. It is also possible to indicate if you want to initialize weights.

The components has several learning parameters which needs to be configured:

```
trainer:set_option("learning_rate", 1.0)
trainer:set_option("momentum", 0.5)
trainer:set_layerwise_option("w.*", "weight_decay", 1e-05)
```

Data to train the ANN is defined using matrix and dataset objects. It is possible to build XOR problem on a matrix and use it as training datasets:

```
m_xor = matrix.fromString[[
    4
    ascii
    00
    0 1 1
    101
    1 10
]]
ds_input = dataset.matrix(m_xor, {patternSize={1,2}})
ds_output = dataset.matrix(m_xor, {offset={0,2}, patternSize={1,1}})
```

The variable $m_{-}$xor is a matrix object, loaded from the given string. ds_input is a dataset.matrix object, which traverses the matrix by rows, computing a sliding window of patternSize=\{1,2\}. The desired output of the ANN is another dataset.matrix, but in this case computing the sliding window with size ( 1,1 ) and skipping the first two columns offset $=\{0,2\}$.
Finally, we need to train the ANN:

```
for i=1,10000 do
    local error = trainer:train_dataset{ input_dataset = ds_input,
                                    output_dataset = ds_output }
    print(i, error)
end
```

This code trains the ANN for 10,000 epochs, feeding the ANN with input_dataset and using as desired output the given output_dataset. Patterns are grouped at mini-batches of size 4 (bunch_size), and each training epoch is the training with the full dataset.
This simple example gives you some insight about how to use APRIL-ANN toolkit, but it is not useful in a bit more complicated problems. Next section will explain DIGITS problem, which trains an ANN to classify handwritten digits.

### 1.5 DIGITS task

The task aborded at this section is classification of handwritten digits. The code is at EXAMPLES/digits.lua , and could be executed following this command: april-ann digits.lua. This task uses as data a large PNG image with handwritten digits ordered by columns and rows. Each columns corresponds to each digit class (from 0 to 9 ), and each row contains 10 examples (one for each class). There are 1000 patterns (100 for each clasS). So, first the image is loaded using this code, and converted to a matrix where 0 represents white color and 1 represents black color:

```
digits_image = ImageIO.read(string.get_path(arg[0]).."digits.png")
m1 = digits_image:to_grayscale():invert_colors():matrix()
```

This code uses ImageIO.read function to load the PNG image (you need to compile libpng package), and uses string.get_path function in order to find where the file is located. The image is converted to grayscale, colors are inverted to be $0=$ white and $1=$ black, and finally the corresponding matrix of this image is generated.

Second, the training input and output dataset are generated following this code:

```
-- TRAINING --
train_input \(=\) dataset.matrix(m1,
    \{
    patternSize \(=\) \{16,16\},
    offset \(=\{0,0\}\),
    numSteps \(=\{80,10\}\),
    stepSize \(=\{16,16\}\),
    orderStep \(=\{1,0\}\)
    \})
-- a simple matrix for the desired output
\(\mathrm{m} 2=\operatorname{matrix}(10,\{1,0,0,0,0,0,0,0,0,0\})\)
-- a circular dataset which advances with step -1
train_output = dataset.matrix(m2,
```

    patternSize = {10},
    offset = {0},
    numSteps = {800},
    stepSize = {-1},
    circular = {true}
    })

```

This is a more complicated example of how to create datasets from matrices. The variable train_input is a dataset.matrix generated by a sliding-window of size \(16 x 16\) (the size of one digit), which moves in steps of \(16 \times 16\) (first 16 in columns, and when arrive to the end it moves 16 in rows and returns to column 0 ). The number of patterns (numSteps) is 80 by rows and 10 by columns. The output dataset needs an special matrix which contains only one 1 and 9 zeroes, so the 1 on each pattern will correspond to its class. The dataset.matrix in this case slides backwards (stepSize \(=\{-1\}\) ), so the 1 moves forward, and is circular (window positions out of the matrix take the values of the opposite matrix positions). It has 800 patterns ( 80 x 10 ).

For validation datasets the script is coded similarly:
```

-- VALIDATION --
val_input = dataset.matrix(m1,
{
patternSize = {16,16},
offset = {1280,0},
numSteps = {20,10},
stepSize = {16,16},
orderStep = {1,0}
})
val_output = dataset.matrix(m2,
{
patternSize = {10},
offset = {0},
numSteps = {200},
stepSize = {-1},
circular = {true}
})

```

However, in this case the val_input dataset needs the option parameter offset to not be 0, because validation patterns are the 200 last patterns (it begins at image row position 1280). The first 800 digits are used for training.
The MLP is generated following same steps as for XOR, but in this case the topology description string uses tanh for activation of hidden layer, and \(\log\) _softmax for activation of output layer. In this case the use_fanin and use_fanout flags are set to true, and the error function is multi_class_cross_entropy, which is a version of cross-entropy error function, but mathematically simplified for log_softmax as output activation functions (if you try other output you must use mse). The two-class version of cross-entropy (ann.loss.cross_entropy) is simplified to be used with log_logistic outputs:
```

bunch_size = 64
thenet = ann.mlp.all_all.generate("256 inputs 128 tanh 10 log_softmax")
trainer = trainable.supervised_trainer(thenet,
ann.loss.multi_class_cross_entropy(),
bunch_size)

```
trainer: build()
trainer:randomize_weights\{
```

    random = random(52324),
    use_fanin = true,
    use_fanout = true,
    inf = -1,
    sup = 1,
    }
trainer:set_option("learning_rate", 0.01)
trainer:set_option("momentum", 0.01)
trainer:set_layerwise_option("w.*", "weight_decay", 1e-05)

```

For training, it is needed to declare a table which contains the pair input/output datasets and some specific parameters (i.e. shuffle random object to train each epoch with a different permutation of patterns):
```

training_data = {
input_dataset = train_input,
output_dataset = train_output,
shuffle = random(25234),
}
validation_data = {
input_dataset = val_input,
output_dataset = val_output,
}

```

The final snippet code train the MLP using holdout-validation, following a stopping criterion which depends on the relative value between current_epoch/best_validation_epoch: when this proportion is greater than 2 the training is stopped (that is, MLP training will stop at 200 epochs if the last best validation epoch is at epoch 100; MLP training will stop at 400 epochs if the last best validation epoch is at epoch 200). Stopping criterion is selected using function helper trainable.stopping_criteria.make_max_epochs_wo_imp_relative, and the MLP is trained using the class trainable.train_holdout_validation. This last class receives a table which fields are self-explanatory, and follows a holdout-validation algorithm in its execute method, and after each epoch get_state_string method is used for output facilities.
```

print("\# Epoch Training Validation BestEpoch BestValidation")
stopping_criterion =
trainable.stopping_criteria.make_max_epochs_wo_imp_relative(2)
train_func = trainable.train_holdout_validation{
min_epochs = 4,
max_epochs = 1000,
stopping_criterion = stopping_criterion,
}
clock = util.stopwatch()
clock:go()
epoch_function = function()
local tr_loss = trainer:train_dataset(training_data)
local va_loss = trainer:validate_dataset(validation_data)
return trainer,tr_loss,va_loss
end
while train_func:execute(epoch_function) do
print(train_func:get_state_string())
end
clock:stop()
cpu,wall = clock:read()

```
```

num_epochs = result.last_epoch
printf("\# Wall total time: %.3f per epoch: %.3f\n", wall, wall/num_epochs)
printf("\# CPU total time:%.3f per epoch: %.3f\n", cpu, cpu/num_epochs)
printf("\# Validation error: %f", result.best_val_error)

```

\subsection*{1.6 Final remarks}

This introduction explains you the basic steps to write and execute scripts for pattern recognition using ANNs and the toolkit APRIL-ANN. Please, feel free to use this scripts as initial template for yours ;)

APRIL-ANN has a lot of interesting features. The following list show the most important features, which are detailed in the following sections of this documentation:
- Multidimensional matrix library. It allows to perform efficient mathematical operations in Lua.
- Abstract token definition. A token represents anything, and is used in several parts of the toolkit for information interchange: matrix instances can be wrapperd into a tokens.matrix instance, and they are interchangable in ANN components.
- Dataset abstraction. It has the ability to build powerful sliding windows over matrices. At the same time, it is possible to filter datasets producing new datasets on-the-fly. Two abstraction exists: dataset, and dataset.token.
- Artificial neural networks. Different packages are implemented to perform efficient training of ANNs. Three main concepts: ANN component, loss function and optimization algorithm.
- Trainable package. This package knows all the ANNs stuff, and is a good start point to work with ANNs. Implements a lot of useful code for intrspection, training and testing.
- Random package. The generation of pseudo-random numbers is in this package.
- Automatic differentiation. For more advanced machine learning, an experimental library for automatic differentiation has been added. It allows to specify totally more general models than ANNs abstraction, but with an important loss in efficiency. However, it is useful to do cool things for research with a little implementation effort, before implement them in ANNs.
- Matlab package. It allows to load (not save) matrices and data in MAT format. It stills in experimental phase, but the most important things are available.
- Statistics package. Look here for some statistics standard techniques. PCA, running mean and variance computation, pearson correlation, ...
- Complex numbers. In experimental phase, APRIL-ANN allows to work with complex numbers, and complex matrices.
- Util package. It contains a lot of utilities for Lua script development.
- GZIO package. This is the binding of libZ for load/save of compressed files.
- Image and ImageIO packages. The class Image allows to work with color or gray images. The package ImageIO implements useful functions for generic read/write of images, depending in their extension.

\section*{Chapter 2}

\section*{matrix package}

This documentation is structured as follows:
- Introduction
- Matrix basic methods like dim(), get(), rewrap(), select(), ...
- Data initialization methods like fill(), zeros(), linspace(),...
- Serialization as toString(), toFilename(), ...
- Low level access as size(), stride(), offset(), data(), ...
- Sliding window
- Math operations using stndard operators.
- BLAS API as \(\operatorname{axpy}()\), gemv(), gemm(), ...
- LAPACK API as svd(), inv(),...
- Component-wise operations as \(\tan (), \tanh (), \ldots\)
- Matrix level operations as min(), sum(), eq(), ...
- Indexing and sorting as index(), indexed_fill(), order(), ...
- Matrix functions as repmat(), triu(), ...
- Matrix extensions as real_fftwh(), iterate(), convolution().
- Sparse matrix
- Other matrix flavours
- Matrix dictionaries

\subsection*{2.1 Introduction}

Package matrix could be loaded via the standalone binary, or in Lua with require("aprilann.matrix").
A matrix is a multidimensional data container, by default float data. It is similar to the concept of tensor, as defined in libraries like Torch. This notion of tensor is not to be confused with tensors in physics and engineering, known as tensor fields.
The data would be stored following row_major order by default, but different methods can change the stride of the dimensions. Additionally a matrix can be transposed or not, being the transposition a symbolical state, sharing the same data reference as the non-transposed matrix.
From Lua, a matrix is declared using one of the available constructors:
```

> -- row major constructor
>m1 = matrix(3,3) -- this is a uninitialitzed 3x3 matrix of floats

```
```

> -- It is also possible to receive a table with data (in row-major order)
> m2 = matrix (3,3, {1, 2, 3, 4, 5, 6, 7, 8, 9})
> print(m2)
123
456
7 8 9

# Matrix of size [3,3] in row_major [0x23d5b20 data= 0x23d5e90]

```

Observe that print function shows the same for \(m 2\) and \(m 3\), but internally the data is in different order. The pretty print of a matrix shows the data and a commented line with the size of the matrix and two memory pointers values, the first is the pointer to the \(\mathrm{C}++\) object related with the given matrix, and the second is a pointer to the \(\mathrm{C}++\) data object where values are stored (memory block, explained below).
The matrix and its data is separated to allow the declaration of sub-matrices:
```

> m4 = m2:slice({2,1},{1,3})
> print(m4)
4 5 6

# Matrix of size [1,3] in row_major [0x2218a90 data= 0x23d5e90]

```

In this case, the matrix \(m 4\) is a slice which begins at position \(\{2,1\}\) of matrix \(m 2\), and has sizes \(\{1,3\}\) in each dimension. Note that the matrix pointer is different, but the data pointer is the same as for m2 (any change to m 4 will be reflected at m 2 .)

Besides, it is possible to do a sub-matrix cloning the data (deep copy) if you add to slice method a new boolean argument with true value:
```

> m5 = m2:slice({2,1},{1,3}, true)
> print(m5)
4 5 6

# Matrix of size [1,3] in row_major [0x220c6f0 data= 0x2250d60]

```

A shortcut for slicing is to use the operator \(m\) [...], which has a meaning similar to Matlab or Octave. It is overloaded and it is parsed into a slice or select method call, so, it is slower than using directly the slice or select methods, but it is easier to understand and use. This operator receives as argument a number or a table.
- \(m[n]\) In case of given a number, the operator is equivalent to a m:select \((1, n)\) in case the matrix has more than one dimension, and returns a matrix object with one less dimension. In case of uni-dimensional matrix, this call is equivalent to m:get( \(n\) ) and returns a Lua number value.
- \(m[\{s 1, s 2, \ldots\}]\) In case of given a table, the should be the same length of the matrix number of dimensions. In every dimension position, three possible values could be given:
- A number, indicating an exact dimension position: \(m=m 2[\{2,3\}]\)
- A table, with start and end positions in the dimension: \(m=m 2[\{2,\{1,3\}\}]\)
- A string, with start and end positions in the dimension: \(m=m 2[\{2, \quad 1: 3\) ' \(\}]\)

The following examples are equivalent:
```

> = m2:slice({2,1},{1,3})
4 5 6

# Matrix of size [1,3] in row_major [0xf44470 data= 0xdeae90]

```
```

> = m2[{2, {1,3}]}
4 5 6

# Matrix of size [1,3] in row_major [0xf3c8d0 data= 0xdeae90]

> = m2[{2, '1:3'}]
4 5 6

# Matrix of size [1,3] in row_major [0xe32dc0 data= 0xdeae90]

```

It is possible to use the string shortcut to indicate a whole dimension, or only start/end positions:
```

> = m2[{':', '2:3'}]
2 3
5 6
8 9

# Matrix of size [3,2] in row_major [0xef1260 data= 0xdeae90]

> = m2[{'2:', '2:3'}]
5 %

# Matrix of size [2,2] in row_major [0xe08f50 data= 0xdeae90]

> = m2[{':2', '2:3'}]
2 3
5 6

# Matrix of size [2,2] in row_major [0xf04290 data= 0xdeae90]

```

A different shortcut exists for assignation operator, using newindex metamethod. The matrix will be indexed using [] operator or [\{\}] operator:
```

> -- assigns a 0 to all the row values at columns 2:3
> m2[{ ':', '2:3' }] = 0
> -- assigns another matrix all the row values at columns 2:3
> m2[{ ':', '2:3' }] = matrix(m2:dim(1),2):linspace()
> -- assigns 5 to all the values at position 2 in dimension 1
>m2[2] = 5
> -- assigns 10 to all values less than 3
> m2[m2:lt(3)] = 10

```

\subsection*{2.2 Memory block}

Every matrix has an underlying block of memory which is reinterpreted with the matrix shape (dimension sizes, and offset). It is possible to build a memory block in Lua by using any of the mathcore.block table constructors. Currently, mathcore.block.float, mathcore.block. double and mathcore.block.int32 are available.
```

> b = mathcore.block.float{1,2,3,4,5} -- initialized to a table
> print(b)
1 2 3 4 ... 5

# Float block size 5 [data= 0x1ab98e0]

> b = mathcore.block.float(20) -- not initialized

```

Every memory block has three basic methods:
- \(\mathrm{n}=\mathrm{b}: \operatorname{size}()\) returns the number of elements in the memory block.
- \(\mathrm{v}=\mathrm{b}: \mathrm{raw}_{\mathrm{g}} \mathrm{get}(\mathrm{p})\) returns the value at the given p position. Note that the position is \(\mathbf{0}\)-indexed as in C, because this is a low-level \(\mathrm{C}++\) method.
- b:raw_set ( \(\mathrm{p}, \mathrm{v}\) ) sets vas the value at the given p position. Note that the position is 0-indexed as in C.

Like in matrix objects, it is possible to use operator []:
- \(\mathrm{v}=\mathrm{b}[\mathrm{p}]\) is equivalent to \(\mathrm{v}=\mathrm{b}: \mathrm{raw}_{\mathrm{r}}\) get ( p\()\).
- \(b[p]=v\) is equivalent to \(b: r a w \_s e t(p, v)\).

Remember that memory blocks are indexed from 0 , like in C , because they are a wrapper around a C pointer.

\subsection*{2.3 Hints}

NOTICE: Almost all matrix methods returns the caller matrix (when it is possible), allowing to chain transformation sequences.
NOTICE: In Lua the arrays start at 1 instead of 0 , so, in the matrix methods the dimensions start at 1 .

\subsection*{2.4 Constructor}

There are different valid matrix constructors.
- \(m=\) matrix (d1, d2, ..., dn) a list of dimension sizes.
- m = matrix (d1, d2, ..., dn, table) a list of dimension sizes besides an array table with all the matrix elements in row-major order.
- m = matrix (d1, d2, ..., dn, block) a list of dimension sizes plus a float memory block (mathcore.block.float).
- \(m=\operatorname{matrix}\{e 1, e 2, \ldots\), en \(\}\) creates a one-dimensional matrix with the given data elements.
- \(m=\) matrix(block) creates a one-dimensional matrix with the given float memory block as data.

\subsection*{2.5 MMapped matrix}
\(\mathrm{m}=\operatorname{matrix}\). MMapped (...)
It is possible to force the declaration of matrix memory as a mmapped anonymous file. This function receives exactly same arguments as the default matrix constructor.
```

> -- the following matrix will be allocated as mmapped memory
> -- shared when forking the process
> m = matrix.MMapped(2,2):linear()
> print(m)
0 1
2 3

# Matrix of size [2,2] stride [2,1] ref [0x14c1f50 data= 0x14c2020]

```

Another way is to serialize a matrix in MMap format (see serialization section).

\subsection*{2.6 Basic matrix methods}

\subsection*{2.6.1 dim}
```

[table | number] = m:dim([number])

```

It returns the size of matrix dimensions. Without arguments, it returns a Lua table with the sizes. If an argument is given, it returns the size of the given dimension.
```

> a = matrix(4,3,2)
> = a:dim()
table: 0x23a4780
> = table.concat(a:dim(), " ")
4 2
> = a:dim(1), a:dim(2), a:dim(3)
4 2

```

\subsection*{2.6.2 get}
```

number = m:get(p1, p2, ...)

```

This method returns the value of a given matrix position.
```

> a = matrix(3,4,{1,2,3,4, 5,6,7,8, 10,11,12,13})
> = a:get(1,1)
1
> = a:get (2,3)
7

```

\section*{2.6 .3 set}
```

matrix = m:set(p1, p2, ..., value)

```

This method sets the value of a matrix position, and returns the caller matrix, allowing a sequence of sets.
```

> a = matrix(3,4,{1,2,3,4, 5,6,7,8, 10,11,12,13})
> a:set(2,3, 10000)
> a:set(2,4, 500):set(4,1, 200)
> = a
1234
5 6 10000 500
2001112 13

# Matrix of size [3,4] in row_major [0x27093d0 data= 0x2709960]

```

\subsection*{2.6.4 clone}
```

matrix = m:clone()

```

It allows to clone matrices (deep copy). If the caller matrix was transposed, the resulting clone will contain the data in a transposed shape, but with its stride in row major order.
```

> a = matrix(2,3,{1,2,3, 4,5,6}) -- row major matrix
> b = a:clone() -- clone (or deep copy) of a
> c = a:transpose() -- clone of a with different order
> c = c:clone() -- clone of a in row major order

```

\subsection*{2.6.5 copy_from_table}
```

matrix = m:copy_from_table(table)

```

This method copies the data in the given table into the caller matrix, traversing the matrix in row_major order, as in matrix constructor. The table must fit in matrix size. The caller matrix is returned.
```

> a = matrix (2,3)
> a:copy_from_table({1,2,3, 4,5,6})

```

\subsection*{2.6.6 map}
```

matrix = m:map(m1, m2, ..., function)

```

Maps the matrix values by a given list of matrices and a Lua map function. The Lua function will be called for every possible matrix position. The Lua function receives the caller matrix value at the given position, the value of the second matrix, the value of the third matrix, and so on. The Lua function returns nil, or only one value which will be assigned to the caller matrix in-place. All the matrices must have the same dimension sizes. The number of given matrices could be \(>=0\).
```

> m = matrix(2,2):linear()
> m2 = matrix(2,2):linear(10)
> m3 = matrix(2,2):linear(100)
> m
0

# Matrix of size [2,2] in row_major [0x1f12050 data= 0x1f0f6a0]

> = m2
10 11
1 2 ~ 1 3

# Matrix of size [2,2] in row_major [0x1f11cc0 data= 0x1f12110]

> = m3
100 101
102 103

# Matrix of size [2,2] in row_major [0x1f12740 data= 0x1f11e00]

> m:map(m2,m3,function(x,y,z) return x+y+z end)
> = m
110 113
116 119

# Matrix of size [2,2] in row_major [0x1f12050 data= 0x1f0f6a0]

```

\subsection*{2.6.7 rewrap}
```

matrix = m:rewrap(size1, size2, ...)

```

This method only works if the data is contiguous in memory. The caller matrix is reinterpreted as if it was of another number of dimensions and sizes. A different matrix instance is returned, but the data pointer is shared.
```

> a = matrix(2,3,{1,2,3, 4,5,6})
> = a
123
45

```
```


# Matrix of size [2,3] in row_major [0x2700850 data= 0x2700900]

> b = a:rewrap (3,2)
> = b
12
34
5 6

# Matrix of size [3,2] in row_major [0x2701360 data= 0x2700900]

```

\subsection*{2.6.8 select}
```

matrix = m:select(dimension, index [, matrix])

```

This methods returns a matrix with one less dimension, resulting of select at the caller matrix the indicated dimension at the given index. The resulting matrix references the internal data of original matrix. If given, the third argument must be a matrix which will be used to store the result of the select call, and must fit the expected dimensions. In this last case, the computation effort is dismissed to constant.
```

>m = matrix(4,3):zeros()
> m
0 0
0 0
0 0
0 0 0

# Matrix of size [4,3] [0x23dcab0 data= 0x23727e0]

> = m:select(2,2):fill(9)
9 9 9 9

# Matrix of size [4] [0x23dd330 data= 0x23727e0]

> = m:select(1,3):fill(4)
44

# Matrix of size [3] [0x23dd790 data= 0x23727e0]

> = m
0 9 0
0 0
44
0 9 0

# Matrix of size [4,3] [0x23dcab0 data= 0x23727e0]

```

NOTE that the third argument matrix must be created by a previous call to select over the same dimension (but not the same index). As example, the following design pattern gives the same variable as third argument result and as left-side of the expression, allocating the memory in the first loop iteration, and reusing it in the following:
```

> m = matrix(4,5):linear()
> for i=1,m:dim(2) do
result = m:select(2,i,result)
end

```

\subsection*{2.6.9 transpose}
```

matrix = m:transpose()

```

This method returns a matrix which is a transposition of the caller object. Note that both, the caller and the transposition, reference the same data.
```

> m = matrix(3,4):linear()
> = m

| 0 | 1 | 2 | 3 |
| :--- | :--- | :--- | :--- |
| 4 | 5 | 6 | 7 |
| 8 | 9 | 10 | 11 |

# Matrix of size [3,4] in row_major [0x2777140 data= 0x27799b0]

> = m:transpose()

| 0 | 4 | 8 |
| :--- | :--- | :--- |
| 1 | 5 | 9 |
| 2 | 6 | 10 |
| 3 | 7 | 11 |

# Matrix of size [4,3] in row_major [0x274e620 data= 0x27799b0]

```

\subsection*{2.6.10 slice}
```

matrix = m:slice(position, size [, clone])

```

This methods produces a sub-matrix of the caller matrix. By default, the returned sub-matrix shares the data pointer with the caller, but it is also possible to do a deep copy sub-matrix. The syntax is:
```

m:slice(pos_table, size_table, clone=false)

```
being pos_table a Lua table with the position of first element (starting at 1 , not 0 ), and size_table a Lua table with the size of each dimension. The last argument, clone, is an optional boolean (by default false) indicating if the resulting matrix will be a clone or not.
```

> a = matrix(3,4,{1,2,3,4, 5,6,7,8, 10,11,12,13}) -- row major matrix
> = a
1234
5 678
10 11 12 13

# Matrix of size [3,4] in row_major [0x2706530 data= 0x2706b00]

> b = a:slice({2,1},{2,2}) -- slice at position (2,1) with size 2x2
> = b
5 6
10 11

# Matrix of size [2,2] in row_major [0x2707cd0 data= 0x2706b00]

> -- same slice as before but making a clone (deep copy)
> b = a:slice({2,1},{2,2}, true)
> b
5 6
10 11

# Matrix of size [2,2] in row_major [0x2708a20 data= 0x2708ad0]

```

\subsection*{2.6.11 operator[]}

\subsection*{2.6.11.1 Right hand side operator (___index)}
```

matrix = m[number]

```

A shortcut for select or get methods. The operator is equivalent to a m: select \((1, n)\) in case the matrix has more than one dimension, and returns a matrix object with one less dimension. In case of uni-dimensional matrix, this call is equivalent to \(\mathrm{m}: \operatorname{get}(\mathrm{n})\) and returns a Lua number value.

This operator can be used in left and/or right hand of an assignment. In the right hand:
- \(m[k e y]=\) number is equivalent to \(m[k e y]: f i l l(\) number \()\) in case the right-hand is a number.
- \(\mathrm{m}[\mathrm{key}]=\) matrix is equivalent to \(\mathrm{m}[\mathrm{key}]: \operatorname{copy}(\) matrix \()\) in case the right-hand is a matrix.
matrix \(=m[\{s 1, s 2, \ldots\}]\)
A shortcut for slicing, using the __index metamethod. It is similar to Matlab or Octave slice operators. The call is parsed and converted into a slice method call, so, it is slower than using directly the slice method, but it is easier to understand. This operator receives a variable number of arguments, as many as dimensions has the caller matrix object. In every dimension position, three possible values could be given:
- A number, indicating an exact dimension position: \(m=m 2[\{2,3\}]\)
- A table, with start and end positions in the dimension: \(m=m 2[\{2,\{1,3\}\}]\)
- A string, with start and end positions in the dimension: \(m=m 2[\{2, \quad 1: 3\) ' \(\}]\)

The following examples are equivalent:
```

> = m2:slice({2,1},{1,3})
4 5 6

# Matrix of size [1,3] in row_major [0xf44470 data= 0xdeae90]

> = m2[{2, {1,3}}]
4 5 6

# Matrix of size [1,3] in row_major [0xf3c8d0 data= 0xdeae90]

> = m2[{2, '1:3'}]
4 5 6

# Matrix of size [1,3] in row_major [0xe32dc0 data= 0xdeae90]

```

It is possible to use the string shortcut to indicate a whole dimension, or only start/end positions:
```

> = m2[{':', '2:3'}]
2 3
5 6
8 9

# Matrix of size [3,2] in row_major [0xef1260 data= 0xdeae90]

> = m2[{'2:', '2:3'}]
5

# Matrix of size [2,2] in row_major [0xe08f50 data= 0xdeae90]

> = m2[{':2', '2:3'}]
2 3
5 6

# Matrix of size [2,2] in row_major [0xf04290 data= 0xdeae90]

```

\subsection*{2.6.11.2 Left hand side operator (___ newindex)}
m [key] = value
Different cases depending in the type of key and the type of value.
- \(k e y=\) number, value=number: it is equivalent to m:select(1,key):fill(value)
- key=number, value=matrix: it is equivalent to m: select (1, key) :copy (value)
- key=table, value=number: it is equivalent to \(m[k e y]: f i l l(v a l u e)\)
- key=table, value=matrix: it is equivalent to m[key] :copy (value)
- key=matrixBool, value=number: it is equivalent to m:masked_fill(key, value)
- key=matrixBool, value=matrix: it is equivalent to m:masked_copy(key, value)
```

> -- assigns a 0 to all the row values at columns 2:3
> m2[{ ':', '2:3' }] = 0
> -- assigns another matrix all the row values at columns 2:3
> m2[{ ':', '2:3' }] = matrix(m2:dim(1),2):linspace()

```

\subsection*{2.6.12 join}
```

matrix = matrix.join(dimension, m1, m2, ...)

```

This function joins the given matrices by the given dimension. All the dimensions of the matrices must be the same, except the given dimension, which could differ. It is possible to add a new axis at left and join all matrices using the new added axis given a dimension=0 parameter. Similarly, it is possible to add a new axis at right for joining all matrices using this new axis given a dimension=num_dims+1, being num_dim the number of dimensions of the given matrices.

Warning, this method duplicates the memory needed, because all the matrices are copied to the destination matrix.
```

> m1 = matrix(10,2):linear()
> m2 = matrix(10,3):linear()
> outm = matrix.join(2, m1, m2)
> = outm

| 0 | 1 | 0 | 1 | 2 |
| :--- | :--- | :--- | :--- | :--- |
| 2 | 3 | 3 | 4 | 5 |
| 4 | 5 | 6 | 7 | 8 |
| 6 | 7 | 9 | 10 | 11 |
| 8 | 9 | 12 | 13 | 14 |
| 10 | 11 | 15 | 16 | 17 |
| 12 | 13 | 18 | 19 | 20 |
| 14 | 15 | 21 | 22 | 23 |
| 16 | 17 | 24 | 25 | 26 |
| 18 | 19 | 27 | 28 | 29 |

# Matrix of size [10,5] in row_major [0x1f9c100 data= 0x1f9c1c0]

>
m1 = matrix(10,3):linear()
-- m2 remains the same
-- add new axis at left
= matrix.join(0, m1, m2)

# pos [1,1,1]

| 0 | 1 | 2 |
| :--- | :--- | :--- |
| 3 | 4 | 5 |
| 6 | 7 | 8 |
| 9 | 10 | 11 |
| 12 | 13 | 14 |
| $\cdots$ |  |  |
| 27 | 28 | 29 |

```
```


# pos [2,1,1]

| 0 | 1 | 2 |
| :--- | :--- | :--- |
| 3 | 4 | 5 |
| 6 | 7 | 8 |
| 9 | 10 | 11 |
| 12 | 13 | 14 |
| $\ldots$ |  |  |
| 27 | 28 | 29 |

# Matrix of size [2,10,3] stride [30,3,1] ref [0x1940f90 data= 0x177c280]

>
> -- add new axis at right
> = matrix.join(3, m1, m2)

# pos [1,1,1]

    0 0
    1 1
    2 2
    
# pos [2,1,1]

    3 3
    4 4
    5 5
    
# pos [10,1,1]

    27 27
    28 28
    29 29
    
# Matrix of size [10,3,2] stride [6,2,1] ref [0x1b42ef0 data= 0x1b42fe0]

```

\subsection*{2.6.13 clamp}
```

matrix = m:clamp(lower, upper)

```

This method clamps the matrix components to a given range [min,max], modifying the matrix in-place. The caller matrix instance is returned.
```

>a = matrix(3,3,{1,2,3,4,5,6,7,8,9})
> = a
123
4 5
7 9

# Matrix of size [3,3] in row_major [0xe56a30 data= 0xe56f40]

> a:clamp(3,6)
> = a
3 3 3
46
6 6 6

# Matrix of size [3,3] in row_major [0xe56a30 data= 0xe56f40]

```

\subsection*{2.6.14 adjust_range}
matrix = m:adjust_range (min, max)
This method modifies in-place the matrix components, interpolating the values to be in the given range [min,max]. The caller matrix is returned.
```

> a = matrix(3,3,{1,2,3,4,5,6,7,8,9})
> a:adjust_range(3,6)
> = a
3 3.375 3.75
4.1254.54.875
5.25 5.625 6

# Matrix of size [3,3] in row_major [0x25cca30 data= 0x25ccf40]

> = a:adjust_range(0,1)
00.125 0.25
0.375 0.5 0.625
0.75 0.875 1

# Matrix of size [3,3] in row_major [0x25cca30 data= 0x25ccf40]

> = a:adjust_range(1,9)
12 3
4 5
7 9

# Matrix of size [3,3] in row_major [0x25cca30 data= 0x25ccf40]

```

\subsection*{2.6.15 is_contiguous}
```

boolean = m:is_contiguous()

```

Indicates if the matrix internal data is contiguous at memory (in row major order).

\subsection*{2.6.16 contiguous}
```

matrix = m:contiguous()

```

Returns a contiguous version of the caller matrix. If the matrix is contiguous, returns itself. Otherwise, returns a copy of the caller. Note that, if the matrix is a slice or a transposition of another matrix, therefore it could be non-contiguous.

\subsection*{2.7 Data initialization methods}

\subsection*{2.7.1 fill}
matrix = m:fill(number)
This is an in-place method which sets all components to a given value.
```

> a = matrix(2,3):fill(4) -- a 2x3 matrix filled with 4
> = a
444
444

# Matrix of size [2,3] in row_major [0x26ff9b0 data= 0x26ffa20]

```

\subsection*{2.7.2 zeros}
```

matrix = m:zeros()

```

This is equivalent to \(\mathrm{m}: \mathrm{fill}(0)\)

\subsection*{2.7.3 ones}
```

matrix = m:ones()

```

This is equivalent to \(\mathrm{m}: \mathrm{fill}(1)\)

\subsection*{2.7.4 linear}
```

matrix = m:linear(start=0, step=1)

```

Initializes the matrix starting at the given index and using the given step. The index and the step is optional.
```

>m = matrix (3, 2, 2):linear(1, 2)
> m

# pos [1,1,1]

1 3
57

# pos [2,1,1]

9 11
1315

# pos [3,1,1]

17 19
21 23

# Matrix of size [3,2,2] in row_major [0x149de00 data= 0x149daa0]

> m = matrix(2,2):linear()
> m
O 1
2 3

# Matrix of size [2,2] in row_major [0x149f110 data= 0x149f1e0]

```

\subsection*{2.7.5 linspace}
```

matrix = m:linspace(a=1, b=m:size())

```

Initializes the matrix with a linear space distribution. It receives two optional arguments, why default a=1 and \(b=m\) :size(). It returns the caller matrix.
```

> m = matrix(5):linspace(1,20)
> m
1 5.75 10.5 15.25

# Matrix of size [5] in row_major [0x291f200 data= 0x291ecd0]

```

\subsection*{2.7.6 logspace}
matrix \(=m: \operatorname{logspace}(a=1, b=m: \operatorname{size}()\), base=10)
Initializes the matrix with a logarithmic distribution between a and b with the given logarithm base. It receives three optional arguments, why default \(a=1, b=m: \operatorname{size}()\) and base=10. It returns the caller matrix.
```

> m = matrix(5):logspace(0.001,0.1)
> = m
0.001 0.00316228 0.01 0.0316228 0.1

# Matrix of size [5] in row_major [0x291fed0 data= 0x291fd50]

```

\subsection*{2.7.7 uniform}
```

matrix = m:uniform(lower, upper [, random] )

```

This method initializes the matrix with random integers taken uniformly from the given range of values:
```

> m = matrix(10):uniform(0,10,random(1234))
> = m
36 54 8 9 1 7 9 10

# Matrix of size [10] in row_major [0x2716b10 data= 0x2716490]

```

The random object is optional, but to ensure reproducibility it is recommended.

\subsection*{2.7.8 uniformf}
```

matrix = m:uniformf(lower=0, upper=1 [, random] )

```

This method initializes the matrix with random floats taken uniformly from the given range of values:
```

> m = matrix(2,2):uniformf(-10, 10, random(1234))
> = m
-6.16961 -0.0467267
2.44218 6.35677

# Matrix of size [2,2] in row_major [0x1000e90 data= 0xe47410]

```

The random object is optional, but to ensure reproducibility it is recommended.

\subsection*{2.7.9 diag}
```

matrix = m:diag(number)

```

This method sets the matrix diagonal components to a given value, modifying in-place the caller matrix. For any number of dimensions, the diagonal are whose components which positions are equals at all dimensions.
```

> a = matrix(3,3,3):ones():diag(5)
> = a

# pos [1,1,1]

5 1 1
11

```

111
\# pos [2,1,1]
111
151
111
\# pos [3,1,1]
111
111
115
\# Matrix of size [3,3,3] in row_major [0x1718f10 data= 0x1718d50]

\subsection*{2.8 Matrix serialization}

\subsection*{2.8.1 toString}
```

string = m:toString( mode='ascii' )

```

This method returns a Lua string which represents the caller matrix. It receives an optional argument indicating if the matrix data will be stored in ascii or binary format (by default ascii).
```

> a = matrix(3,5):ones()
> = a
1 1 1 1 1
1 1 1 1 1
1 1 1 1 1

# Matrix of size [3,5] in row_major [0xd80a10 data= 0xd815d0]

> = a:toString()
3 5
ascii
1 1111111111
111111
> = a:toString("ascii")
3 5
ascii
1 1 1 1 1 1 1 1 1
1 1 1 1 1 1
> = a:toString("binary")
3 5
binary
8Ffe98Ffe98Ffe98Ffe98Ffe98Ffe98Ffe98Ffe98Ffe98Ffe98Ffe98Ffe98Ffe98Ffe98Ffe9

```

\subsection*{2.8.2 fromString}
```

matrix = matrix.fromString(filename)

```

This method loads a matrix from a Lua string generated by method matrix.toString.
```

> a = matrix.fromString[[3 5
>> ascii

```
```

>> 1
>> 11 1 1 1 1 1 1
>> ]]
> = a
1 1 1 1 1
1 1 1 1 1
11111

# Matrix of size [3,5] in row_major [0xd983b0 data= 0xdfe5c0]

```

\subsection*{2.8.3 toFilename}
```

m:toFilename(filename, mode='ascii')

```

This method stores a matrix in a given filename. It also receives an optional argument with ascii or binary (by default ascii). It allows to compress the output file using GZIP, if the filename has 'gz' extension.
```

> a = matrix (3,3)
> a:toFilename("a.mat", "binary")
> a:toFilename("a.mat.gz", "binary")

```

\subsection*{2.8.4 fromFilename}
```

matrix = matrix.fromFilename(filename)

```

This method loads a matrix from a given filename, expecting the format used by matrix.toFilename method. It allows to load compressed files using GZIP, if the filename has '.gz' extension.
```

> a = matrix.fromFilename("a.mat")
> a = matrix.fromFilename("a.mat.gz")

```

\subsection*{2.8.5 toTabFilename}
```

m:toTabFilename(filename)

```

This method stores a matrix in a given filename, but without header, and formatting the data to be formatted by lines and spaces, one matrix row per line. It is limited to bi-dimensional matrices. It allows to compress the output file using GZIP, if the filename has '.gz' extension.
```

> a = matrix(3,3)
> a:toTabFilename("a.mat")
> a:toTabFilename("a.mat.gz")

```

\subsection*{2.8.6 fromTabFilename}
```

matrix = matrix.fromTabFilename(filename)

```

This method loads a matrix from a given filename, formatted as done by matrix.toTabFilename. The size of the matrix is computed in a first loop over all the data, so this method needs two passes to load the matrix. It allows to load compressed files using GZIP, if the filename has '.gz' extension.
```

> a = matrix.fromTabFilename("a.mat")
> a = matrix.fromTabFilename("a.mat.gz")

```

\subsection*{2.8.7 toMMap}
m:toMMap(filename)
Stores the matrix in a file in a binary machine-dependent format, so it could be loaded using mmap function (matrix.fromMMap). The endianism must be the same between machines where matrix is stored/loaded.

\subsection*{2.8.8 matrix.fromMMap}
```

matrix = matrix.fromMMap(filename [,write [,shared]])

```

Loads the matrix from a file in a binary machine-dependent format, by using the mmap function (matrix.toMMap). The endianism must be the same between machines where matrix is stored/loaded. Two additional boolean arguments are allowed. The second boolean argument indicates if writing is available, by default it is true. Be careful, if writing is set to false, any attempt of writing will throw a segmentation fault. The third boolean argument indicates if the data is shared between different processes, by default it is true. If both arguments are true, any writing will be available to any process which shares this map. Besides, writings will be synchronized in the hard disk (but not instantly). If writing is true, but shared is false, then the memory is mapped as copy-on-write. For more info, see the manual page of mmap function (PROTECT_WRITE, MAP_SHARED and MAP_PRIVATE).

\subsection*{2.8.9 toTable}
```

table = m:toTable()

```

This method returns a plain Lua table (one-dimensional table) which contains the matrix data in row_major order, as expected by matrix constructors.
```

>a = matrix(3,2,{1,2,3,4,5,6})
> = a
12
34
56

# Matrix of size [3,2] in row_major [0x9ddce0 data= 0x9ddd30]

> t = a:toTable()
> = table.concat(t, " ")
123456

```

\subsection*{2.8.10 read}

\subsection*{2.8.11 write}

\subsection*{2.9 Low-level matrix access}

These methods allows raw accessing of matrix components.

\subsection*{2.9.1 size}
```

number = m:size()

```

This method returns the number of elements in the matrix.
```

> a = matrix(3,4,{1,2,3,4, 5,6,7,8, 10,11,12,13})
> = a:size()
12

```

\subsection*{2.9.2 stride}
```

table = m:stride()

```

This method is similar to m:dim, but returning the stride of the dimension (the offset between elements at each dimension)
```

> a = matrix(4,3,2)
> = a:stride()
table: 0x23a5fe0
> = table.concat(a:stride(), " ")
6 2 1
> = a:stride(1), a:stride(2), a:stride(3)
6 2 1
> a = a:transpose()
> = a:stride(1), a:stride(2), a:stride(3)
14 12

```

\subsection*{2.9.3 offset}
```

number = m:offset()

```

It returns the offset from data first position. Only sub-matrices has an offset! \(=0\).
```

> a = matrix(2,3)
> = a:offset()
0
> b = a:slice({2,1},{1,1})
> = b:offset()
3

```

\subsection*{2.9.4 data}
```

block = m:data()

```

Returns a float memory block (mathcore.block.float) with the underlying data pointer.

\subsection*{2.9.5 raw__get}
```

number = m:raw_get(pos)

```

It receives a raw position at the underlying data pointer, and returns its value. It is useful to combine stride and offset methods in order to compute the raw position.
```

>a = matrix(3,2, {1,2,3,4,5,6})
> = a
12
34

```
```

5 6

# Matrix of size [3,2] in row_major [0x144fce0 data= 0x144fd90]

> = a:raw_get(a:offset() + a:stride(1)*1 + a:stride(2)*0), a:get(2,1)
3 3

```

NOTE! that the strides are multiplied by matrix position minus 1.

\subsection*{2.9.6 raw__set}
m:raw_set (pos, value)
It receives a raw position at the underlying data pointer and a number. The given position is set to given number value. It is useful to combine stride and offset methods in order to compute the raw position.
```

> a = matrix(3,2, {1,2,3,4,5,6})
> = a
12
34
5 6

# Matrix of size [3,2] in row_major [0x144fce0 data= 0x144fd90]

> -- equivalent to a:set(2,1, 10)
> a:raw_set(a:offset() + a:stride(1)*1 + a:stride(2)*0, 10)
> = a
12
104
5

# Matrix of size [3,2] in row_major [0x144fce0 data= 0x144fd90]

```

NOTE! that the strides are multiplied by matrix position minus 1 .

\subsection*{2.10 Sliding window iterator}

For fast and easy matrix traversal, a C++ sliding window object is binded to Lua. It works similarly to dataset.matrix, but circularity and out-of-matrix default values are not supported. The object is constructed using the method sliding_window of matrix, and could be iterated using its method iterate():
```

> m = matrix(4,2,3):uniformf(-10,10,random(1234)) -- randomly initialized matrix
> for submat in m:sliding_window():iterate() do print(submat) end

# pos [1,1,1]

-6.16961 -0.0467267 2.44218
6.35677 -1.24545 2.24224

# Matrix of size [1,2,3] in row_major [0x253f160 data= 0x253dec0]

# pos [1,1,1]

5.70717 5.4272 5.59952
7.2134-4.54815 -6.98726

# Matrix of size [1,2,3] in row_major [0x253fa40 data= 0x253dec0]

# pos [1,1,1]

-4.47071 -6.02962 6.03744

```
```

6.30326 9.16279 -6.82369

# Matrix of size [1,2,3] in row_major [0x2540230 data= 0x253dec0]

# pos [1,1,1]

7.51865 -7.67724 -2.84365
-9.74185 0.0199025 -0.263331

# Matrix of size [1,2,3] in row_major [0x25409c0 data= 0x253dec0]

```

It is possible to modify the default behavior giving this parameters to sliding_window method:
- offset: a Lua table with offset applied to the window in each coordinate (starting at 0 ).
- size: a Lua table with the window size for each coordinate.
- step: a Lua table with the step size at each coordinate (each value must be \(>=1\) ).
- numSteps: a Lua table with the number of steps in each coordinate (each value must be \(>=1\) ).
- orderStep: a Lua table with the traversal order of coordinates (starting at 1).
```

> m = matrix(4,2,3):uniformf(-10,10,random(1234))
> for w in m:sliding_window{ step={2,1,1}, size={1,1,2} }:iterate() do print(w) end

# pos [1,1,1]

-6.16961 -0.0467267

# Matrix of size [1,1,2] in row_major [0x9fdb90 data= 0x9cf2d0]

# pos [1,1,1]

-4.47071 -6.02962

# Matrix of size [1,1,2] in row_major [0x9fe0f0 data= 0x9cf2d0]

```

Manual iteration of the sliding_window is also possible using the following methods:
- matrix = sw:get_matrix([matrix]): returns the matrix generated by the window at its current position. It is possible to pass an optional argument, a destination matrix, so the computation effort is dismissed to constant. NOTE that this matrix must be created by a previous call to get_matrix over the same sliding_window.
- sw: next(): moves the window to the next position.
- sw:is_end(): returns true if the window has finished the matrix traversal.
```

> m = matrix(4,2,3):uniformf(-10,10,random(1234))
> wo = m:sliding_window{ step={2,1,1}, size={1,1,2} }
> while not wo:is_end() do m=wo:get_matrix(m) print(m) wo:next() end

```

\subsection*{2.11 Fast mathematical operations}

This operations uses standard Lua math operators for friendly user interaction, but they work with BLAS API for best performance. However, all this operations return a new instantiated matrix, for best performance it is recommended to use directly the BLAS interface.

The operators binary \(+,-,^{*}, /\), and unary operators,\(-^{\wedge}\), are implemented as algebraic operations. The + and - operators only work when the matrices has the same sizes:
```

> a= matrix(3,3,3,{1,2,3,4,5,6,7,8,9,
10,11,12,13,14,15,16,17,18,
19,20,21,22,23,24,25,26, 27})
> = a+a

# pos [1,1,1]

246
81012
1416 18

# pos [2,1,1]

20 22 24
26 28 30
3234 36

# pos [3,1,1]

384042
444648
50 52 54

# Matrix of size [3,3,3] in row_major [0x1196d90 data= 0x1196e40]

> = a-a

# pos [1,1,1]

O 0 0
0 0
0 0

# pos [2,1,1]

0 0
0 0
0 0

# pos [3,1,1]

0 0
0 0
O 0

# Matrix of size [3,3,3] in row_major [0x1198d80 data= 0x1198a50]

```

The operator \({ }^{*}\) only works with vectors or bi-dimensional matrices. If needed, you can rewrap the matrix data before the operation. Depending on the dimension of the two matrices, the multiplication could be:
- A dot product between two vectors: when the two matrices are unidimensional vectors, the first one a vector and the second one a column vector:
```

> a, b = matrix(4,{1,2,3,4}), matrix(4,1,{5,6,7,8})
> = a*b
70

# Matrix of size [1] in row_major [0xfa9230 data= 0xfc2300]

```
- An outter product between two vectors: when the first matrix is a column vector, and the second matrix is a unidimensional matrix or a bi-dimensional matrix (row or column vector).
```

> a = matrix(4,{1,2,3,4})
> b = matrix(4,1,{5,6,7,8})

```
```

> = b*a
5 10 15 20
6 12 18 24
714 21 28
816 24 32

# Matrix of size [4,4] in row_major [0x1001940 data= 0x1176a80]

```
- A matrix-vector product when the first matrix is a bi-dimensional matrix and the second is a vector. The output has the same number of dimensions as the given vector.
```

>a = matrix(2,2,{1,2,3,4})
> b = matrix(2,{5,6})
> = a*b
17 39

# Matrix of size [2] in row_major [0x105baa0 data= 0xfe80f0]

> b = matrix(1,2,{5,6})
> = a*b
17
39

# Matrix of size [2,1] in row_major [0x107e3c0 data= 0x107fb30]

> b = matrix (2,1,{5,6})
> a*b
17
39

# Matrix of size [2,1] in row_major [0x10c4700 data= 0x10c6890]

```
- A matrix-matrix product when the two matrices are bi-dimensional and not vectors.
```

> a=matrix(3,2,{1,2,3,4,5,6})
> b=matrix(2,4,{1,2,3,4,5,6,7,8})
> = a*b
11 14 17 20
23 30 3744
35465768

# Matrix of size [3,4] in row_major [0x1114270 data= 0x11165d0]

```

A multiplication by a scalar is also possible, if you multiply one matrix by one number.
```

> a=matrix(3,2,{1,2,3,4,5,6})
> = a*5
510
15 20
2530

# Matrix of size [3,2] in row_major [0x10f2160 data= 0x10d14e0]

```

The component-wise operator / is allowed for division between matrix and a scalar, or between a scalar and a matrix.

The operator ^ is also allowed only with scalars.
The unary operator - is equivalent to multiply by -1 .

\subsection*{2.11.1 scalar_add}
```

matrix = m:scalar_add(number)

```

Adds to all the components, in-place, the given scalar number. Returns the caller matrix object.

\subsection*{2.11.2 div}
```

matrix = m:div(scalar)

```

Produces the computation between the component-wise inversion of the matrix and the given scalar. This operation is done in-place.
```

>m = matrix(2,2,{1,2,3,4})
> m:div(1)
> = m
1 0.5
0.3333 0.25

# Matrix of size [3,2] in row_major [0x1cf2160 data= 0x10d15e0]

```

\subsection*{2.12 BLAS interface}

The most efficient way to do operations if using the BLAS interface directly. All the methods are prepared to adjust the BLAS operations to the given matrices, so you don't need to be worried about strides and sizes.

All of this methods are in-place, so they modify the caller object, and returns it to allow operation sequences.

\subsection*{2.12.1 axpy}
```

matrix = m:axpy(alpha, X)

```

The AXPY operation computes addition of vectors:
\(\mathrm{Y}=\) alpha * \(\mathrm{X}+\mathrm{Y}\)
The method receives two positional parameters: the alpha scalar and the matrix X . The X and Y matrix sizes must be equals, and the number of dimensions is not a problem. This method interprets all the data as a sequence, calling several times to AXPY BLAS function if necessary:
```

>a = matrix(4,{1,2,3,4})
> b = matrix(4,{5,6,7,8})
> a:axpy(2.0, b)
> = a
11 14 17 20

# Matrix of size [4] in row_major [0x107e3c0 data= 0x1110970]

> a = matrix(2,2,2,{1,2,3,4,5,6,7,8})
> b = matrix(2,2,2,{9,10,11,12,13,14,15,16})
> a:axpy(1.0, b)
> = a

# pos [1,1,1]

10 12
1416

```
```


# pos [2,1,1]

18 20
22 24

# Matrix of size [2,2,2] in row_major [0xfb1f40 data= 0x1056f00]

```

\subsection*{2.12.2 gemv}
```

matrix = m:gemv{ beta, alpha, Y, X, trans_A}

```

The GEMV operation computes matrix-vector multiplication:
```

Y = beta * Y + alpha * op(A) * X

```
being Y the caller matrix (a vector), A another matrix, and X a vector (unidimensional matrix, or bidimensional with one row (or one column)), and beta and alpha are scalars. The op(A) is transposition operation.

The method receives a table with:
- A field, the other matrix.
- X field, the vector.
- alpha field, the scalar
- beta field, the other scalar.
- trans_A field, a boolean which indicates if the A matrix will be transposed or not. It is optional, by default is false.
```

>a = matrix(3,2,{1,2, 3,4, 5,6})
>b = matrix(2,{7,8})
> c = matrix(3)
> c:gemv{ A=a, X=b, alpha=2, beta=0 }
> = c
46 106 166

# Matrix of size [3] in row_major [Oxfbeff0 data= 0xfaf640]

```

\subsection*{2.12.3 gemm}
matrix \(=m:\) gemm \(\{\) beta, alpha, \(A, B, \ldots\}\)
The GEMM operation computes matrix-matrix multiplication:
\(\mathrm{Y}=\) beta \(* \mathrm{Y}+\mathrm{alpha} * \mathrm{op}(\mathrm{A}) * \mathrm{op}(\mathrm{B})\)
being Y the caller matrix (a vector), A another matrix, and B a matrix, and beta and alpha are scalars. The \(o p(A)\) and \(o p(B)\) are transposition operations.

The method receives a table with:
- A field, the other matrix.
- B field, the vector.
- alpha field, the scalar
- beta field, the other scalar.
- trans_A field, a boolean which indicates if the A matrix will be transposed or not. It is optional, by default is false.
- trans_B field, a boolean which indicates if the B matrix will be transposed or not. It is optional, by default is false.
```

> a = matrix(3,2,{1,2, 3,4, 5,6})
> b = matrix(4,2,{7,8, 9,10, 11,12, 13,14})
> c = matrix(3,4):ones()
> c:gemm{ A=a, B=b, alpha=1, beta=1, trans_B=true}
> = c
24 30 36 42
5468 82 96
84106 128 150

# Matrix of size [3,4] in row_major [0x1452a20 data= 0x144cbf0]

```

\subsection*{2.12.4 ger}
matrix \(=m: \operatorname{ger}\{X, Y\), alpha \(\}\)
The GER operation computes outter product of vectors:
\(\mathrm{Z}=\mathrm{Z}+\) alpha \(* \mathrm{X} * \mathrm{Y}\),
being Z the caller matrix (a squared matrix), X and Y two vectors, and beta and alpha are scalars. The Y vector is transposed.
```

>a = matrix(3,{1,2,3})
> b = matrix(3,{4,5,6})
> c = matrix(3,3):zeros()
> c:ger{ X=a, Y=b, alpha=2 }
> = c
8 10 12
16 20 24
24 30 36

# Matrix of size [3,3] in row_major [0x1f06b20 data= 0x1f18080]

```

\subsection*{2.12.5 dot}
```

number = m:dot(matrix)

```

The DOT operation computes the dot-product of two vectors, the caller matrix and a given matrix. It returns a number.
```

>a = matrix(3,{1,2,3})
> b = matrix(3,{4,5,6})
> = a:dot(b)
32

# Matrix of size [1] in row_major [0x1f4ffe0 data= 0x2076e20]

```

\subsection*{2.12 .6 scal}
```

matrix = m:scal(number)

```

The SCAL operation computes the multiplication of a matrix by a scalar.
```

>a = matrix(3,{1,2,3})
> a:scal(4)
> = a
4 8 12

# Matrix of size [3] in row_major [0x1f3b230 data= 0x201e9a0]

```

\subsection*{2.12.7 copy}
```

matrix = m:copy(matrix)

```

The COPY operation copies the content of a given matrix in the caller matrix object.
```

> a = matrix(3,3,{1,2,3,4,5,6,7,8,9})
> b = matrix(3,3):fill(5)
> a:copy(b)
> = a
5 5 5
5 5
5 5

# Matrix of size [3,3] in row_major [0x1f7e870 data= 0x1f49ef0]

> a = matrix(3,3,{1,2,3,4,5,6,7,8,9})
> b = matrix(2,2,{1,2,3,4})
> c = a:slice({2,1},{2,2})
> c:copy(b)
> = a
1 2 3
126
349

# Matrix of size [3,3] in row_major [0x1fb64e0 data= 0x1fbd600]

```

\subsection*{2.13 LAPACK interface}

\subsection*{2.13.1 svd}
\(\mathrm{U}, \mathrm{S}, \mathrm{VT}=\mathrm{m}: \mathrm{svd}()\)
This method computes the Singular Values Decomposition of the caller matrix. It returns three matrices:
- U a matrix with the left singular vectors.
- S a sparse diagonal matrix with singular values.
- VT a matrix with the transposed right singular vectors.

\subsection*{2.13.2 inv}
matrix \(=m: \operatorname{inv}()\)
Computes the inverse of the caller matrix. Check that your matrix is not singular, otherwise the returned matrix won't be correct.

\subsection*{2.13.3 pinv}
matrix \(=m: \operatorname{pinv}()\)
Computes the pseudo-inverse of the caller matrix, using the SVD method.

\subsection*{2.14 Component-wise operations}

This operations are applied in-place and over all the components of the caller matrix. If it is possible, the caller matrix is returned.

\subsection*{2.14.1 tan}
matrix \(=m: \tan ()\)
Computes the TAN function of all the components.

\subsection*{2.14.2 tanh}
matrix \(=m: \tanh ()\)
Computes in-place the TANH function of all the components.

\subsection*{2.14.3 atan}
matrix = m:atan()
Computes in-place the ATAN function of all the components.

\subsection*{2.14.4 atanh}
matrix \(=m: \operatorname{atanh}()\)
Computes in-place the ATANH function of all the components.

\subsection*{2.14.5 \(\sin\)}
matrix \(=m: \sin ()\)
Computes in-place the SIN function of all the components.

\subsection*{2.14.6 \(\sinh\)}
matrix \(=m: \sinh ()\)
Computes in-place the SINH function of all the components.

\subsection*{2.14.7 asin}
matrix = m:asin()
Computes in-place the ASIN function of all the components.

\subsection*{2.14.8 asinh}
```

matrix = m:asinh()

```

Computes in-place the ASINH function of all the components.

\section*{\(2.14 .9 \cos\)}
matrix \(=m: \cos ()\)
Computes in-place the COS function of all the components.

\subsection*{2.14.10 cosh}
```

matrix = m: cosh()

```

Computes in-place the COSH function of all the components.

\subsection*{2.14.11 acos}
```

matrix = m:acos()

```

Computes in-place the ACOS function of all the components.

\subsection*{2.14.12 acosh}
```

matrix = m:acosh()

```

Computes in-place the ACOSH function of all the components.

\subsection*{2.14.13 abs}
```

matrix = m:abs()

```

Computes in-place the ABS function of all the components.

\subsection*{2.14.14 complement}
```

matrix = m:complement()

```

Computes in-place the complement function of all the components: \(\mathrm{X}=1-\mathrm{X}\)

\section*{\(2.14 .15 \quad \log\)}
matrix \(=m: \log ()\)
Computes in-place the LOG function of all the components.

\subsection*{2.14.16 \(\log 1 p\)}
matrix \(=m: \log 1 p()\)
Computes in-place the LOG1P function of all the components.

\subsection*{2.14.17 plogp}
matrix \(=m: p \log ()\)
Computes in-place the \(p^{*} \log (p)\) operation over all components. It is useful to compute entropy related measures.

\subsection*{2.14.18 exp}
matrix \(=m: \exp ()\)
Computes in-place the EXP function of all the components.

\subsection*{2.14.19 pow}
matrix \(=m:\) pow(number)
Computes in-place the POWER of all the components by a given scalar.

\subsection*{2.14.20 sqrt}
matrix \(=\mathrm{m}:\) sqrt ( \()\)
Computes the SQRT function of all the components.

\subsection*{2.14.21 cmul}
matrix = m:cmul(matrix)
Computes in-place a component-wise multiplication between the caller and a given matrix.

\subsection*{2.15 Matrix level operations}

This operations are applied taking into account all the data at the matrix.

\subsection*{2.15.1 min}
\(\min , \operatorname{argmin}=m: \min ()\)
Returns the minimum and its position in the matrix.
```

>a = matrix(3,4,{1,2,3,4,5,6,7,12,9,10,11,8})
> = a:min()
1 1
matrix,matrixInt32 = m:min(dim [, matrix[, matrixInt32]] )

```

Applies the min operator over the elements of the given dimension, and returns a matrix with the same number of dimensions, but with the size of dimension dim equals 1 . The second matrix argument is optional, and if given, the returned matrix will be this second argument.
```

> a = matrix(3,4,{1,2,3,4,
>> 5,6,7,12,
>> 9,10,11,8})
> = a:min(1)
1 2 3 4

# Matrix of size [1,4] in row_major [0x1f06bb0 data= 0x1f06cb0]

> = a:min(2)
1
5
8

# Matrix of size [3,1] in row_major [0x1f07560 data= 0x1f06d90]

```

\subsection*{2.15.2 max}
```

max,argmax = m:max()

```

Returns the maximum and its position in the matrix.
```

> a = matrix(3,4,{1,2,3,4,5,6,7,12,9,10,11,8})
> = a:max()
12 8
matrix,matrixInt32 = m:max(dim [, matrix[, matrixInt32] ] )

```

Applies the max operator over the elements of the given dimension, and returns a matrix with the same number of dimensions, but with the size of dimension dim equals 1. The second matrix argument is optional, and if given, the returned matrix will be this second argument.
```

>a = matrix(3,4,{1,2,3,4,
>> 5,6,7,12,
>> 9,10,11,8})
> = a:max(1)
9 10 11 12

# Matrix of size [1,4] in row_major [0x1f05500 data= 0x1f05600]

> = a:max(2)
4
1 2
1 1

```

\subsection*{2.15.3 eq}
```

matrixBool = m:eq(number or matrix)

```

This method computes in-place a comparison between all the components with the given value, and converts the component in true or false if it is less than the given value or not. If the value is another matrix, both matrices will be compared component-by-component.

\subsection*{2.15.4 lt}
```

matrixBool = m:lt(number or matrix)

```

This method computes in-place a comparison between all the components with the given value, and converts the component in true or false if it is less than the given value or not. If the value is another matrix, both matrices will be compared component-by-component.

\subsection*{2.15 .5 gt}
matrixBool = m:gt(number or matrix)
This method computes in-place a comparison between all the components with the given value, and converts the component in true or false if it is greater than the given value or not. If the value is another matrix, both matrices will be compared component-by-component.

\subsection*{2.15.6 sum}
number \(=m\) :sum ( )
Computes the sum of all the components of the caller matrix, and returns its value.
```

matrix = m:sum( number [, matrix] )

```

Receives a number indicating the dimension where the sum must be run, and returns a matrix with each possible sum of the given dimension. The second matrix argument is optional, and if given, the returned matrix will be this argument.
```

>m = matrix(2,2,{1,2,3,4})
> = m:sum(1)
4 6

# Matrix of size [1,2] in row_major [0x19e0620 data= 0x19d2480]

> = m:sum(2)
3
7

# Matrix of size [2,1] in row_major [0x19e0a40 data= 0x19d3b90]

```

\subsection*{2.15.7 norm2}
```

number = m:norm2()

```

The NORM2 operation computes the euclidean norm of the caller matrix. It returns a number.
```

> a = matrix(2,2,2,{1,2,3,4,5,6,7,8})
> = a:norm2()
14.282856941223

```

\subsection*{2.16 Indexing and sorting}

This operations allow to extract or sort matrices by indexing any of its dimensions.

\subsection*{2.16.1 index}
matrix \(=m: i n d e x(d i m, i d x)\)
This method returns a new deep cloned matrix but taking only the indexes of dimension dim indicated at idx object. The idx object can be three different data types:
- A one-dimensional matrixInt32 with all the indices you want to take.
- A Lua table with the indices you want to keep. This table will be converted into a matrixInt32 instance.
- A one-dimensional matrixBool were true value in the indices you want to keep.

This method can be combined with eq, lt, gt methods to select a bunch of rows or columns depending in a simple condition. The following example uses index and lt to select all the rows where its first column is less than 0 .
```

>m = matrix(10, 2):uniform(-10,10,random(1234))
> print(m)
5 9
-4 2
10 5
7 -1
1 2
\#.

# Matrix of size [10,2] stride [2,1] ref [0x204cce0 data= 0x1e3c310]

> m_neg_idx = m:select(2,1):lt(0)
> print(m_neg_idx)
F T F F F F F F F T

# MatrixBool of size [10] stride [1] ref [0x1f64820 data= 0x1e886a0]

> m_neg = m:index(1, m_neg_idx)
> print(m_neg)
-4 2
-5 -8

# Matrix of size [2,2] stride [2,1] ref [0x1d72450 data= 0x1f499a0]

```

\subsection*{2.16.2 indexed_fill}
```

m = m:indexed_fill(dim, idx, number)

```

This method fills with number all the values at the given dimension dim whose indices are in idx object. The idx object can be three different data types:
- A one-dimensional matrixInt32 with all the indices you want to take.
- A Lua table with the indices you want to keep. This table will be converted into a matrixInt32 instance.
- A one-dimensional matrixBool were true value in the indices you want to keep.

The following example fills with 0 the values at column 1 which are negative.
```

>m = matrix(10,2):uniform(-10,10,random(1234))
> print(m)
5 9
-4 2
10 5
7 -1
1 2
-5 -8

# Matrix of size [10,2] stride [2,1] ref [0x204cce0 data= 0x1e3c310]

```
```

> m_neg = m:index(1, m:select(2,1):lt(0))
> m_neg_idx = m:select(2,1):lt(0)
> print(m_neg_idx)
F T F F F F F F F T

# MatrixBool of size [10] stride [1] ref [0x1f64820 data= 0x1e886a0]

> col1 = m(':',1)
> col1:indexed_fill(1, m_neg_idx, 0)
> print(m)

```

\subsection*{2.16.3 indexed_copy}
```

m = m:indexed_copy(dim, idx, matrix)

```

This method copies the values of matrix at the indices of dimension dim indicated by idx object. The idx object can be three different data types:
- A one-dimensional matrixInt32 with all the indices you want to take.
- A Lua table with the indices you want to keep. This table will be converted into a matrixInt32 instance.
- A one-dimensional matrixBool were true value in the indices you want to keep.

\subsection*{2.16.4 masked_fill}
```

m:masked_fill(mask, value)

```

\subsection*{2.16.5 masked_copy}
```

m:masked_copy(mask, value)

```

\subsection*{2.16.6 order}
```

matrixInt32 = m:order()

```

Returns a permutation of the caller matrix which sorts its data. The permutation is given as a matrixInt32 with the indices of the caller matrix. The caller matrix shold be a one-dimensional matrix (rank 1 tensor).
```

> m = matrix(10,2):uniform(-10,10,random(1234))
> print(m)
5 9
-4 2
10 5
7 -1
1 2

```
```

-5 -8

# Matrix of size [10,2] stride [2,1] ref [0x10bf090 data= 0x10bf160]

> ord = m:select(2,1):order()
> print(ord)
10 2 5 1 ..

# MatrixInt32 of size [10] stride [1] ref [0xe4eba0 data= 0xeb3230]

> sorted = m:index(1, ord)
> print(sorted)
-5 -8
-4 2
1 2
5 9
5 8
...
10 5

# Matrix of size [10,2] stride [2,1] ref [0x1c270c0 data= 0x1ef0080]

```

\subsection*{2.16.7 order__rank}
```

matrixInt32 = m:order_rank()

```

Returns the rank of the matrix elements in its sorted permutation. The caller matrix should be a onedimensional matrix (rank 1 tensor).
```

> m = matrix(10,2):uniform(-10,10,random(1234))
> print(m)
$5 \quad 9$
-4 2
10 5
7 -1
1 2
-5 -8

# Matrix of size [10,2] stride [2,1] ref [0x10bf090 data= 0x10bf160]

> rnk = m:select(2,1):order_rank()
> print(rnk)
4 2 10 9 ... 1

# MatrixInt32 of size [10] stride [1] ref [0x2cf0100 data= 0x2cf0020]

```

\subsection*{2.17 Matrix class operations (no instance methods)}

More matrix operations are located at matrix.op, most of them are equivalent to methods in matrix objects, but implemented to be allocate new memory instead of being in-place, and receiving the caller matrix as first argument. New operations have been defined in this table to reduce the overhead of matrix instance table. Only the new operations are documented here.

\subsection*{2.17.1 matrix.op.repmat}

\subsection*{2.17.2 matrix.op.diag}

\subsection*{2.17.3 matrix.op.triu}

\subsection*{2.17.4 matrix.op.tril}

\subsection*{2.18 Other Matrix operations (extensions)}

The table matrix.ext contains new function extensions which work over matrices. This functions are here because the extensions are pretty new, still in testing, and to not polute too much the matrix class with new methods.

\subsection*{2.18.1 matrix.ext.real_fftwh}
```

matrix = matrix.ext.real_fftwh(m, wsize=m:size(), wadvance=wsize, dest=nil)

```

This functions computes real FFT with Hamming window to the given matrix m. The FFT is computed for all the possible positions of a sliding window of size wisize. The sliding window advances wadvance samples every iteration. By default, the function configures wsize and wadvance just to compute FFT over the whole given matrix \(m\). The matrix \(m\) should have only one dimension (rank 1). The result is new allocated matrix with size \(N x F\) where \(N=(m: s i z e()-\) wsize)/wadvance +1 and \(F\) is the size of the FFT output. In case the argument dest is given, it should be a matrix instance of size NxF, and it would be the result matrix, avoiding the allocation of a new matrix.
```

> a = matrix(200):uniformf(0,1,random(1234))
> f = matrix.ext.real_fftwh(a, 20, 10)
> print(f)
5.78204 17.9694 2.60205 1.93296 ... 0.210018
4.80782 11.8858 0.97495 1.46241 ... 2.67692
4.15355 9.48432 1.71497 0.480176 ... 0.498562
5.12262 16.0089 3.65927 0.276271 ... 1.00497
5.57981 16.7664 2.00985 0.0188873 ... 0.336096
...
4.96313 15.267 3.44396 0.307427 ... 0.539195

# Matrix of size [19,16] stride [16,1] ref [0x1efbe50 data= 0x1f46330]

```

\subsection*{2.18.2 matrix.ext.iterate}

\subsection*{2.18.3 matrix.ext.convolution}

\section*{Chapter 3}

\section*{Sparse matrix}
matrix.sparse

\subsection*{3.1 Constructors}
\(\mathrm{s}=\) matrix. sparse (matrix)
s = matrix.sparse(d1, d2, values, indices, first_index)
\(\mathrm{s}=\) matrix.sparse.csc (matrix)
s = matrix.sparse.csr(matrix)

\subsection*{3.1.1 diag}
s = matrix.sparse.diag(obj, [format="csr"])
- A number
- A matrix
- A table

\subsection*{3.2 Dictionary of keys builder}
```

dok = matrix.sparse.builders.dok()

```

\subsection*{3.2.1 set}
```

dok = dok:set(row, col, value)

```
3.2.2 build
```

sparse = dok:build([num_rows, [num_cols, [format="csr"]]])

```

\subsection*{3.3 Sparse matrix Basic methods}
3.3.1 size
3.3.2 non_zero_size
3.3.3 get
3.3.4 iterate
3.3.5 fill
3.3.6 zeros
3.3.7 ones
3.3.8 to_dense
3.3.9 get_sparse_format
3.3.10 dim
3.3.11 slice
3.3.12 clone
3.3.13 transpose
3.3.14 isfinite
3.3.15 min
3.3.16 max
3.3.17 equals
3.3.18 sqrt
3.3.19 pow
3.3.20 tan
3.3.21 tanh
3.3.22 atan
3.3.23 atanh
3.3.24 \(\sin\)
3.3.25 \(\sinh\)
3.3.26 asin
3.3.27 asinh

\section*{Chapter 4}

\section*{Other kind of matrices}

Currently is possible to use complex, double, int32 and char matrices, supporting load and save, matrix structural methods, and some of them also support mathematical operations:
- matrixBool: a matrix of boolean values. Basic functionality.
- matrixComplex: fully working matrix type, with almost all the methods described above.
- matrixDouble: partial working matrix type, only allow structural methods (explained at MatFormat section).
- matrixInt32: partial working matrix type, only allow structural methods (explained at MatFormat section).
- matrixChar: partial working matrix type, only allow structural methods (explained at MatFormat section).

In all cases, you could use april_help to ask which methods are available. Complex, MatrixChar type implements a method to_string_table.

All matrices implement method convert_to(type) which receives a type string with one of these values: "float", "double", "complex", "int32", "bool", "char"; allowing to convert a matrix of one type into a different type with a casting and precision loss in some cases.
```

>m = matrix(5,5):uniformf(-10,10,random(12354))
> print(m)
1.03926 -6.82017 <rrrer
1.54086 -1.43963 7.11541 1.20382
5.89334 9.04666 -0.688719 -9.25703
5.4027 -3.25782 -0.7066
-0.986174 8.1467 -7.01133 -9.03494 5.69565

# Matrix of size [5,5] stride [5,1] ref [0x16d0410 data= 0x16d04e0]

> print(m:convert_to("int32"))

| 1 | -6 | -7 | -2 | -9 |
| :---: | :---: | :---: | :---: | :---: |
| 1 | -1 | 7 | 1 | -2 |
| 5 | 9 | 0 | -9 | -3 |
| 5 | -3 | 0 | -5 | -8 |
| 0 | 8 | -7 | -9 | 5 |
| $x$ xInt32 of size $[5,5]$ | stride $[5,1]$ ref $[0 \times 187 d 2 b 0$ data= $0 \times 187 d 380]$ |  |  |  |

```

\section*{4.1 matrixComplex}

The constructor of a matrixComplex receives a table with complex numbers (see utils section). A complex number uses float single precission resolution for real and imaginary part:
```

> -- using strings which are converted to complex numbers (slow performance)
> m = matrixComplex(2,2, { "1+1i", "2+2i", "3+2i", "4+1i" })
> = m
1+1i 2+2i
3+2i 4+1i

# MatrixComplex of size [2,2] in row_major [0x24d52c0 data= 0x24d4a00]

>
> -- using directly complex numbers
> m = matrixComplex(2,2, { complex(1,1), complex(2,2), complex(3,2), complex(4,1) })
> = m
1+1i 2+2i
3+2i 4+1i

# MatrixComplex of size [2,2] in row_major [0x24d6550 data= 0x24d6650]

```

Besides the standard matrix methods, the matrixComplex implements the following:
- caller \(=m: \operatorname{conj}()\) computes the conjugate in-place, modifying the caller matrix, and returning the caller matrix instance.
- matrix \(=\mathrm{m}\) :real() returns the real part of the caller matrixComplex.
- matrix \(=m: i m g()\) returns the imaginary part of the caller matrixComplex.
- matrix \(=m: a b s()\) returns the modulus of the polar form of matrixComplex.
- matrix \(=\mathrm{m}\) :angle() returns the angle of the polar form of matrixComplex.
- matrix = m:to_float() converts the caller matrix in a matrix object which has one additional dimension. This additional dimension has always size 2 , and keeps the real and imaginary parts of the caller matrixComplex. The additional dimension will be the last. Note that the returned matrix and the matrixComplex caller references the same memory pointer.

\section*{4.2 matrixDouble}
matrixDouble is the type of matrices for double data. This kind of matrices don't accept mathematical operations, but yes structural operations as select, slice, etc.
```

>m = matrixDouble(2,3,{1,2,3,4,5,6})
> = m

| 1 | 2 | 3 |
| :--- | :--- | :--- |
| 4 | 5 | 6 |

# MatrixDouble of size [2,3] [0x2512c70 data= 0x251ad70]

```

\subsection*{4.2.1 matrixInt32}
matrixInt32 is the type of matrices for integer data. This kind of matrices don't accept mathematical operations, but yes structural operations as select, slice, etc.
```

>m = matrixInt32(2,3,{1,2,3,4,5,6})
> = m

```
\begin{tabular}{ccc}
1 & 2 & 3 \\
4 & 5 & 6 \\
\# MatrixInt32 of size & {\([2,3]\)} & {\([0 \times 2512 c 70\)}
\end{tabular}

\section*{4.3 matrixChar}
matrixChar is the type of matrices for char data. This kind of matrices don't accept mathematical operations, but yes structural operations as select, slice, etc.

Exists an special method, to_string_table(), which converts the matrix in a table of strings, concatenating the chars in row_major order.
```

> m = matrixChar(2,2, { "h","ola" })
> m
[1,1] = h
[1,2] = o
[2,1] = 1
[2,2] = a

# MatrixChar of size [2,2] [0x12c3310 data= 0x12c3410]

> = unpack(m:to_string_table())
ho la

```

\section*{Chapter 5}

\section*{Matrix dictionary tools}

The table matrix. dict contains several functions which allow to execute matrix operations over tables of matrices.

\section*{5.1 clone}
another \(=\) matrix.dict.clone(tbl)
Returns a deep copy of the table.

\section*{5.2 clone_only_dims}
```

another = matrix.dict.clone_only_dims(tbl)

```

Returns a deep copy of the table, but without copying the matrix data content, only cloning the matrix dimension sizes.

\subsection*{5.3 Implemented operations}

The following list of operations are implemented to be executed over all the contained matrices:
- number = matrix.dict.size()
- tbl = matrix.dict.fill(tbl,number)
- tbl = matrix.dict.ones(tbl)
- tbl = matrix.dict.zeros(tbl)
- tbl = matrix.dict.axpy(tbl, number, tbl2)
- number \(=\) matrix.dict.dot(tbl, tbl2)
- tbl = matrix.dict.copy(tbl, tbl2)
- tbl = matrix.dict.scalar_add(tbl, number)
- tbl = matrix.dict.complement(tbl)
- tbl = matrix.dict.pow(tbl, number)
- tbl = matrix.dict.scal(tbl, number)
- tbl = matrix.dict.inv(tbl)
- tbl \(=\) matrix.dict.sqrt(tbl)
- \(\mathrm{tbl}=\) matrix. dict. \(\exp (\mathrm{tbl})\)
- tbl = matrix.dict.plogp(tbl)
- tbl \(=\) matrix.dict. \(\log 1 p(t b l)\)
- tbl = matrix.dict.cos(tbl)
- \(\mathrm{tbl}=\) matrix. dict. \(\cosh (\mathrm{tbl})\)
- \(\mathrm{tbl}=\) matrix.dict.acos(tbl)
- tbl = matrix.dict.acosh(tbl)
- tbl = matrix.dict.tan(tbl)
- tbl = matrix.dict.tanh(tbl)
- \(\mathrm{tbl}=\) matrix.dict.atan(tbl)
- \(\mathrm{tbl}=\) matrix.dict.atanh(tbl)
- tbl = matrix.dict.sin(tbl)
- tbl = matrix.dict.sinh(tbl)
- \(\mathrm{tbl}=\) matrix.dict.asin(tbl)
- tbl = matrix.dict.asinh(tbl)

\section*{Chapter 6}

\section*{tokens package}

\subsection*{6.1 Introduction}

Package tokens could be loaded via the standalone binary, or in Lua with require("aprilann.tokens").
A Token is an abstract \(\mathrm{C}++\) class which has different specializations for different tasks and purposes. This class and its specializations are binded to Lua, allowing Lua scripts to be a glue language between C++ algorithms which are developed over the Token abstraction.
In this way, the current implementation of Artificial Neural Networks (ANNs) receives as input a token and produce a as output a token. Normally, for ANNs, this token contains a matrix, but it is also possible to wrap matrix.sparse objects and token vectors. Every ANN component checks the token type, and specialized computations could be done depending in the token type.

From Lua side, matrix instances can be given and taken as tokens.

\subsection*{6.2 Abstract class: tokens.base}

This class defines the basic interface shared for all token types. It is an abstract class which couldn't be instantiated in Lua. If you try, you will see the following message:
```

> tokens.base()
tokens.base:tokens.base: Abstract class!!!
stack traceback:
[C]: in function 'base'
stdin:1: in main chunk
[C]: in ?

```

Usually, \(\mathrm{C}++\) method calls return an instance to the class tokens.base, but in some cases it is possible to transform the generic reference to any of the child classes, or in other cases, it is possible to retrieve the contained data.

The transformation between tokens and matrix instances is performed automatically by the glue code between C++ and Lua.

\subsection*{6.2.1 Interface methods}

The following methods are in the generic interface of tokens.base class.

\subsection*{6.2.1.1 clone}
token \(=\mathrm{t}:\) clone ()
The method clone is implemented in all the tokens, and returns a deep copy of the caller.

\subsection*{6.3 Token types}

\subsection*{6.3.1 Token bunch vector}
tokens.vector.bunch
The token bunch vector is an array of tokens. Some ANN components allow to receive a vector of tokens which could contain sparse vectors.
```

> t = tokens.vector.bunch()
> t = tokens.vector.bunch(10)
> t = tokens.vector.bunch{ t1, t2, ... }

```

\subsection*{6.3.1.1 clear}
\(\mathrm{t}=\mathrm{t}:\) clear ()
```

6.3.1.2 size
number = t:size()

```

\subsection*{6.3.1.3 set}
```

t = t:set(position, token)

```
> = t:set(1, matrix(2,3):linear())

\subsection*{6.3.1.4 push__back}
\(\mathrm{t}=\mathrm{t}:\) push_back(token)
> = t:push_back(matrix (1,2):linear())
```

6.3.1.5 at
token = t:at(position)
> = t:at(1)
> = t:at(2)

```

\subsection*{6.3.1.6 iterate}
```

lua iterator = t:iterate()
> for i,v in t:iterate() do print(i) print(v) end

```

\section*{Chapter 7}

\section*{dataset package}

\subsection*{7.1 Introduction}

Package dataset could be loaded via the standalone binary, or in Lua with require("aprilann.dataset").
The dataset table is a namespace and a Lua abstract class which adds an abstraction layer of set of patterns to the multi-dimensional matrices. It is also possible to do patterns pre-processing and, union and join operations of different datasets, an identity matrix dataset, and so on.

Every dataset implements following methods:
- number \(=\) ds:numPatterns(), it returns the number of patterns in the given ds dataset.
- number \(=\) ds:patternSize(), it returns the size of one pattern.
- table \(=\) ds:getPattern(i), it receives a number between 1 and numPatterns(), and returns a table with the i-th pattern.
- ds:putPattern(i,t), it receives a number between 1 and numPatterns(), and a table with patternSize() numbers, and overwrites the i-th pattern with the given table.
- iterator \(=\) ds:patterns(), an iterator function to use in Lua for statements: for \(i, t\) in ds:patterns() do ... end.
- table \(=\) ds:mean(), it returns the mean per each pattern component.
- table,table = ds:mean_deviation(), it returns the mean and standard deviation per each pattern component.
- number, number \(=\) ds:min_max(), it returns the minimum and maximum value of the dataset.
- ds:normalize_mean_deviation(), it receives two tables of patternSize length, the first with means, and the second with standard deviations, and the method normalizes the data substracting mean and dividing by standard deviation.
- matrix = ds:toMatrix(), it returns a new allocated bi-dimensional matrix object which contains all dataset patterns (numPatterns rows and patternSize columns).

\section*{7.2 dataset.matrix}

This is the most important kind of dataset, allowing to create patterns moving a multi-dimensional window through a matrix object. This dataset takes the matrix by reference, so any change in the matrix will be reflected in the patterns produced by the dataset:
```

xor_in = matrix(4,2, {0,0,
0,1,

```
```

    1,0,
    1,1})
    xor_out = matrix(4, {0, 1, 1, 0})
-- by default, dataset.matrix traverses the matrix by rows
ds_xor_in = dataset.matrix(xor_in)
ds_xor_out = dataset.matrix(xor_out)

```

For a given matrix with dimensions \(n 1, n 2, \ldots, n k\), by default the dataset contains \(n 1\) number of patterns with size \(n 2 \mathrm{x} \ldots \mathrm{x} n \mathrm{k}\). For a bidimensional matrix it is a row-major order traversal. For a vector, it is the traversal of all its elements:
```

>a = matrix(2, 2, {1,2,3,4})
> b = dataset.matrix(a)
> for i,j in b:patterns() do print(table.concat(j,",")) end
1,2
3,4
>a = matrix(2,2,2,{1,2,3,4,5,6,7,8})
> b = dataset.matrix(a)
> for i,j in b:patterns() do print(table.concat(j,",")) end
1,2,3,4
5,6,7,8
>a = matrix(4,{1,2,3,4})
> b = dataset.matrix(a)
> for i,j in b:patterns() do print(table.concat(j,",")) end
1
2
3
4

```

Until this point, none benefit of dataset over matrix is presented. We are going to show that for the same given matrix, we could generate several different dataset modifying some parameters which has been taken by default until now.
When we instantiate a dataset.matrix, the first argument is a K-dimensional matrix with size n 1 X n 2 x \(\ldots \quad \mathrm{x} \mathrm{nK}\). The second argument could be a Lua table with the following fields:
- patternSize, a table array with \(\mathbf{K}\) positive integers. It indicates the size of each pattern taken from the underlying matrix. By default it is patternSize=\{ 1, n2, n3, ..., nK \}.
- offset, a table array with \(\mathbf{K}\) signed integers. It indicates the offset of the first pattern. A negative value is useful to compute a pattern which traverses the matrix limits. The first initial position is 0 . Its default value is offset \(=\{0,0, \ldots, 0\}\).
- numSteps, a table with \(\mathbf{K}\) estrict positive integers ( \(>0\) ). It indicates the number of steps used for each dimension to generate all the possible patterns. Its default value is numSteps=\{n1, 1, .., 1\(\}\). The total numPatterns() method returns the product of all numSteps components.
- stepSize, a table with \(\mathbf{K}\) signed integers. It indicates the number of coodinates which are slided for each dimension with every pattern. Its default value is stepSize \(=\{1, \ldots, 1\}\). Obviusly, in every i dimension where numSteps [i]=1, the stepSize[i] is not important. Depending on the values of stepSize and patternSize, the matrix will be traversed with overlapping between patterns or not.
- orderStep, a table with a permutation of the \(\mathbf{K}\) dimensions, indicating the order for matrix traversal. By default, the matrix is traversed in row_major order, so its value is orderStep=\{ \(K-1, K-2, \ldots\), \(2,1,0\}\). Varying the order of this numbers, it is possible to produce a different order traversal, as for example a col_major order.
- defaultValue is a number (not necesarily an integer), used to fill the pattern positions which are out of the matrix limits. By default its value is defaultValue=0.
- circular is a table with \(\mathbf{K}\) booleans (true or false) which indicate for every matrix dimension if it is circular or not. By default it is false in all dimensions circular=\{ false, false, ..., false \}. When a dimension is not circular, the pattern positions out of the matrix limits are filled with defaultValue. When a dimension is circular, the pattern positions out of the matrix are re-interpreted starting at the first position of this dimension in the matrix. For example, a bi-dimensional matrix whith one circular dimension seems cilindrical. If the two dimensions are circular, it seems thyroidal (like a donut).

Look a short example of this parameters. We want to generate a dataset with binary XOR patterns using only one matrix:
```

> m_xor = matrix.fromString[[
4 3
ascii
0 0
0 1 1
1 0 1
1 0
]]
> ds_input = dataset.matrix(m_xor,{patternSize={1,2}})
> ds_output = dataset.matrix(m_xor,{offset={0,2},patternSize={1,1}})
> for i=1,ds_input:numPatterns() do
>> printf("%d -> Input: %s Output: %s\n",i,
>> table.concat(ds_input:getPattern(i),","),table.concat(ds_output:getPattern(i),","))
>> end
-> Input: 0,0 Output: 0
-> Input: 0,1 Output: 1
-> Input: 1,0 Output: 1
4 -> Input: 1,1 Output: 0

```

We could implement the following function:
```

function dataset_pair(m,sizein,sizeout)
local d_in = dataset.matrix(m,{patternSize = {1,sizein}})
local d_out = dataset.matrix(m,{offset={0,sizein},patternSize = {1,sizeout}})
return d_in,d_out
end
-- which could be used as this
ds_input,ds_output = dataset_pair(m_xor,2,1)

```

\section*{7.3 dataset.identity}

This dataset represents the traversing of an identity matrix. It receives as first argument the number of patterns (which is at the same time the patternSize), a second optional argument which is the value of zero (by default is 0.0 ), and a third optional argument with the value of one (default is 1.0 ).
```

> ds_eye = dataset.identity(5)
> print(ds_eye:toMatrix())

```
```

| 1 | 0 | 0 | 0 | 0 |
| :--- | :---: | :---: | :---: | :---: |
| 0 | 1 | 0 | 0 | 0 |
| 0 | 0 | 1 | 0 | 0 |
| 0 | 0 | 0 | 1 | 0 |
| 0 | 0 | 0 | 0 | 1 |
| $\#$ | Matrix of size $[5,5]$ | in row_major | $[0 \times 1418 b d 0$ | data= $0 \times 1418 c d 0]$ |

```

The dataset.identity is equivalent to following code, but is more efficient:
```

> ds_eye = dataset.matrix(matrix(5,5):zeros():diag(1))
> print(ds_eye:toMatrix())

| 1 | 0 | 0 | 0 | 0 |
| :--- | :--- | :--- | :--- | :--- |
| 0 | 1 | 0 | 0 | 0 |
| 0 | 0 | 1 | 0 | 0 |
| 0 | 0 | 0 | 1 | 0 |
| 0 | 0 | 0 | 0 | 1 |

# Matrix of size [5,5] in row_major [0x129f930 data= 0x12fb470]

```

\section*{7.4 dataset.indexed}

The dataset.indexed allows to map indexes with patterns. It is useful to specify the output of a classification task, in which case the underlying dataset will be the association of ANN output for each of the classes. Another possibility is to use dataset. indexed to select a random set of patterns from the underlying dataset. NOTE that dataset.indexed uses float numbers to represent the indices, so the maximum integer number which could be indexed is 16777216 . If you need more resolution, use dataset.index_filter (which is less general than this).

The constructor receives 2 arguments, the first is the base dataset. The second is a table array with as many dataset objects as patternSize() of the base dataset, acting every one of this as a dictionary. The patternSize() of the resulting dataset.indexed object is equals to the sum of the patternSize() of all the dictionaries.

Following code is an example for a classification task ANN output:
```

> dict = dataset.identity(10)
> -- a random matrix with integers [1,10]
> m_base = matrix(100):uniform(1,10,random(1234))
> ds_base = dataset.matrix(m_base)
> indexed_ds = dataset.indexed( ds_base, { dict })

```

The following is code for a random subset of patterns from a given dataset:
```

-- a matrix with 100 patterns with real numbers in [-1,1]
> m_dict = matrix(100, 10):uniformf(-1,1,random(1234))
> dict = dataset.matrix(m_dict)
> -- a random matrix with 10 integers in range [1,100], a selection of patterns
> m_base = matrix(10):uniform(1,100,random(1234))
> ds_base = dataset.matrix(m_base)
> indexed_ds = dataset.indexed( ds_base, { dict })

```

\section*{7.5 dataset.index_filter}

The dataset.index_filter is like dataset.indexed but only for the case of indexing a random subset of patterns from a given base dataset, which receives as first argument. As second argument, a vector of unsigned integers (util.vector_uint) is expected.
```

> -- a dataset with 100 patterns of size 5, randomized at range [0,1]
> base_ds = dataset.matrix(matrix(100,5):uniformf())
> uint_vector = util.vector_uint()
> rnd = random(1234)
> -- a subset of 10 patterns from indices at range [1,100]
> for i=1,10 do uint_vector:push_back( rnd:randInt(1,100) ) end
> print(uint_vector)

| 48 | 84 | 39 | 54 | 77 | 25 | 16 | 50 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |

# vector_uint of size 10

> index_filter_ds = dataset.index_filter(base_ds, uint_vector)
> print(index_filter_ds:toMatrix())

| 0.528819 | 0.915766 | 0.220549 | 0.828223 | 0.28173 |
| :--- | :--- | :--- | :--- | :--- |
| 0.73919 | 0.424762 | 0.354582 | 0.368474 | 0.0355779 |


| 0.512678 | 0.494687 | 0.731773 | 0.672073 | 0.411915 |
| :--- | :--- | :--- | :--- | :--- |


| 0.575729 | 0.169612 | 0.346667 | 0.925921 | 0.332662 |
| :--- | :--- | :--- | :--- | :--- |


| 0.298257 | 0.460495 | 0.179573 | 0.32725 | 0.610076 |
| :--- | :--- | :--- | :--- | :--- |


| 0.219746 | 0.15807 | 0.581498 | 0.531874 | 0.200707 |
| :--- | :--- | :--- | :--- | :--- |

    0.00641197 0.86275 0.407079 0.279832 
    0.456097 0.463612 0.521626 0.951389 0.659111
    0.4136 0.734821 0.212726 0.314356 0.50499
    0.662668 0.584882 0.457253 0.325801 0.217475
    
# Matrix of size [10,5] in row_major [0x12a2710 data= 0x13eaa10]

```

\section*{7.6 dataset.join}

The dataset.join object joins the outputs from several dataset objects which has the same numPatterns. The patternSize of the resulting dataset is equals to the sum of every patternSize of its components. It requieres as argument a table with the datasets which you want to join.
```

-- ds1, ds2 and ds3 are three datasets with the same numPatterns
> join_ds = dataset.join{ ds1, ds2, ds3 }

```

\section*{7.7 dataset.union}

This dataset allows to convert several dataset objects with the same patternSize as they were one unique dataset which its numPatterns is equals to the sum of all the numPatterns of every given dataset. It receives only one argument, a table with the dataset which will be unionized.
```

> -- ds1, ds2 and ds3 are datasets with the same patternSize
> union_ds = dataset.union{ ds1, ds2, ds3 }

```

\section*{7.8 dataset.slice}

The dataset.slice is useful to extract a contiguous subset of patterns from a given dataset (for more general subsets use dataset.indexed or dataset.index_filter). It requieres 3 arguments. The first is the base dataset. The second and third arguments are the initial and final indices of the patterns which form the subset (first valid index is 1, and last valid index is numPatterns() of base dataset).
```

> -- slice with 100 patterns, from 101 to 200
> slice_ds = dataset.slice(base_ds, 101, 200)

```

\section*{7.9 dataset.deriv}

The dataset.deriv receives a dataset and outputs the original data, the first derivative, or the second derivative, depending on the parameters received. It receives a table with a maximum of four fields:
- dataset: the base dataset, which contains data for derivative computation.
- deriv0: an optinal boolean, by default is true, which indicates if the output of the dataset will contain the original pattern, without derivative.
- deriv1: an optinal boolean, by default is true, which indicates if the output of the dataset will contain the first derivative.
- deriv2: an optinal boolean, by default is true, which indicates if the output of the dataset will contain the second derivative.
```

> -- ds is the base dataset
> only_first_deriv_ds = dataset.deriv{ dataset=ds, deriv0=false, deriv1=true, deriv2=false }

```

\subsection*{7.10 dataset.contextualizer}

The contextualizer is a dataset which adds context from the adjacent patterns (left and right). If any of the adjacent patterns is out of the base dataset size, it fills it with the first or the last pattern. The constructor receives four arguments:
1. The base dataset.
2. The size of the left context.
3. The size of the right context.
4. A boolean optionally argument indicating if the left and right contexts needs to be swapped. By default is false, and in almost all cases it is what you need ;)
```

> ds = dataset.contextualizer(dataset.identity(2,0,1),1,1)
>
> print(ds:toMatrix())

| 1 | 0 | 1 | 0 | 0 | 1 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 0 | 0 | 1 | 0 | 1 |
| \# Matrix of size | $[2,6]$ | in row_major | $[0 \times 18357 b 0$ | data | 0x18358b0] |

```

\subsection*{7.11 dataset.split}

This dataset allows to select a subset of the components of patterns produced by another dataset. So, the resulting dataset will have the same number of patterns, but different pattern size. The subset is an interval of the base dataset. It receives three positional arguments:
1. The base dataset.
2. The first position in the interval (counting from 1).
3. The last position in the interval (counting from 1).
```

> ds = dataset.split(dataset.identity(5,0,1), 2, 4)
> print(ds:toMatrix())

| 0 | 0 | 0 |
| :--- | :--- | :--- |
| 1 | 0 | 0 |
| 0 | 1 | 0 |
| 0 | 0 | 1 |
| 0 | 0 | 0 |

# Matrix of size [5,3] in row_major [0xcb0f80 data= 0xcb1080]

```

\subsection*{7.12 dataset.perturbation}

\subsection*{7.13 dataset.salt_noise}

\subsection*{7.14 dataset.sub__and__div__normalization}

This dataset applies on-the-fly a subtraction and division normalization, as for example a zero-mean one-standard-deviation normalization. So, for a dataset with \(N\) patternSize, given a vector of sub values s1, s2, \(\ldots, s N\), and a vector of div values \(\mathrm{d} 1, \mathrm{~d} 2, \ldots, \mathrm{dN}\), a ds:getPattern(i) of the resulting dataset will produce a pattern with (v1-s1)/d1, (v2-s2)/d2, ..., (vN-sN)/dN, being vj the \(j\) component of pattern i.
```

> eye_ds = dataset.identity(5,0,1)
> sub,div = {1,2,-1,2,-1},{0.1,0.1,0.1,0.1,0.1}
> ds = dataset.sub_and_div_normalization(eye_ds,sub,div)
> print(ds:toMatrix())

| 0 | -20 | 10 | -20 | 10 |
| :---: | :---: | :---: | :---: | :---: |
| -10 | -10 | 10 | -20 | 10 |
| -10 | -20 | 20 | -20 | 10 |
| -10 | -20 | 10 | -10 | 10 |
| -10 | -20 | 10 | -20 | 20 |

# Matrix of size [5,5] in row_major [0xf47d70 data= 0xcfa060]

```

\section*{Chapter 8}

\section*{The token dataset: dataset.token}

\subsection*{8.1 Methods}

\subsection*{8.1.1 numPatterns}

\subsection*{8.1.2 patternSize}

\subsection*{8.1.3 getPattern}
token \(=\) ds:getPattern(number)

\subsection*{8.1.4 getPatternBunch}
```

token = ds:getPatternBunch(table)

```

\subsection*{8.1.5 putPattern}
8.1.6 putPatternBunch

\subsection*{8.1.7 patterns}

\section*{8.2 dataset.token.sparse_matrix}
```

ds = dataset.token.sparse_matrix(sparse matrix in CSR)
> m = matrix.sparse.diag{1,2,3,4,5,6}
> ds = dataset.token.sparse_matrix(m)
> print(ds:getPattern(1))
1 0 0 0 0

# SparseMatrix of size [1,6] in csr [0x2aea350 data= 0x2aea420 0x2aea4a0 0x2aea4e0], 1 non-zeros

> print(ds:getPatternBunch{3,5})

```


\section*{8.3 dataset.token.union}
```

ds = dataset.token.union(table)

```

\section*{8.4 dataset.token.vector}
```

ds = dataset.token.vector(psize)
ds:push_back(token)

```

\section*{8.5 dataset.token.filter}
```

ds = dataset.token.filter(dataset, obj)

```

\subsection*{8.6 My own Lua dataset.token}

It is possible to develop Lua dataset classes which has to complain interface of dataset.token class. The unique restriction is that your Lua dataset couldn't be used as input to other C++ dataset objects. However, the Lua dataset can use C++ objects or Lua objects without making any distinction.

The following is a piece of a pure Lua dataset.token which replicates the behavior of dataset.join, but using tokens. matrix type is needed for instances which you want to join.
```

ds_join,ds_join_methods = class("ds_join")
function ds_join:constructor(t)
assert(type(t)=="table" and \#t>0,
"Needs an array of dataset.token instances as argument")
local psize = 0 -- we sum here the pattern size of all the given datasets
local nump = 0 -- we store here the number of patterns, which must be
-- equals in all the given datasets
local data = {} -- this table will store the given datasets
for _,v in ipairs(t) do
psize = psize + v:patternSize()
local aux_nump = v:numPatterns()
assert(nump==0 or nump==aux_nump)
nump = aux_nump
table.insert(data, v)
end
self.data=data
self.num_patterns=nump
self.pattern_size=psize
end
function ds_join_methods:numPatterns() return self.num_patterns end
function ds_join_methods:patternSize() return self.pattern_size end
function ds_join_methods:getPattern(idx)
-- use the given matrix or construct a new one

```
```

    local m = matrix(1,self:patternSize())
    local col_pos = 1
    for _,ds in ipairs(self.data) do
        local psize = ds:patternSize()
        local dest_m = m:slice({1,col_pos}, {1,psize})
        dest_m:copy(ds:getPattern(idx))
        col_pos = col_pos + psize
    end
    return m
    end
function ds_join_methods:getPatternBunch(idxs)
-- use the given matrix or construct a new one
local m = matrix(\#idxs,self:patternSize())
assert(m:dim(1)==\#idxs and m:dim(2)==self:patternSize())
local col_pos = 1
for _,ds in ipairs(self.data) do
local psize = ds:patternSize()
local dest_m = m:slice({1,col_pos}, {\#idxs,psize})
dest_m:copy(ds:getPatternBunch(idxs))
col_pos = col_pos + psize
end
return m
end

```

\section*{Chapter 9}

\section*{ann package}

\subsection*{9.1 Introduction}

Several packages contain neural networks stuff: require("aprilann.ann"), require("aprilann.ann.loss"), require("aprilann.ann.optimizer"), require("aprilann.trainable").

This page describe the utilities to build and train ANNs. Four main sections are written: a desciprion of ANN concepts in APRIL-ANN, the easy building procedure for MLPs, the training helpers, and finally the full description of the aprilann.ann package.

\subsection*{9.2 ANN components}

Inspired by other toolkits (as Torch 7 or pyBrain), ANNs are described as a composition of blocks call ANN components, so one component is a neural network itself. A list of all available components appears executing:
```

april_help(ann.components)

```

Nevertheless, the composition procedure will be explained later. An ANN component is identified by a name string (which will be automatically generated if not given). The name must be unique. Some components contains weights in their core, which are estimated by gradient descent algorithm (backpropagation). Connection weights objects are identified by a weights name parameter, which could be reused. If two components have the same weights name, then they share the same connections object.

All components have an input and output size, which defines the number of weights (if needed) and the fan-in/fan-out of the component. Components need to be build (build method) once they are constructed. Build procedure allocates memory for connections and checks input/output sizes of components.

More accurate description is available at april_help, but don't be affraid, the next section presents an abstraction for train MLPs which automatically does a lot of this work:
```

april_help(ann.components.base)
april_help(ann.components.base.build)

```

\subsection*{9.3 The easy way: all-all MLP}

The simpliest kind of ANN is a Multilayer Perceptron (MLP) where each layer is fully connected with the next layer (feed-forward, all-all connections).

\subsection*{9.3.1 Building the MLP: ann.mlp.all__all.generate}

The method generate returns an special component object, which cannot be modified. Actually, it is a Lua table formed by an ann. components.stack instance and other information useful to load and save the MLPs, and it implements wrapper Lua functions to ANN component methods.
```

-- creates an ANN component for a MLP with the given description
thenet = ann.mlp.all_all.generate("256 inputs 128 tanh 10 log_softmax")
-- creates an instance of a trainer object for previous ANN component,
-- using the multi-class cross-entropy loss function (for 10 output units),
-- and using a bunch_size of 32. Loss function and bunch_size are optional.
trainer = trainable.supervised_trainer(thenet,
ann.loss.multi_class_cross_entropy(10),
32,
-- this last parameter is optional, by default is
-- SGD => Stochastig Gradient Descent
ann.optimizer.sgd())
-- builds the component contained into trainer object
trainer:build()
-- initializes the weights randomly, using fan-in and fan-out
trainer:randomize_weights{
random = random(1234),
inf = -0.1,
sup = 0.1,
use_fanin = true,
use_fanout = true,
}

```

As said before, each component has a unique name, and if needed a weights name. The next code iterates over all components:
```

> for name,c in trainer:iterate_components() do print(name,c) end
actf1 instance 0x7fc3e94850a0 of ann.components.base
actf2 instance 0x7fc3e9485550 of ann.components.base
b1 instance 0x7fc3e9484f80 of ann.components.base
b2 instance Ox7fc3e9485410 of ann.components.base
c1 instance 0x7fc3e9484a10 of ann.components.base
layer1 instance 0x7fc3e9484e80 of ann.components.base
layer2 instance 0x7fc3e9485310 of ann.components.base
w1 instance 0x7fc3e9484ee0 of ann.components.base
w2 instance 0x7fc3e9485370 of ann.components.base

```

The MLP is composed by 9 components, two activation functions (actf1 and actf2), two bias components (b1 and b2), one stack component which works as a container (c1), two hyperplane components containing one bias and one dot_product each one (layer1 and layer2), and finally two dot_product components (w1 and w2) which contains weight matrixes.

It is also possible to iterate over all weigths names:
```

> for name,connections in trainer:iterate_weights() do print(name,type(connections)) end
b1 matrix

```
```

b2 matrix
w1 matrix
w2 matrix

```

So, our MLP contains two bias vectors (b1 and b2, corresponding with b1 and b2 components), and two weights matrixes ( w 1 and w2, corresponding with w1 and w2 components). All MLPs generated automatically assign this names to its components and weights.

One time the component is build by using a trainer instance, the trainer exposes two interesting methods trainer:component (COMPONENT_NAME_STRING) which returns the component given its name, and trainer:weights(WEIGTHS_NAME_STRING) which returns the connection weigths object given its weigths_name attribute.

More info about trainable.supervised_trainer doing:
april_help(trainable.supervised_trainer)

\subsection*{9.3.2 Loss functions: ann.loss}

The loss function is used to train the ANNs via gradient descent algorithm. Trainer objects needs an instance of a loss function to perform training, being a very useful abstraction of standard training procedures.

Detailed information about loss functions is in:
```

april_help(ann.loss)

```

The loss function could be set at trainer constructor, or using the method set_loss_function:
trainer:set_loss_function(ann.loss.mse())

Three main error functions are implemented: mean square error (MSE), two class cross-entropy, and multiclass cross-entropy. Note that cross-entropy like functions are specialized for log_logistic or log_softmax output activation functions. Almost all the constructors accepts a SIZE=0 parameter, which means that the layer has a dynamic size.:
- ann.loss.mse(SIZE) returns an instance of the Mean Squared Error error function for SIZE neurons. It is a quadratic loss function.
- ann.loss.mae(SIZE) returns an instance of the Mean Absolute Error function, for SIZE neurons. It is not a quadratic loss function.
- ann.loss.cross_entropy (SIZE) returns an instance of the two-class cross-entropy. It only works with log_logistic output activation function. It is based on Kullback-Leibler divergence.
- ann.loss.multi_class_cross_entropy (SIZE) returns an instance of the multi-class cross-entropy. The parameter must be SIZE>2, so for two-class problems only one output unit with cross-entropy is needed. It only works with log_logistic or log_softmax output activation function (its better to use log_softmax). It is based on Kullback-Leibler divergence.

\subsection*{9.3.3 ann.optimizer}

The optimizer is an object which implements the learning algorithm. Every class in ann.optimizer is an optimizer. Several learning hyperparameters are available, depending in the selected optimizer. This learning hyperparameters are known as options, and could be set globally (to all the connection weight layers of the ANN), or layerwise (to a concrete connection weights object, identified by its name). Optimizers implement the following API:
- other \(=\) optimizer:clone(): returns a deep copy of the caller object.
- value = optimizer:get_option(name): return the global value of a given learning option name.
- optimizer: set_option(name, value): sets the global value of a given learning option name.
- optimizer:set_layerwise_option(layer_name, option_name, value): sets a layerwise option.
- value = optimizer:get_layerwise_option(layer_name, option_name): returns the layerwise option of the given.
- value = optimizer:get_option_of(layer_name, option_name): returns the option which is applicable to the given layer_name. If a layerwise option was previously defined, the method returns its value. Otherwise, the value of the global option will be returned.

\subsection*{9.3.3.1 ann.optimizer.sgd}

Different optimizer objects are implemented. They train the neural network following different algorithms which rely in the computation of gradients done by ANN components. Them incorporate regularization and momentum hyperparameters. They options are algorithm dependentendt. In case of Stochastic Gradient Descent, the options are:
- learning_rate: the learning rate controls the portion of the gradient used to update the weights. This value is smoothed depending in the bunch_size and in the number \(K\) of times that a weight connections object is shared between different components. The smoothing value: learning_rate/sqrt(bunch_size+K)
- momentum: is a inertial hyperparameter which applies a portion of the weight update in the previous iteration.
- weight_decay: a L2 regularization term.
- L1_norm: a L1 regularization term.
- max_norm_penalty: a constrain penalty based on the two-norm of the weights.

The algorithm uses the following learning rule:
\(\mathrm{w}=(1-\mathrm{weight} \text { _decay)})_{\mathrm{w}}{ }^{\prime}+\operatorname{momentum*(\mathrm {w}^{\prime }}\) - w") + lr'*grad(L)/grad(w')
where w , \(\mathrm{w}^{\prime}\) and \(\mathrm{w}^{\prime \prime}\) are the weight values at next, current, and previous iterations; lr' is the learning_rate smoothed by the sqrt, and \(\operatorname{grad}(\mathrm{L}) / \operatorname{grad}\left(\mathrm{w}^{\prime}\right)\) is the loss function gradient at the given weight.

\subsection*{9.3.4 Trainer set and get of hyperparameters}

The hyperparemters of optimizer objects can be modified by the trainer object:
- trainer:set_option(name, value): sets a global learning option value.
- value=trainer: get_option(name): gets a global learning option value.
- trainer:set_layerwise_option(layer_name_match,option_name,value): sets a layerwise learning option value of all the connection weight objects whose name matches the given layer_name_match Lua pattern string.
- value=trainer:get_option_of(layer_name,option_name): gets the option value applicable to the given layer.
```

trainer:build()
trainer:set_option("learning_rate", number)
trainer:set_option("momentum", number)
-- regularization is recommended to not be applied at bias connections
trainer:set_layerwise_option("w.*", "weight_decay", number)
trainer:set_layerwise_option("w.*", "max_norm_penalty", number)
-- for dropout (see dropout http://www.cs.toronto.edu/~nitish/msc_thesis.pdf)
-- dropout is a very especial option, it modifies training, but also modifies
-- validation (or test) phase. Also it must be applied carefully to not apply
-- dropout at the output of your model. Dropout is applied as another component
-- which acts as a stochastic filter.

```

\subsection*{9.4 Supervised trainer description}

See the documentation for trainable package.

\subsection*{9.4.1 Stopping criteria}

See the documentation for trainable package.

\section*{9.5 ann package reference}

ANNs are implemented as a composition of components which implements define the three main operations of an ANN: forward step (compute outputs), backprop step (neuron gradient computation), and gradient computation step (weight gradients). All components are child classes of ann.components.base. See april_help(ann.components.base) for on-line documentation.

Two main remarks before continue following sections. The components has two special properties:
- name: is a string which identifies the component in a unique manner, is forbidden that two components sharing the same name.
- weights_name: is a string which identifies the connections (weights or biases) of the component. This name could be share by different components, which means that they share the same connections object.

\subsection*{9.5.1 Tokens and matrices}

The components are integrated in Lua via the abstract class token, which has two specializations for ANNs:
- tokens.matrix is a token which contains a matrix instance.
- tokens.sparse_matrix is a token which contains a matrix.sparse instance.

In any case, ANN components wrap the given matrix objects into a token, and unwrap matrix objects when returning a token. So, in practice, you can ignore the token/matrix association.

NOTE that ANN components work with dense matrix or with csr sparse matrices.

\subsection*{9.5.2 Components basis}

All components has defined the following basic properties, which are tokens: input, output, error_input, and error_output. Four are the basic methods to train the components:
- component,table,table \(=\) build(): this method reserves memory for weights and prepares the component to work with.
- reset(iteration): it releases all the tokens internally allocated (or given by Lua), and receives the current iteration number. This iteration is not related with the training loop or epoch, it is related to optimizer objects which implement line search or similar (Conjugate Gradient or RProp).
- token=forward(token[, boolean]): it receives an input token and returns the output token. For simplicity, it is possible to give a matrix instead of a token, and the method will wrap automatically the given matrix. In any case, the returned value is a token.
- token=backprop(token): it receives an error input token (gradient), and returns the output error token (gradient). For simplicity, it is possible to give a matrix instead of a token, and the method will wrap automatically the given matrix. In any case, the returned value is a token.
- gradients=compute_gradients( [gradients] ): compute the weight gradients, by using the data stored at the components (input/output tokens, input/output error tokens), given and produced during forward and backprop methods. Additionally, it receives a table of matrix with previously computed gradients, which will be used to store the data avoiding the allocation of new memory. The method returns a table of matrix with the gradients computed for each connection weights object.

Combining this methods with loss functions a component could be trained following this basic example. A linear component is trained to follow OR function, for input \(=[0,1]\) and target output \(=[1]\). By default the weights are not initialized, so they contains memory trash.
```

> o = ann.optimizer.gsd() -- the optimizer
> l = ann.loss.mse(1) -- MSE loss function
> -- an hyperplane component (explained later)
> c = ann.components.hyperplane{ input=2, output=1 }
> c:build() -- allocates memory for weights, and checks components integrity
> l:reset() -- set to zero all the things
> c:reset() -- set to zero all the things
> o:execute(function()
-- the true indicates training
output_token=c:forward(matrix(1,2,{0,1}), true)
-- gradient with desired output 1

```
```

            output_error=c:backprop(l:gradient(output_token,
                            matrix(1,1,{1})))
    grad = c:compute_gradients(grad)
return l:compute_loss(output_token,
matrix(1,1,{1}),
grad
end, c:copy_weights())
> output_token=c:forward(matrix(1,2,{0,1}))
> print(output_token) -- the output is closer to 1
0.2

# Matrix of size [1,1] [0xb01ce0 data= 0xad97d0]

```

\subsection*{9.5.3 Methods common to all the components}

Note that all matrices must had at least two dimensions. All computations are done in bunch mode (using mini-batches) and the first dimension size is the number of patterns contained by the bunch. The rest of dimensions must complain the input constrains of the component. A lot of components work with linear inputs, so the input matrix will be bi-dimensional, but some components work with multidimensional matrices. It is possible to use matrices of only one dimension and they will be reinterpreted as two dimensional matrices with only one row, but better if you work always with two-dimensional matrices.

\subsection*{9.5.3.1 Building procedure}

Before doing anything, components could be composed together to build larger components. This procedure needs to call build method at the end, to check the input/output sizes and reserve memory for weights and biases.

The c:build() call executes recursively the build method of all the components composition. This method returns two tables:
```

> caller_component, weights_dict, components_table = c:build()

```

The caller_component is the component c in this case.
The weights_dict is a table of matrices, which indexes name (weight name) strings with weight matrices.
The components_table is a Lua table indexed by each name (component name) and contains a reference to the component instance, which is useful to initialize hyper-parameter and other stuff in a component-wise manner.

\subsection*{9.5.3.2 Input/output sizes}
- number = c:get_input_size(): returns the size of the input for the caller component. In case of unknown input size, a zero will be returned.
- number = c:get_output_size(): returns the size of the output for the caller component. In case of unknown output size, a zero will be returned.
- table = c:precompute_output_size( [table] ): allows to compute the output size shape, given an input shape. It is useful to be combined with convolutional ANNs, in order to ask for the output shape size of the convolution. The given table must complains the expected input shape of the component (normally is one dimension, but with CNNs it could be multi-dimensional). The returned table will contain as many dimensions as the produced by the caller component (idem as for input).

\subsection*{9.5.3.3 Back-propagation computation methods}
- token = c:forward ( token [, boolean] ) receives a token and an optional boolean (by default false). The boolean indicates if this forward is during training or not, because some components has an special behavior during training. It returns a token with the output computation of the caller component. For simplicity, it is possible to give a matrix instead of a token, and the method will wrap automatically the given matrix. In any case, the returned value is a token.
 and returns another token with the output error (gradient of each input neuron). For simplicity, it is possible to give a matrix instead of a token, and the method will wrap automatically the given matrix. In any case, the returned value is a token.
- gradients = c:compute_gradients ( gradients ) returns the weight gradients computed using the tokens given at forward and backprop methods.
- c:reset() releases the retained tokens in forward and backprop steps.

\subsection*{9.5.3.4 Getters of produced and retained tokens}

During forward and backprop steps the components compute outputs and error outputs (gradients), and retain the input and error input (gradients) tokens. Before call reset method, you could ask the component for its retained tokens:
- token = c:get_input() returns the token given as input at forward method.
- token = \(\mathrm{c}:\) get_output () returns the token computed as output by forward method.
- token = c:get_error_input() retruns the token given as error input at backprop method.
- token = c:get_error_output() returns the token computed as error output by backprop method.

\subsection*{9.5.4 Weights matrices and bias vectors}

Components which require weights has internally a matrix instance. This object is allocated calling the build method of the components (or using the build method of a trainer), and is identified by the weigths_name property, so components with the same weigths_name share the same connections object.

This matrices are defined with OUTPUTxINPUT size (output rows, input columns), so:
- Bias vectors: has INPUT=1 and OUTPUT=number of neurons, and they are a column vector.
- Weight matrices: contain OUTPUTSxINPUTS weights.

The weights matrices has this format:
```

w(i1,o1) w(i2,o1) w(i3,o1) ...
w(i1,o2) w(i2,o2) w(i3,o2) ...

```
where \(\mathrm{w}(\mathrm{a}, \mathrm{b})\) is the weight which connects input a with output b . Be sure that your matrices has this format.

\subsection*{9.6 Components list}

The ANN models are modular components which can be sorted in several ways to produce different topologies.

\subsection*{9.6.1 Basic components}

\subsection*{9.6.1.1 base}
```

ann.components.base{ size=0, [name=STRING] }

```

The class ann. components.base is the base of all ANN components. It is possible to instance an object of this class, and it performs identity function. The constructor receives optionally the name of the component. The constructor receives two optional arguments, the size=0, by default it allows any input size, and the name of the component.
```

> c1 = ann.components.base{ name="base1" }
> c2 = ann.components.base()
> input = matrix(10,10):uniformf(0,1,random(237))
> output = c2:forward(input)
> = output:equals(input)
true

```

\subsection*{9.6.1.2 bias}
ann.components.bias\{ size=NUMBER, [name=STRING], [weights=STRING] \}
The class ann. components.bias implements an additive bias of a given size. The bias is added iteratively to all the patterns in the bunch (mini-batch). The constructor receives two fields:
- name of the component, an optional field.
- weights name of the component, an optional field.
- size the size of the bias vector.

This components contains a vector of SIZEx1, which is added transposed to all the input patterns (first dimension of the bunch).
```

> b1 = ann.components.bias{ name='b1', weights='b1', size=5 }
> _,weights = b1:build()
> weights('b1'):linspace()
> = weights('b1')
1
2
3
4
5
Matrix of size [5,1] [0x162eb00 data= 0x16b0260]
input = matrix(4,5):linspace()
> = input

| 1 | 2 | 3 | 4 | 5 |
| :--- | :--- | :--- | :--- | :--- |
| 6 | 7 | 8 | 9 | 10 |

11 12 13 14

```
```

16 17 18 19 20

# Matrix of size [4,5] [0x185a3d0 data= 0x17e18d0]

> output = b1:forward(input)
> = output

| 2 | 4 | 6 | 8 | 10 |
| :--- | :--- | :--- | :--- | :--- |
| 7 | 9 | 11 | 13 | 15 |
| 12 | 14 | 16 | 18 | 20 |
| 17 | 19 | 21 | 23 | 25 |

# Matrix of size [4,5] [0x185b370 data= 0x1718450]

> -- the bias component executes the following operation
> for i=1,input:dim(1) do input(i,':'):axpy(1.0, weights('b1'):transpose()) end
> = input

| 2 | 4 | 6 | 8 | 10 |
| :--- | :--- | :---: | :---: | :---: |
| 7 | 9 | 11 | 13 | 15 |
| 12 | 14 | 16 | 18 | 20 |
| 17 | 19 | 21 | 23 | 25 |
| \# Matrix of size | $[4,5]$ | $[0 \times 185 a 3 d 0$ | data $=$ | $0 \times 17 e 18 d 0]$ |

```

\subsection*{9.6.1.3 dot_product}
```

ann.components.dot_product{ ... }

```

The class ann.components.dot_product implements the dot product between a weights vector of every neuron and the given input vector, which is a vector-matrix product. If the input is a matrix with a bunch of patterns, the component executes a matrix-matrix product. The component contains a weights matrix with size 0xI, where 0 is the number of neurons (output size), and I is the number of inputs (input size). The constructor receives:
- name is a string with the component name, optional.
- weights is a string with the weights name, optional.
- input is a number with the input size.
- output is the number of neurons.
- transpose=false is a boolean indicating if the weights matrix is transposed. It is optional, by default it is transpose=false.
```

> c = ann.components.dot_product{ weights='w1', input=4, output=5 }
> _,weights = c:build()
> weights('w1'):linspace()
> = weights('w1')

| 1 | 2 | 3 | 4 |
| :--- | :--- | :--- | :--- |
| 5 | 6 | 7 | 8 |
| 9 | 10 | 11 | 12 |
| 13 | 14 | 15 | 16 |
| 17 | 18 | 19 | 20 |

# Matrix of size [5,4] [0x186e620 data= 0x182b050]

> input = matrix(3,4):linspace()
> = input

| 1 | 2 | 3 | 4 |
| :--- | :--- | :---: | :--- |
| 5 | 6 | 7 | 8 |
| 9 | 10 | 11 | 12 |
| \# Matrix of size | $[3,4]$ | $[0 \times 168 f 420$ | data= |
| Ox1835190] |  |  |  |

```
```

> output = c:forward(input)
> = output

| 30 | 70 | 110 | 150 | 190 |
| :--- | :--- | :--- | :--- | :--- |
| 70 | 174 | 278 | 382 | 486 |
| 110 | 278 | 446 | 614 | 782 |

# Matrix of size [3,5] [0x185ee70 data= 0x18655c0]

> -- the performed operation is
> = input * weights('w1'):transpose()

| 30 | 70 | 110 | 150 | 190 |
| :--- | :--- | :--- | :--- | :--- |
| 70 | 174 | 278 | 382 | 486 |
| 110 | 278 | 446 | 614 | 782 |

# Matrix of size [3,5] [0x1869f50 data= 0x1645e60]

```

In case of very sparse inputs, it is possible to replace the input matrix by a tokens.sparse_matrix, allowing to improve the efficiency of the operation. Transformation of matrices into tokens and tokens into matrix is automatically performed.
```

> -- a matrix with two rows:
> -- first row: active components are the 3 with 1, and the 2 with 0.5
> -- second row: active components are the 1 with 0.3
> dense_input = matrix(2,4):zeros():set(1,3,1):set(1,2,0.5):set (2,1,0.3)
> sparse_input = matrix.sparse( dense_input )
> = sparse_input
0 0.5 1 0
0.3 0 0 0

# SparseMatrix of size [2,4] in csr [0x17deaa0 data= 0x17864b0 0x17c9540 0x167cdb0], 3 non-zeros

> output = c:forward(input)
> = output

| 4 | 10 | 16 | 22 | 28 |
| :--- | :--- | :--- | :--- | :--- |
| 0.3 | 1.5 | 2.7 | 3.9 | 5.1 |

# Matrix of size [2,5] [0x18612d0 data= 0x17fb8a0]

> -- which is equivalent to the following
> output = c:forward(dense_input)
> = output

| 4 | 10 | 16 | 22 | 28 |
| :--- | :--- | :--- | :--- | :--- |
| 0.3 | 1.5 | 2.7 | 3.9 | 5.1 |

# Matrix of size [2,5] [0x185ee70 data= 0x1636e60]

```

\subsection*{9.6.1.4 hyperplane}
ann.components.hyperplane\{ ... \}
The class ann.components.hyperplane is a wrapper around a bias and a dot_product components, implementing an hyperplane separator. The constructor receives:
- name an optional string with the component name.
- dot_product an optional string with the dot_product component name.
- bias an optional string with the bias component name.
- dot_product_weights an optional string with the dot_product component weights name.
- bias_weights an optional string with the bias component weights name.
- input a number with the input size.
- output a number with the input size.
- transpose=false a boolean indicating if the dot_product weights will be transposed in the operation.
```

> c = ann.components.hyperplane{ dot_product_weights='w1', bias_weights='b1',
input=128, output=256 }
> _,weights = c:build()
> for name,w in pairs(weights) do print(name) print(w) end
w1
Large matrix, not printed to display

# Matrix of size [256,128] [0x185ee70 data= 0x16ae840]

b1
Large matrix, not printed to display

# Matrix of size [256,1] [0x1869120 data= 0x165d540]

```

\subsection*{9.6.2 Activation function components}

\subsection*{9.6.2.1 logistic}
ann. components.actf.logistic()

\subsection*{9.6.2.2 log_logistic}
ann. components.actf.log_logistic()

\subsection*{9.6.2.3 softmax}
ann.components.actf.softmax()

\subsection*{9.6.2.4 log_softmax}
ann.components.actf.log_softmax ()

\subsection*{9.6.2.5 tanh}
ann. components.actf.tanh()

\subsection*{9.6.2.6 hardtanh}
ann. components.actf.hardtanh()

\subsection*{9.6.2.7 relu}
ann.components.actf.relu()

\subsection*{9.6.2.8 softplus}
ann.components.actf.softplus()

\subsection*{9.6.2.9 \(\sin\)}
ann. components.actf.sin()

\subsection*{9.6.3 Container components}

\subsection*{9.6.3.1 stack}
ann.components.stack()
```

> ann.components.reset_id_counters() -- reset ID name generator
> mlp = ann.components.stack()
> mlp:push( ann.components.hyperplane{ input=100, output=200 } )
> mlp:push( ann.components.actf.logistic() )
> mlp:push( ann.components.hyperplane{ input=200, output=40 } )
> mlp:push( ann.components.actf.log_softmax() )
> _,weights = mlp:build()
> for name,w in pairs(weights) do print(name) print(w) end
w0
Large matrix, not printed to display

# Matrix of size [200,100] [0x1863df0 data= 0x1668030]

w2
Large matrix, not printed to display

# Matrix of size [40,200] [0x186bfd0 data= 0x17c71b0]

b1
Large matrix, not printed to display

# Matrix of size [200,1] [0x186aee0 data= 0x18159f0]

b3
Large matrix, not printed to display

# Matrix of size [40,1] [0x186d6d0 data= 0x175c910]

```

\subsection*{9.6.3.2 join}
ann.components.join()

\subsection*{9.6.4 Filter components}

\subsection*{9.6.4.1 dropout}
ann. components.dropout()
```

> c = ann.components.dropout{ random=random(3284), prob=0.5, value=0.0 }

```

\subsection*{9.6.4.2 select}
ann.components.select()

\subsection*{9.6.4.3 slice}
```

ann.components.slice()

```

\subsection*{9.6.4.4 gaussian__noise}
ann.components.gaussian_noise\{ random, prob, var, mean \}

\subsection*{9.6.4.5 salt__and__pepper}
```

ann.components.salt_and_pepper{ random, prob, zero, one }

```

\subsection*{9.6.5 Convolutional components}

This components are used to build Convolutional Neural Networks. If you use dataset.matrix, your patterns will be flattened at converted into a one dimensional matrix. This forces to add a rewrap components at the beginning of your ANN. Follows an example of a FULL CNN for MNIST task (28x28 pixels, images of digits):
```

-- tables for the CNN configuration
ishape = {1, 28, 28} -- for input matrix rewrapping
conv1 = {1, 5, 5} nconv1=20
maxp1 = {1, 2, 2}
conv2 = {nconv1, 5, 5,} nconv2=50
maxp2 = {1, 2, 2}
hidden = 500
thenet = ann.components.stack():
push( ann.components.rewrap{ size=ishape } ):
push( ann.components.convolution{ kernel=conv1, n=nconv1 } ):
push( ann.components.convolution_bias{ n=nconv1, ndims=\#conv1 } ):
push( ann.components.actf.tanh() ):
push( ann.components.max_pooling{ kernel=maxp1,} ):
push( ann.components.convolution{ kernel=conv2, n=nconv2 } ):
push( ann.components.convolution_bias{ n=nconv2, ndims=\#conv2 } ):
push( ann.components.actf.tanh() ):
push( ann.components.max_pooling{ kernel=maxp2 } ):
push( ann.components.flatten() )
-- using the method precompute_output_size, it is possible to know
-- the size of the convolution after the flatten operation
local conv_size = thenet:precompute_output_size()[1]
thenet:
push( ann.components.hyperplane{ input=conv_size, output=hidden } ):
push( ann.components.actf.tanh() ):
push( ann.components.hyperplane{ input=hidden, output= 10 } ):
push( ann.components.actf.log_softmax() )

```

\subsection*{9.6.5.1 convolution}
ann.components.convolution\{ kernel, step, \(n\), name, weights, ... \}
A convolutional component could be created as:
```

> c = ann.components.convolution{ kernel={3, 5, 5}, step={1, 1, 1}, n=10,
name="conv-W1", weights="W1",
input_planes_dim=1 }

```

This component executes a convolution using the given kernel sizes, moving the convolution window following step table, and using n different kernels. This module has a dynamic input/output size, the convolution is performed over all the input following the indicated parameters.
- input_planes_dim is a number (optional, by default is 1 ) which indicates the dimension \(\mathbf{K}\) at input matrix where are located the input planes.
- kernel is a table which describes the size of each kernel. The \(\mathbf{K}\) element of this table is always the number of PLANES at the input matrix. Therefore, a kernel over a 1-dim signal will be like kernel=\{1, \(5\}\) being \(\mathbf{K}=\mathbf{1}\). For a 2 D image will be kernel=\{1, 5, 5\}, for a 2 D image with RGB color will be kernel \(=\{3,5,5\}\) if \(\mathbf{K}=\mathbf{1}\), otherwise it could be kernel=\{5, 3, 5\} if \(\mathbf{K}=\mathbf{2}\) or kernel=\{5, 5, 3\} if \(\mathbf{K}=\mathbf{3}\). For a RGB video sequence the kernel will be kernel=\{3,5,5,5\} for \(\mathbf{K}=\mathbf{1}\), and so on.
- step is a table which indicates how to move the kernel. The number of steps at each dimension will be (input_dim[i] - kernel[i])/step[i] + 1. The \(\mathbf{K}\) element of this table is forced to be 1, so that is the number of planes at input matrix. The step is optional, by default has all its elements assigned to 1.
- n is the number of kernels to be applied. It is the number of output planes produced by this component (number of neurons).
- name and weights are the strings with for search components and connection objects.

The output produced by this component will be of:
- output_size[1]=n
- output_size \([i+1]=(\) input__size[i] - kernel \([\mathrm{i}]) /\) step \([\mathrm{i}]+1\), FOR \(\mathrm{i}=1, \ldots\), , input_planes_dim- 1
- output__size[i]=(input_size[i] - kernel[i])/step[i] + 1, FOR i=input_planes_dim+1,..., \#kernel

By default, input_planes_dim=1, so the output size will be simplified as:
- output_size \([1]=\mathrm{n}\)
- output__size \([\mathrm{i}]=(\) input__size \([\mathrm{i}]-\operatorname{kernel}[\mathrm{i}]) /\) step \([\mathrm{i}]+1\), FOR \(\mathrm{i}=2, \ldots\), \(\#\) kernel

\subsection*{9.6.5.2 convolution__bias}
```

ann.components.convolution_bias{ n, ndims, name, weights }
> c = ann.components.convolution_bias{ n=10, ndims=3,
name="conv-B1", weights="B1" }

```
- n is the number of planes at the input (the first dimension size of the input matrix).
- ndims is the number of dimensions expected at the input matrix.
- name and weights as usual

\subsection*{9.6.5.3 max_pooling}
ann.components.max_pooling\{ kernel, name \}
> \(c=\) ann.components.max_pooling\{ kernel=\{1, 2, 2\}, name="pool-2" \}
- kernel is a table with the sizes of the kernel applied to the input matrix. Depending on this the behavior of the max-pooling could be to do a down-sampling of an input matrix (as in the example), or to convert the input in a fixed size feature vector (kernel \(=\{1,0,0\}\) ). The 0 value at one component means to fit this dimension with the same dimension of input matrix. So, the last example \{1, 0,0\(\}\) will be a max-pooling computed over all positions for each input plane, producing as output a feature vector of INPUT PLANES size.
- name as usual.

\subsection*{9.6.5.4 flatten}
```

ann.components.flatten{ [name] }

```

This components converts an input matrix formed by N patterns of any dimensionality to an output bidimensional matrix with N rows and M columns, where M is the product of all input matrix dimensions (except the first one which is the number of patterns).
```

> c = ann.components.flatten{ name="flatten" }

```

\subsection*{9.6.6 Other components}

\subsection*{9.6.6.1 copy}
ann.components.copy

\section*{Chapter 10}

\section*{ann.loss package}

Related with module require("aprilann.ann.loss").
This package defines the loss functions included in APRIL-ANN. All loss functions share the same interface. Normally, they are implemented in C++ and binded to Lua.

The interface of loss functions is the following:
- loss,loss_matrix = loss:compute_loss(input,target): this method computes the loss between two tokens, the input and the target. Normally they are bi-dimensional matrix instances with size NxM , where N is the number of patterns in the bunch (mini-batch), and M is the number of outputs in the ANN component. The method returns two values, the loss, which is a number with the mean loss in the given bunch of patterns. The loss_matrix, which is a one-dimensional matrix of size N containing the loss for every pattern. In some cases, as for example in FMeasure-based loss functions, this loss matrix is of size 1 , because the loss function is computed over the bunch of patterns, and is not separable.
- gradient = loss:gradient(input,target): this method computes the gradient of the loss between the two input and the target. It returns a bi-dimensional matrix with size NxM . Each component of this matrix is the partial derivative ANN outputs respect to the loss function.
- loss,loss_matrix = loss:accum_loss(loss,loss_matrix): this method receives the output of compute_loss method, and accumulates the given loss in its internal state. It is useful to compute the loss of a large number of patterns.
- loss_matrix = loss:accum_loss(loss_matrix): this method is a specialization of the previous one, but receiving only the loss_matrix.
- mean, variance = loss:get_accum_loss(): this method returns two numbers, the mean and the variance of the accumulated loss in the internal state of the loss function object.

Tt is possible to develop new loss functions by implementing Lua classes derived from ann.loss class, following this example:
```

> myloss,myloss_methods = class("myloss",ann.loss)
> function myloss:constructor()
-- Your code to initialize self reference
end
> function myloss_methods:compute_loss(input,target)
-- YOUR CODE

```
```

        return loss,loss_matrix
    end
    > function myloss_methods:gradient(input,target)
-- YOUR CODE
return gradient_token
end
> function myloss_methods:accum_loss(loss,loss_matrix)
local loss_matrix = loss_matrix or loss
-- YOUR CODE
return loss or loss_matrix, loss_matrix
end
> function myloss_methods:get_accum_loss()
-- YOUR CODE
return loss_mean,loss_variance
end
> function myloss_methods:reset()
-- YOUR CODE
end
> function myloss_methods:clone()
-- YOUR CODE
return cloned_obj
end

```

\subsection*{10.1 Mean squared error (MSE)}

This loss function is defined at the object ann.loss.mse:
> loss \(=\) ann.loss.mse()

The constructor could receive an optional parameter with the expected number of outputs at the ANN component. If given, it will be used as sanity check forcing to be equal to the given input/target sizes. If not given, the size check will be ignored.

This loss function computes the mean squared error between the given input/target patterns. It computes the following expression:
\[
J=\frac{1}{2 N} \sum_{i, j}\left(h_{i}^{j}-t_{i}^{j}\right)^{2}
\]

Figure 10.1: MSE

Where \(N\) is the number of patterns, \(h_{-}{ }^{\wedge}{ }^{\wedge} j\) is the position ( \(i, j\) ) in the input matrix (pattern \(i\), component \(j\) ), and \(t_{\_} \mathrm{i}^{\wedge} \mathrm{j}\) is the same position at the target matrix.

\subsection*{10.2 Mean absolute error (MAE)}

This loss function is defined at the object ann.loss.mae:
```

> loss = ann.loss.mae()

```

The constructor could receive an optional parameter with the expected number of outputs at the ANN component. If given, it will be used as sanity check forcing to be equal to the given input/target sizes. If not given, the size check will be ignored.

This loss function computes the mean absolute error between the given input/target patterns. It computes the following expression:
\[
J=\frac{1}{N M} \sum_{i, j}\left|h_{i}^{j}-t_{i}^{j}\right|
\]

Figure 10.2: MAE

Where \(N\) is the number of patterns, \(M\) is the number of outputs, \(h_{-} i^{\wedge} j\) is the position ( \(i, j\) ) in the input matrix (pattern \(i\), component \(j\) ), and \(t_{-} i^{\wedge} j\) is the same position at the target matrix.

\subsection*{10.3 Cross entropy}

This loss function is defined at the object ann.loss.cross_entropy:
> loss \(=\) ann.loss.cross_entropy()

The constructor could receive an optional parameter with the expected number of outputs at the ANN component. If given, it will be used as sanity check forcing to be equal to the given input/target sizes. If not given, the size check will be ignored.

This object is implemented to work only with log_logistic activation function. This loss function computes the cross entropy between the given input/target patterns, interpreting the ANN component output as a binomial distribution. It computes the following expression:
\[
J=\frac{1}{N} \sum_{i, j}-\left[t_{i j} \log h_{i}^{j}+\left(1-t_{i j}\right) \log \left(1-h_{i}^{j}\right)\right]
\]

Figure 10.3: CE

Where \(N\) is the number of patterns, \(h_{-} i^{\wedge} j\) is the position ( \(i, j\) ) in the input matrix (pattern \(i\), component \(j\), in natural scale), and \(t_{\_} \mathrm{i}^{\wedge} j\) is the same position at the target matrix.

\subsection*{10.4 Multi-class cross entropy}

This loss function is defined at the object ann.loss.multi_class_cross_entropy:
```

> loss = ann.loss.multi_class_cross_entropy()

```

The constructor could receive an optional parameter with the expected number of outputs at the ANN component. If given, it will be used as sanity check forcing to be equal to the given input/target sizes. If not given, the size check will be ignored.
\[
J=\frac{1}{N} \sum_{i, j}-t_{i j} \log h_{i}^{j}
\]

Figure 10.4: CE

This object is implemented to work only with log_softmax activation function. This loss function computes the cross entropy between the given input/target patterns, interpreting the ANN component output as a multinomial distribution. It computes the following expression:

Where \(N\) is the number of patterns, \(h_{-} i^{\wedge} j\) is the position ( \(i, j\) ) in the input matrix (pattern \(i\), component \(j\), in natural scale), and \(t \_i^{\wedge} j\) is the same position at the target matrix.

\subsection*{10.5 Macro averaging multi-class F-Measure}

This loss function is defined at the object ann.loss.batch_fmeasure_macro_avg:
```

> loss = ann.loss.batch_fmeasure_macro_avg{ beta=0.5 }

```

The constructor could receive an optional table parameter with the following fields:
- size=0: expected number of outputs at the ANN component. If given, it will be used as sanity check forcing to be equal to the given input/target sizes. If not given, the size check will be ignored.
- beta=1: the b parameter in the F-Measure expression below. By default it is set to 1 .
- complement=false: a boolean indicating if the input/target values must be computed complemented (1-value), swapping positive and negative classes.

This object is implemented to work with logistic or softmax activation function. This loss function computes the F-Measure between the given input/target patterns, interpreting the ANN component output as a multinomial distribution. It computes the following expression:
\[
J=\frac{1}{M} \sum_{j} \frac{\left(1+b^{2}\right) h_{j} \cdot t_{j}}{\left(\sum o_{j}\right)+b^{2}\left(\sum t_{j}\right)}
\]

Figure 10.5: FM
Where M is the number of outputs, b is the beta parameter of the F -mesaure, \(\mathrm{h}_{-} \mathrm{j} \cdot \mathrm{t}_{-} \mathrm{j}\) is the dot product between column vectors with input/target values of class \(j\), and \(\operatorname{sum}\left(o_{-} j\right)\) and sum( \(\left.t_{-} j\right)\) is the sum of all the elements in the column vectors.

\subsection*{10.6 Micro averaging multi-class F-Measure}

This loss function is defined at the object ann.loss.batch_fmeasure_micro_avg:
```

> loss = ann.loss.batch_fmeasure_micro_avg{ beta=0.5 }

```

The constructor could receive an optional table parameter with the following fields:
- size=0: expected number of outputs at the ANN component. If given, it will be used as sanity check forcing to be equal to the given input/target sizes. If not given, the size check will be ignored.
- beta=1: the b parameter in the F-Measure expression below. By default it is set to 1 .
- complement=false: a boolean indicating if the input/target values must be computed complemented (1-value), swapping positive and negative classes.

This object is implemented to work with logistic activation function. This loss function computes the F-Measure between the given input/target patterns, interpreting the ANN component output as a binomial distribution. If it is used with softmax (multinomial distribution), then this function computes accuracy. It follows this expression:
\[
J=\frac{\left(1+b^{2}\right) h \cdot t}{\left(\sum o\right)+b^{2}\left(\sum t\right)}
\]

Figure 10.6: FM
Where \(b\) is the beta parameter of the F-mesaure, \(\operatorname{dot}(h, t)\) is the dot product between the input/target matrices re-interpreted as two column vectors, and sum(o) and sum(t) is the sum of all the elements in the matrices.

\subsection*{10.7 Zero-one loss function}

This loss function is defined at the object ann.loss.zero_one:
```

> loss = ann.loss.zero_one([nil, [, 0.5 ] ])

```

The constructor could receive an optional first parameter with the expected number of outputs at the ANN component. If given, it will be used as sanity check forcing to be equal to the given input/target sizes. If not given, the size check will be ignored.

It could receive an optional second parameter which by default is 0.5 . This second parameter is the threshold which defines when the output is taken as 1. NOTE that if you are using log_logistic outputs, this threshold must be set to math. \(\log (0.5)\). This parameter is only useful when the model has one output, that is, for two-class problems.
This object is not derivable, so the compute_gradient method is forbidden. The loss function could be use to compute validation error, but not for training. It computes the accuracy of the model classifying to the class with maximum probability.

\section*{Chapter 11}

\section*{ann.optimizer package}

\subsection*{11.1 Introduction}

Related with the module require("aprilann.ann.optimizer").
The optimizer is an object which implements the learning algorithm. Every class in ann.optimizer is an optimizer. Several learning hyperparameters are available, depending in the selected optimizer. This learning hyperparameters are known as options, and could be set globally (to all the connection weight layers of the ANN), or layerwise (to a concrete connection weights object, identified by its name). Optimizers implement the following API.

\subsection*{11.1.1 Interface of ann.optimizer classes}

\subsection*{11.1.1.1 clone}
other = opt:clone()
Returns a deep copy of the caller object.
11.1.1.2 get_option
value = opt:get_option(option)
Return the global value of a given learning option name.

\subsection*{11.1.1.3 set__option}
opt:set_option(option, value)
Sets the global value of a given learning option name.
```

11.1.1.4 set_layerwise__option
opt:set_layerwise_option(layer, option, value)

```

Sets a layerwise option for the given layer name.
```

11.1.1.5 get_layerwise_ooption
value = opt:get_layerwise_option(layer, option)

```

Returns the layerwise option of the given layer name.
```

11.1.1.6 get_option_of
value = opt:get_option_of(layer, option)

```

Returns the option which is applicable to the given layer name. If a layerwise option was previously defined, the method returns its value. Otherwise, the value of the global option will be returned.

\subsection*{11.1.1.7 execute}
loss,gradients,.. = opt:execute(eval, cnn)
This is the core function of optimizer objects. It receives two parameters, and return the same values as returned by eval function. The parameters are:
- eval is a Lua function which returns at least the first two parameters of the list below. The function receives two inputs:
1. A table of candidate weigths to compute the loss.
2. The iteration number of the algorithm.

This function could return more values, all of them will be returned by the call to execute:
1. The loss of a bunch of data (a mini-batch).
2. A gradients matrix dictionary (as returned by ANN components method
`compute_gradients()`). It must be a table of names=>"matrix`.
- cnn a dictionary of matrices with the connection weight objects, as the dictionary returned by ANN components method copy_weights(). It must be a table of names=>matrix. The execute method can modify the matrices contained at cnn, by following the given gradients, can use a bunch of weight candidates and call eval function to test the loss.

\subsection*{11.2 Coupling ANNs with optimizer}

\subsection*{11.2.1 Using a trainer object}

The trainable.supervised_trainer class is the default coupling between the optimizer, the ANN component and the loss function. The optimizer could be set at the constructor:
```

> trainer = trainable.supervised_trainer(ann_component, ann.loss.mse(),
bunch_size, ann.optimizer.sgd())

```

The hyperparemters of optimizer objects can be modified by the trainer object:
- trainer:set_option(option, value): sets a global learning option value.
- value=trainer:get_option(option): gets a global learning option value.
- trainer:set_layerwise_option(layer_match,option, value): sets a layerwise learning option value of all the connection weight objects whose name matches the given layer_match Lua pattern string.
- value=trainer:get_option_of(layer,option): gets the option value applicable to the given layer.
```

trainer = trainable.supervised_trainer(ann_component, ann.loss.mse(),
bunch_size, ann.optimizer.sgd())
trainer:build()
trainer:set_option("learning_rate", number)
trainer:set_option("momentum", number)
-- regularization is recommended to not be applied at bias connections
trainer:set_layerwise_option("w.*", "weight_decay", number)
trainer:set_layerwise_option("w.*", "max_norm_penalty", number)
trainer:set_layerwise_option("w.*", "L1_norm", number)

```

Doing this, when you call trainer:train_dataset (...) or trainer:validate_dataset (...), the object implements a default eval function for the optimizer.

\subsection*{11.2.2 From the scratch}

First, you need to construct the ANN component, the loss function and the optimizer instance, and the configuration of the optimizer.
```

local thenet = ann.mlp.all_all.generate("256 inputs 128 tanh 10 log_softmax")
local thenet,cnns = thenet:build()
local loss = ann.loss.multi_class_cross_entropy()
local opt = ann.optimizer.sgd()
opt:set_option("learning_rate", 0.01)

```

The initialization of the weights is required:
```

local rnd = random(1234)
for _,w in pairs(cnns) do w:uniformf(-0.1,0.1,rnd) end

```

The training is performed over random data, generated on-the-fly:
```

local M = matrix.col_major -- ANNs need col_major matrices
local weight_grads = {} -- upvalue for eval function
for i=1,1000 do
local input = M(1,256):uniformf(0,1,rnd)
local target = M(1,10):zeros():set(1, rnd:randInt(1,10), 1.0)
opt:execute(function(weights,it)
if cnns ~= weights then thenet:build(weights) cnns=weights end
thenet:reset(it)
local out = thenet:forward(input)
local tr_loss,tr_matrix = loss:compute_loss(out,target)
thenet:backprop(loss:gradient(out,target))
weight_grads:zeros()
weight_grads = thenet:compute_gradients(weight_grads)
return tr_loss,weight_grads
end,
cnns)
end

```

All this code could be modified in many ways, to customize or implement your own methods.
NOTE the full code of this example is available at: EXAMPLES/optimizer-from-scratch.lua

\subsection*{11.3 Stochastic Gradient Descent}

The ann.optimizer.sgd class trains the neural network following the Stochastic Grandient Descent algorithm. It incorporates regularization and momentum hyperparameters.
```

> opt = ann.optimizer.sgd()
> loss,gradients = opt:execute(function(weights,it)
-- HERE YOUR CODE
return loss,gradients
end,
-- The connections
cnns)

```

Its options are (default values are indicated with \(=\) symbol):
- learning_rate: the learning rate controls the portion of the gradient used to update the weights.
- decay=1e-05: controls the decay of learning rate.
- momentum=0: is a inertial hyperparameter which applies a portion of the weight update in the previous iteration.
- weight_decay=0: a L2 regularization term.
- L1_norm=0: a L1 regularization term, a naive implementation with ZERO truncation to avoid ZERO cross.
- max_norm_penalty=0: a constrain penalty based on the two-norm of the weights.

The algorithm uses the following learning rule:
```

w = w - lr'*( grad(L)/grad(w') + weight_decay*W' + L1_norm*sign(w') ) + momentum*(W' -
w")

```
where w , w ' and \(\mathrm{w} "\) are the weight values at next, current, and previous iterations; lr' is the learning_rate, and \(\operatorname{grad}(\mathrm{L}) / \operatorname{grad}(\mathrm{w})\) ) is the gradient of the loss function at the given weight. The L1 regularization is performed following truncate gradient algorithm. After this learning rule, the constraint max_norm_penalty is applied, forcing the 2 -norm of the input weights of every neuron to be less than the given parameter.
```

> opt = ann.optimizer.sgd() -- an instance

```

\subsection*{11.4 Averaged Stochastic Gradient Descent}

The ann.optimizer.asgd class trains the neural network following the Averaged Stochastic Grandient Descent algorithm, taken from Leon Bottou, Stochastic Gradient Descent Tricks, Microsoft Research, 2012. It incorporates regularization and learning rate decay hyperparameters.
```

> opt = ann.optimizer.asgd()
> loss,gradients = opt:execute(function(weights,it)
-- HERE YOUR CODE
return loss,gradients
end,
-- The connections
cnns)

```

Its options are (default values are indicated with \(=\) symbol):
- learning_rate: the learning rate controls the portion of the gradient used to update the weights.
- lr_decay=0.75: controls the learning rate decay. The effective learning rate is computed as \(\operatorname{lr} /(1+\) \(l r * t)^{\wedge} l r_{-} d e c a y\), being \(t\) the number of presentations, which has not to be confused with number of epochs. Number of presentations would be higher of number of epochs.
- \(\mathrm{t} 0=0\) : when to start averaging. Before t 0 , the algorithm will be \(S G D\). As before, t 0 is indicated in number of presentations, i.e. one epoch will be t0 = ceil( number_of_patterns / bunch_size ). It is recommended to set this option to at least one epoch.
- weight_decay=0: a L2 regularization term.
```

> opt = ann.optimizer.asgd() -- an instance

```

\subsection*{11.5 Resilient backpropagation (RProp)}

The ann.optimizer.rprop class trains the neural network following the RProp algorithm. It incorporates an option to set the number of iterations done with every mini-batch of patterns. This optimizer has a step size hyperparameter for each weight parameter in the model. All options are global, layer-wise options doesn't make sense here.
```

> opt = ann.optimizer.rprop()
> loss,gradients = opt:execute(function(weights,it)
-- HERE YOUR CODE
return loss,gradients
end,
-- The connections
cnns)

```

Its options are (default values are indicated with \(=\) symbol):
- initial_step=0.1: the initial step size of every weight.
- eta_plus=1.2: value which controls how much proportion is the step increased when the gradient sign is the same between two iterations.
- eta_minus=0.5: value which controls how much proportion is the step decreased when the gradient sign changes between two iterations.
- max_step=50: the maximum value for the weight step hyperparameter.
- min_step=1e-05: the minimum value for the weight step hyperparameter.
- niter=1: the number of iterations done with one mini-batch of patterns.

The algorithm modifies the step(i) parameter of a weight at iteration \(i\) :
```

    | step(i-1) * eta_minus, iff sign(grad(w')/grad(L)) <> sign(grad(w'')/grad(L))
    step(i) = | step(i-1) * eta_plus, iff sign(grad(w')/grad(L)) == sign(grad(w'')/grad(L))

```

It updates the weight following this equation:
```

w = w' - sign(grad(w')/grad(L)) * step(i)

```

In the above equations, \(w, w^{\prime}\) and \(w^{\prime \prime}\) are the weight values at next, current, and previous iterations and \(\operatorname{sign}(\operatorname{grad}(.) / \operatorname{grad}(\mathrm{L}))\) is the sign of the gradient of the loss function at the given weight. Note that the step is saturated with the values max_step and min_step.
```

> opt = ann.optimizer.rprop() -- an instance

```

\subsection*{11.6 Conjugate Gradient (CG)}

The ann.optimizer.cg class trains the neural network following the \(C G\) algorithm. It is a second order Hessian Free optimizer. Its convergence is usually faster than SGD algorithm.
```

> opt = ann.optimizer.cg()
> loss,gradients = opt:execute(function(weights,it)
-- HERE YOUR CODE
return loss,gradients
end,
-- The connections
cnns)

```

Its options are (default values are indicated with \(=\) symbol ):
- rho=0.01: Constant for Wolf-Powell conditions (global option).
- sig=0.5: Constant for Wolf-Powell conditions (global option).
- int=0.1: Reevaluation limit (global option).
- ext=3: Maximum number of extrapolations (global option).
- max_iter: Maximum number of iterations (global option).
- max_eval=1.25*max_iter: Maximum number of evaluations (global option).
- ratio=100: Maximum slope ratio (global option).
- weight_decay: Weights L2 regularization (global and layer-wise option).
- L1_norm: Weight L1 regularization (global and layer-wise option).
- max_norm_penalty: Weight max norm upper bound (global and layer-wise option).

This implementation is rewrite of Torch 7 optim package, which is a rewrite of minimize.m written by Carl E. Rasmussen.
```

> opt = ann.optimizer.cg() -- an instance

```

\subsection*{11.7 Quickprop}

The ann.optimizer.quickprop class trains the neural network following the Quickprop algorithm. It is a second order optimizer which uses a quadratic approximation to speed-up the learning convergence. It is usually faster than SGD, but can suffer of chaotic oscillations.
```

> opt = ann.optimizer.quickprop()
> loss,gradients = opt:execute(function(weights,it)
-- HERE YOUR CODE
return loss,gradients
end,
-- The connections
cnns)

```

Its options are (default values are indicated with \(=\) symbol ):
- learning_rate: It is mandatory to be given.
- mu=1.75: Maximum growth factor.
- epsilon=1e-04: Bootstrap factor.
- max_step=1000: Maximum step value.
- weight_decay: Weights L2 regularization.
- L1_norm: Weight L1 regularization.
- max_norm_penalty: Weight max norm upper bound.
```

> opt = ann.optimizer.quickprop() -- an instance

```

\subsection*{11.8 AdaDelta}

The ann.optimizer.adadelta class trains the neural network following the AdaDelta algorithm. It is a method which dynamically adapts the learning rate just using first order information. It as simple as SGD, and appears to be more robust.
```

> opt = ann.optimizer.adadelta()
> loss,gradients = opt:execute(function(weights,it)
-- HERE YOUR CODE
return loss,gradients
end,
-- The connections
cnns)

```

Its options are (default values are indicated with \(=\) symbol):
- decay=0.95: Decay of the accumulated gradient and updates.
- epsilon=1e-06: To avoid numerical issues.
- weight_decay=0.0: Weights L2 regularization.
- max_norm_penalty=0.0: Weight max norm upper bound.
```

> opt = ann.optimizer.adadelta() -- an instance

```

\section*{Chapter 12}

\section*{ann.graph package}

\subsection*{12.1 Introduction}

This package contains an implementation of ANNs by using a graph description. The graph allow to declare delayed connections, which can be used to develop recurrent neural networks as LSTMs or Elman.

\subsection*{12.2 Graph based ANNs}

Graph ANNs are declared as instances of the class ann.graph. The ANN graph is a model where nodes are ANN componentes (any object of ann. components and objects defined in ann.graph and ann.graph.blocks). So, nodes have an input and an output tokens, in the same way as ANN componentes receive a token and produce as output another token. Nodes can receive any number of connections as input and its output can be connected to other multiple nodes. When multiple input connections are received, they are put together into a tokens.vector. bunch instance. The graph implements properly the propagation of gradients between the nodes, and uses the methods forward, backprop and compute_gradients of the components in every node.

The graph object is considered itself as an ANN component, allowing to declare graphs where nodes are other graphs. Every graph has two special nodes, 'input' and 'output', which are used to connect the visible parts of the ANN.

In ANN graphs loops are allowed, but they cannot be made of normal connections, and the concept of delayed connections is introduced (indeed, normal connections are whose with delay=0). An ANN graph with delayed connections is equivalent to the concept of Recurrent Neural Network (RNN in the following).

The training of RNNs is done following the Back-Propagation Trough Time (BPTT) algorithm. RNNs have an special behavior in forward method, the graph takes note of the state (input, output, gradient deltas, ...) for every node, allowing to take as input the activation in any past instant. The backprop method returns a tokens.null instance, that is, its output is none, this method just annotates the given input error deltas for a future use. Calling the method compute_gradients the error deltas given at backprop are propagated through all the space and time, and the weight gradients are computed.

\subsection*{12.2.1 Constructor}
\(\mathrm{g}=\mathrm{ann} \cdot \operatorname{graph}([\) name ] )
The constructor an optional name argument.

\subsection*{12.2.2 connect}
g:connect ( source, dest1, ..., [ delay=0 ] )
This method connects a path of nodes in the graph. It receives as arguments:
- source: The first node in the path (source). It can be an ANN component or the string 'input'.
- dest1: The second node in the path (dest1). It can be an ANN component or the string 'output'.
- ...: A variadic list of arguments with zero or more nodes which form the path. Every node in this list can be an ANN component or output.
- delay=0: The last argument is optional and by default it is zero. This argument is needed to declare delayed connections. All the connections in the path would be declared with the delay given in this argument. Note that normally only the connection between two nodes need to be delayed, and for this purpose the method g:delayed(source, destination) has been declared.

For correction, a graph is valid only if the input node is a source and output node is a sink, and every node is reachable from the input.

The following example shows how to declare a Jordan network.
```

> g = ann.graph()
> bind = ann.graph.bind()
> out_actf = ann.components.logistic()
> g:connect('input', bind,
ann.components.hyperplane{ input=2, output=4 },
ann.components.actf.logistic(),
ann.components.hyperplane{ input=4, output=1 },
out_actf, 'output')
> g:delayed(out_actf, bind) -- recurrent connection
> g:build()

```

\subsection*{12.2.3 delayed}
```

g:delayed( source, destination )

```

This is equivalent to g : connect(source, destination, 1 ).

\subsection*{12.2.4 show__nodes}
```

g:show_nodes()

```

This method is used for debug purposes, and show all the nodes in the given graph. If the graph contains other graphs as nodes, their nodes would be shown recursively. The output indicates the level of recursion, the name of the component in the corresponding node, and the type of the object, as in the following example (extracted from a LSTM test):
```


# (level) name type

(0) a2 ann.components.actf.log_logistic
(0) parity::output
(0) LSTM
(1) LSTM::f::layer
(1) LSTM::input
(1) LSTM::o::actf

```
```

string

```
string
ann.graph +
ann.graph +
    ann.components.hyperplane
    ann.components.hyperplane
    string
    string
    ann.components.actf.logistic
```

    ann.components.actf.logistic
    ```
```

    (1) LSTM::i::peephole
    (1) LSTM::o::gate
    (1) LSTM::o::layer
    (1) LSTM::f::gate
    (1) LSTM: :actf
    (1) LSTM::memory
    (1) LSTM::o::peephole
    (1) LSTM::i::actf
    (1) LSTM::cell_input
    (1) LSTM::output
    (1) LSTM::i::gate
    (1) LSTM::f::actf
        (1) LSTM::i::layer
        (1) LSTM::f::peephole
    (0) }1
(0) parity::input
ann.graph.bind
ann.graph.cmul
ann.components.hyperplane
ann.graph.cmul
ann.components.actf.softsign
ann.graph.add
ann.graph.bind
ann.components.actf.logistic
ann.components.hyperplane
string
ann.graph.cmul
ann.components.actf.logistic
ann.components.hyperplane
ann.graph.bind
ann.components.hyperplane
string

```

\subsection*{12.2.5 dot_graph}
\(g:\) dot_graph(filename)
This method is for debug. It writes to the given filename a DOT graph which can be transformed in PDF using graphviz.

\subsection*{12.2.6 build}
```

g,weights,components = g:build( [ table ] )

```

See ANN package doc.

\subsection*{12.2.7 forward}
```

output = g:forward( input, [ during_training=false ] )

```

See ANN package doc.

\subsection*{12.2.8 backprop}
```

output = g:backprop( input )

```

See ANN package doc.
Note that this method changes its default behavior when the graph is a RNN. In this case, the output of this method is a tokens.null instance, so it can be ignored.

\subsection*{12.2.9 compute_gradients}
table = g:compute_gradients ( [table] )
See ANN package doc.

\subsection*{12.2.10 bptt_backprop}
table = g:bptt_backprop()
Forces the BPTT algorithm execution, and returns a table (Lua array) with the delta gradients at the ANN input for every time instant.

\subsection*{12.2.11 get__bptt__state}
table = g:get_bptt_state()
Returns a table with the state of the whole ANN for every time instant.
table = g:get_bptt_state (time)
Returns a table with the state of the whole ANN for the given time instant.

\subsection*{12.2.12 reset}
g:reset ( [ n ] )
See ANN package doc.
Additionally with the standard behavior, this method reinitializes the BPTT tables, and must be called before starting a new sequence.

\subsection*{12.2.13 get_is_recurrent}
boolean = g:get_is_recurrent()
Indicates if the caller graph is recurrent or not.

\subsection*{12.2.14 set_bptt_truncation}
g:set_bptt_truncation ( backstep )
Changes the BPTT algorithm behavior, truncating the gradient computation every backstep number of iterations. This value can be math.huge to indicate an infinite limit. Besides this value, another usual one is 1, which transforms allow to use the algorithm as a kind of on-line learning algorithm.

\subsection*{12.3 Graph junctions}

\subsection*{12.3.1 bind}
ann.graph.bind\{ [ name=string ], [ input=number ], [ output=number ], [ size=number ] \}

\subsection*{12.3.2 add}
ann.graph.add\{ [ name=string ], [ input=number ], [ output=number ] \}

\subsection*{12.3.3 cmul}
ann.graph.cmul\{ [ name=string ], [ input=number ], [ output=number ] \}

\subsection*{12.3.4 index}
ann.graph.index(n, \{ [ name=string ], [ input=number ], [ output=number ] \})

\subsection*{12.4 Graph blocks constructors}

\subsection*{12.4.1 Elman}
ann.graph.blocks.elman\{ [ name=string ], [ input=number ],
[ output=number ], [ actf=string ] \})

\subsection*{12.4.2 LSTM}
ann.graph.blocks.lstm\{ [ name=string ], [ input=number ], [ output=number ], [ actf=string ], [ peepholes=true ], [ input_gate=true ], [ forget_gate=true], [ output_gate=true ] \})

\section*{Chapter 13}

\section*{ann.autoencoders package}

\subsection*{13.1 Introduction}

Package autoencoders could be loaded via the standalone binary, or in Lua with require("aprilann.autoencoders).
Stacked Denoising Auto-Encoders (SDAE) are a kind of deep neural network which is pre-trained following greedy layerwise algorithm but introducing at noise input of each layerwise auto-encoder. Some function facilities are implemented to help with the training of SDAE.

\subsection*{13.2 Greedy layerwise pre-training of SDAE}

Greedy layerwise pre-training consists in train each pair of layers, from input to output, in a greedy way (see Paper SDAE, 2010, Vincent Pascal et al.). Pre-training receives as input a table with parameters of training algorithm. For example, a table like this:
```

layers = {
{ size= 256, actf="logistic"}, -- INPUT
{ size= 256, actf="logistic"}, -- FIRST HIDDEN LAYER
{ size= 128, actf="logistic"}, -- SECOND HIDDEN LAYER
{ size= 32, actf="logistic"}, -- THIRD HIDDEN LAYER
}
perturbation_random = random(824283)
params_pretrain = {
input_dataset = train_input, -- a dataset which is the input of the autoencoders
replacement = nil, -- a number (or nil) indicating replacement
on_the_fly = false, -- a boolean (or nil) for on-the-fly
shuffle_random = random(1234), -- for shuffle durint backpropagation
weights_random = random(7890), -- for weights random initialization
layers = layers, -- layers description
supervised_layer = { size = 10, actf = "log_softmax" }, -- it is possible to pre-train supervise
output_datasets = { train_output }, -- the output dataset
bunch_size = bunch_size, -- the size of the mini-batch
optimizer = function() return ann.optimizer.sgd() end, -- optimizer function
training_options = { -- this table contains learning options and dataset noise filters
-- global options
global = {
-- pure ANN learning hyperparameters

```
```

        ann_options = { learning_rate = 0.01,
                        momentum = 0.02,
                        weight_decay = 1e-05 },
            -- noise filters (a pipeline of filters applied to input in order). Each one must be a dataset
            noise_pipeline = { function(ds) return dataset.perturbation{ -- gaussian noise
                        dataset = ds,
                                mean = 0, -- gaussian mean
                        variance = 0.01, -- gaussian variance
                            random = perturbation_random } end,
                        function(ds) return dataset.salt_noise{ -- salt noise (or mask noise)
                        dataset = ds,
                        vd = 0.10, -- percentage of values masked
                        zero = 0.0, -- mask value
                                random = perturbation_random } end },
            min_epochs = 4,
            max_epochs = 200,
            pretraining_percentage_stopping_criterion = 0.01,
        },
        -- it is possible to overwrite global values with layerwise dependent values (also noise_pipeline)
        layerwise = { { min_epochs=50 }, -- first autoencoder pretraining
        { min_epochs=20 }, -- second autoencoder pretraining
        { ann_options = { learning_rate = 0.04,
                                momentum = 0.02,
                                weight_decay = 4e-05 },
            min_epochs=20 }, -- third autoencoder pretraining
        { min_epochs=10 }, }, -- supervised pretraining
    }
    }

```

Fields supervised_layer and output_datasets are optional. If they are given, the last layer will be pre-trained in a supervised manner. Anyway, rest of layers are pre-trained in a unsupervised manner.

If field input_dataset is supplied, then distribution field is forbidden and, in case of pre-train supervised layer, output_datasets table must contain only one element.

If field distribution is supplied, then input_dataset is forbidden and, in case of pre-train supervised layer, output_datasets table has the same number of items than distribution table. In this last case, each item output_datasets[i] is the corresponding supervised output dataset for each item of distribution[i].input_dataset.

Ths table is used passed as argument to the algorithm:
```

sdae_table,deep_net = ann.autoencoders.greedy_layerwise_pretraining(params_pretrain)

```

This function returns one or two tables:
- sdae_table \(=\{\) bias=\{ ... \}, weights=\{ ... \} \}: which contains bias and weights of each unsupervised pre-trained layer.
- deep_net: An ANN component. It could be used to fine-tuning training. If you don't pre-train supervised layer, this component needs that you manually push the supervised layer.

\subsection*{13.2.1 Building codifier from SDAE table}
```

codifier_net = ann.autoencoders.build_codifier_from_sdae_table(sdae_table,
bunch_size,
layers)

```

The codifier is the SDAE without the supervised layer at output. Needs the same layers definition as greedy pre-trainig function. Returns an ANN object which could receive a pattern as input and produces its encoding.

\subsection*{13.2.2 Fine-tunning supervised deep ANN}

The supervised deep ANN could be fine-tuned using cross-validation training algorithm. If you pre-trained supervised layer, object deep_net is directly the whole ANN. Otherwise, you will need to add a new layer to the codifier_net, as in this example:
```

-- if you want, you could clone the deep_net to keep it as it is
local codifier_net = deep_net:clone()
codifier_net:build{ weights = deep_net:copy_weights() }
-- We add an output layer with 10 neurons and softmax activation function
local last_layer = ann.components.hyperplane{
dot_product_weights="lastw",
bias_weights="lastb",
output=10
}
deep_net:push( last_layer )
deep_net:push( ann.components.actf.log_softmax()
trainer = trainable.supervised_trainer(deep_net, loss_function or nil, bunch_size or nil)
-- The output size needs to be overwitten, so it needs to be given at build method
trainer:build{ output = 10 }
weights_random = random(SEED)
-- Now, EXITS TWO WAYS to randomize the weights of last_layer
-- FIRST using the trainer
trainer:randomize_weights{
name_match="~last[bw]\$", -- the name_match is to only randomize connections which name matches
inf=-0.1,
sup=0.1,
random=weights_random
}
-- SECOND using the component
-- (BE CAREFUL AND USE ONLY ONE OF THIS WAYS)
for _,cnn in pairs(last_layer:copy_weights()) do
cnn:randomize_weights{
inf=-0.1,
sup=0.1,
random=weights_random
end

```

\subsection*{13.2.3 Compute encoding}

With a trained SDAE (without supervised layer), it is possible to compute encodings of input patterns using this function:
```

trainer = trainable.supervised_trainer(codifier_net)
encoded_dataset = trainer:use_dataset(input_dataset)

```

\section*{Chapter 14}

\section*{trainable package}

\subsection*{14.1 Introduction}

Related with the module require("aprilann.trainable")
This package implements the class trainable.supervised_trainer, which is a powerful tool when you want to train ANNs following standard algorithms. Additionally it implements generic functions and iterators to implement training loops (dataset iterator, and training function).

If you want to do some specific tricks, it is possible to modify in your script the methods described here, or to re-implement the functionality that you need.

\subsection*{14.2 The supervised trainer class}

The class trainable.supervised_trainer is the most important piece in this package. This class knows the standard API of ANN components, loss functions, optimizers, datasets, and matrix objects, so, this class use them in the correct way to train ANNs following standard algorithms.

\subsection*{14.2.1 Constructor}

The construction of a trainer needs at least an ANN component object, but optionally, it is possible to indicate loss function, bunch size (mini-batch) and optimizer object:
```

> -- a linear component (w1 and b1 are the weight names)
> c = ann.components.hyperplane{ input=10, output=10,
name = "hyperplane",
dot_product_name = "c-w1",
bias_name = "c-b1",
bias_weights = "b1",
dot_product_weights = "w1" }
> -- a trainer
> trainer = trainable.supervised_trainer(c)

```

The arguments of the constructor are positional, described here:
- ANN component: an instance of ann.components.base() or any sub-class of it. The trainer uses a reference to the given object. It is a mandatory argument.
- Loss function: an instance of a sub-class of ann.loss. The trainer uses a reference to the given object. If not given, it will be mandatory in train_* and validate_* methods. By default is nil.
- Bunch-size (mini-batch): a number with the batch size used to compute gradients. Values between 32 and 1024 are usual, depending on the optimizer and in the task. If not given, it will be mandatory in train_*, validate_*, or use_* methods. By default is nil.
- Optimizer: an instance of a sub-class of ann.optimizer. The trainer uses a reference to the given object. If not given, the default optimizer is ann.optimizer.sgd().
- Smooth flag: a boolean value indicating if the gradients must be smoothed. In case of true, gradients will be multiplied by 1 /sqrt (bunch_size+K), being \(K\) the number of times the corresponding weights matrix is shared across the ANN. By default this parameter is true.
```

> -- without bunch-size, without loss function,
> -- using default optimizer, smooth is true
> trainer = trainable.supervised_trainer(c)
> -- without bunch-size, using default optimizer, smooth is true
> trainer = trainable.supervised_trainer(c, ann.loss.mse())
> -- using default optimizer, smooth is true
> trainer = trainable.supervised_trainer(c, ann.loss.mse(), 64)
> -- smooth is true
> trainer = trainable.supervised_trainer(c, ann.loss.mse(), 64,
ann.optimizer.rprop())
> -- all arguments given
> trainer = trainable.supervised_trainer(c, ann.loss.mse(), 64,
ann.optimizer.rprop(), false)

```

\subsection*{14.2.2 Get and set of loss function and optimizer}

\subsection*{14.2.2.1 set loss function}
trainer:set_loss_function(loss)

\subsection*{14.2.2.2 get_loss_function}
loss \(=\) trainer:get_loss_function()

\subsection*{14.2.2.3 set_optimizer}
trainer:set_optimizer(optimizer)

\subsection*{14.2.2.4 get_optimizer}
```

optimizer = trainer:get_optimizer()

```

\subsection*{14.2.3 Building the ANN}

Once the trainer is instantiated, it is mandatory to build the ANN by calling the named method.
```

> trainer:build()

```

The build method could be called without arguments, or giving a table with the following optional fields:
- input: a number with the input size of the model. If not given, it will be set to the input of the given ANN component. If given, this size will be used as sanity check, so, it must be equal to the input size of the ANN component.
- output: a number with the output size of the model. Idem as previous field, but with ANN component output.
- weights: a dictionary (table) with strings as keys and instances of matrix as values. If given, the connection objects used by the components will be taken from this dictionary, so, the sizes must be equals. It could be used to initialize certain components with a given initial parameters.
```

> trainer:build{
input = 10, output = 10,
weights = {
-- ann.connections allocates memory for weight matrices
w1 = ann.connections{ input=10, output=10 },
b1 = ann.connections{ input=1, output=10 },
}
}
> -- giving a table, initialized using its constructor
> trainer:build{
input = 10, output = 10,
weights = {
w1 = ann.connections{ input=10, output=10 },
b1 = ann.connections{ input=1, output=10 },
}
}

```

Once the build method is called, it is recommended to not modify the structure of the ANN component, if you need so, after your modifications the build method must be called again. The connection weights must be modified after calling build, initializing them in some way. Another possibility is to deserialize a previously serialized trainer.

\subsection*{14.2.4 Serialization/deserialization}

It is possible to save a trainer object, always in built state, using util.serialize() and util.deserialize() functions.
```

> util.serialize(trainer, "mytrainer-binary.net")
> trainer2 = util.deserialize("mytrainer-binary.net")

```

\subsection*{14.2.5 Connection weight methods}

\subsection*{14.2.5.1 randomize__weights}
trainer:randomize_weights\{ ... \}
The connection weights could be initialized randomly by using the method trainer:randomize_weights. This method receives a table with the following fields:
- inf: a number with the inferior range bound. It is a mandatory field.
- sup: a number with the superior range bound. It is a mandatory field.
- random: a random object. It is a mandatory field.
- use_fanin: a boolean value indicating if apply a factor fan-in of each layer for its initialization. It is an optional field. By default is false.
- use_fanout: a boolean value indicating if apply a factor fan-out of each layer for its initialization. It is an optional field. By default is false
- name_match: a string with a Lua pattern used to filter which connection objects will be initialized. It is an optional field, by default is .*.

The weights will be initilized in the range [ \(c * \inf , \mathrm{c} * \mathrm{sup}\) ] where c is a factor which depends on use_fanin and use_fanout arguments:
- If none given, then \(\mathrm{c}=1\) for all weight layers.
- If given only use_fanin=true, then c is computed depending in the fan-in of each layer, being \(\mathrm{c}=\) 1/sqrt (fanin).
- If given only use_fanout=true, then c is computed depending in the fan-out of each layer, being \(\mathrm{c}=\) 1/sqrt(fanout).
- If both given, use_fanin=true and use_fanout=true, then \(c\) is computed depending in the fan-in and fan-out of each layer, being \(c=1 /\) sqrt (fanin + fanout).
```

> -- initilize only bias weights
> trainer:randomize_weights{
inf = -0.1,
sup = 0.1,
random = random(213924),
name_match = "b.*",
}
> -- initilize only non-bias weights
> trainer:randomize_weights{
inf = -0.1,
sup = 0.1,
random = random(213924),
name_match = "w.*",
use_fanin = true,
use_fanout = true,
}
> -- initilize all the weights
> trainer:randomize_weights{
inf = -0.1,
sup = 0.1,
random = random(213924),
}

```

Once the trainer is built, it is possible to do some introspection in order to modify or execute methods of connection weights.
```

14.2.5.2 count__weights
number = trainer:count_weights( [pattern=.*] )

```

This method returns the number of connection weights in the current trainer. Optionally the method receives a Lua pattern filtering the counting process to only the weights whom name matches the pattern.
```

> = trainer:count_weights()
2

```

\subsection*{14.2.5.3 weights}
```

number = trainer:weights(name)

```

This method returns the matrix object with the given name.
```

> w1 = trainer:weights("w1")
> = type(w1)
matrix
> b1 = trainer:weights("b1")
> = type(b1)
matrix

```

\subsection*{14.2.5.4 get_components_of}
table = trainer:get_components_of (weights_name)

This method returns a table with ann. components objects which share the given weights_name connection weights. It returns a table because a connection weights object could be shared by more than one ANN components.
```

> iterator(ipairs( trainer:get_components_of("w1") )):apply(print)
1 instance 0xfcf5b0 of ann.components.base
> iterator(ipairs( trainer:get_components_of("b1") )):apply(print)
1 instance 0xff3c90 of ann.components.base

```

\subsection*{14.2.5.5 get__weights__table}
```

table = trainer:get_weights_table()

```

This method returns a dictionary (table) with all the connection weights. This dictionary has the same structure as the weights field of trainer:build(...) method.
```

> weights_table = trainer:get_weights_table()
> print(weights_table)
table: 0x1310a00

```
14.2.5.6.. = trainer:iterate_weights( [pattern=.*] )

This method returns a Lua iterator function which iterates over all the connection weights which name matches the given pattern.
```

> for cnn_name,cnn in trainer:iterate_weights() do print(cnn_name) end
b1
w1
> iterator( trainer:iterate_weights("w.*") ):select(1):apply(print)
w1

```

\subsection*{14.2.5.7 norm2}
```

number = trainer:norm2([pattern=.*])

```

This method computes the 2-norm of the connection weight objects whom name matches the given pattern.
```

> = trainer:norm2()
0.24416591227055
> = trainer:norm2("b.")
0
> = trainer:norm2("w.")
0.24416591227055

```

\subsection*{14.2.5.8 size}
```

number = trainer:size()

```

This methods returns the number of parameters (weights) in the current ANN component.
```

> = trainer:size()

```
110

\subsection*{14.2.5.9 Example}

By using these methods it is possible to manipulate by-hand the connection weights, as in the following example, which initializes to zero the bias connections:
```

> for _,cnn in trainer:iterate_weights("b.*") do cnn:zeros() end

```

REMEMBER that connection weight objects are matrix instances.
The following code shows at screen all the weight matrices:
```

> iterator(trainer:iterate_weights()):apply(print)
0
0
0
0
0
0
0
0
0
O

# Matrix of size [10,1] [0x10aca60 data= 0x10acb20]

    0.0575503 0.0516265 -0.0306808 0.035404 0.0118243 \ldots.
    ```
\begin{tabular}{cccccl}
0.0281929 & 0.0877731 & 0.0842627 & -0.0379949 & \multicolumn{1}{l}{-0.091877} & \(\ldots\) \\
-0.0332023 & 0.0576623 & -0.0335078 & 0.0251189 & -0.0578111 & \(\ldots\) \\
-0.0335119 & 0.0162495 & -0.00910386 & -0.0949801 & 0.00303258 & \(\ldots\) \\
-0.0361652 & -0.0389352 & 0.0628194 & -0.0622919 & -0.0206459 & \(\ldots\) \\
0.0583717 & 0.0910834 & -0.0889903 & -0.0142328 & -0.0750175 & \(\ldots\) \\
-0.0895628 & 0.0412171 & 0.0308301 & -0.0680314 & 0.0948681 & \(\ldots\) \\
-0.00439932 & 0.0975324 & 0.00736945 & 0.013484 & -0.079681 & \(\ldots\) \\
-0.0859327 & 0.0332012 & 0.0374489 & -0.0555631 & -0.0308727 & \(\ldots\) \\
0.0375495 & -0.0474079 & 0.0450424 & -0.0822513 & -0.00803252 & \(\ldots\) \\
\# Matrix of size \([10,10]\) & {\([0 x 10 f e 150\)} & data= 0x10fe210] &
\end{tabular}

\subsection*{14.2.6 Component methods}

Once the trainer is built, it is also possible to do introspection for getting or modify ANN components.

\subsection*{14.2.6.1 count_components}
```

number = trainer:count_components( [pattern=.*] )

```

This method returns the number of ANN components in the current trainer. Optionally the method receives a Lua pattern filtering the counting process to only the components whom name matches the pattern.
```

> = trainer:count_components()
3

```

\subsection*{14.2.6.2 get_components_of}
```

object = trainer:get_component()

```

This method returns the root ANN component, which was given to the constructor.
```

> = trainer:get_component()
instance 0x1175430 of ann.components.hyperplane

```

\subsection*{14.2.6.3 component}
```

number = trainer:component(name)

```

This method returns an ANN component object given its name.
```

> = trainer:component("hyperplane")
instance 0x1175430 of ann.components.base

```
```

14.2.6.4 get_weights_of
object = trainer:get_weights_of(component_name)

```

This method returns the matrix object which belongs to the given component_name.
```

> = trainer:get_weights_of("hyperplane")
nil
> = type( trainer:get_weights_of("c-w1") )
matrix
> = type( trainer:get_weights_of("c-b1") )
matrix

```

\subsection*{14.2.6.5 iterate_components}
```

... = trainer:iterate_components( [pattern=.*] )

```

This method returns a Lua iterator function which iterates over all the ANN components which name matches the given pattern.
```

> for name,c in trainer:iterate_components() do print(name,c) end
hyperplane instance 0x1175430 of ann.components.base
c-w1 instance 0xfcf5b0 of ann.components.base
c-b1 instance 0xff3c90 of ann.components.base
> iterator( trainer:iterate_components("c-w.*") ):apply(print)
c-w1 instance 0xfcf5b0 of ann.components.base

```

\subsection*{14.2.7 Optimizer methods}

The following methods are shortcuts to modify hyperparameters of the optimizer object.

\subsection*{14.2.7.1 has_option}
```

desc = trainer:has_option(option)

```

Returns the description of the given option if it exists at the optimizer. Otherwise it returns nil.

\subsection*{14.2.7.2 set_option}
trainer:set_option(option, value)
Sets the given option name to the given value. Throws an error in case the option doesn't exists at the optimizer.

\subsection*{14.2.7.3 get_option}
value = trainer:get_option(option)
Returns the value of a given option name, or throws an error if the option doesn't exits at the optimizer.

\subsection*{14.2.7.4 set_layerwise_option}
```

trainer:set_layerwise_option(pattern, option, value)

```

This method needs that the trainer was in built state. It traverses all the connection weight objects which name matches the given pattern string, and sets its layer-wise option name to the given value.
```

14.2.7.5 get_option_of
value = trainer:get_option_of(name, option)

```

This method returns the option value which applies to the given connection weight object name.

\subsection*{14.2.8 One batch training, validation and gradients check}

The following methods are prepared to work with a bunch of patterns (mini-batch). They do one batch step of the algorithms, and could be rewritten to do specific things.

\subsection*{14.2.8.1 train__step}
mu, matrix \(=\) trainer:train_step(input, target, loss, optimizer)
This method executes one training step, using the given data:
- input is a token with a bunch (mini-batch) of data, usually it is a matrix instance, where rows are patterns and columns features.
- target is a token with a bunch (mini-batch) of data. Usually it is a matrix instance.
- loss is a ann.loss function object. It is optional, if not given it uses the loss function object instantiated at the trainer object.
- optimizer is an ann.optimizer object. It is optional, if not given it uses the optimizer object instantiated at the trainer object.

The method returns two values:
- mu is the mean of the loss function at the given batch of patterns.
- matrix is a one-dimensional matrix with the loss of every pattern.
```

> mean,loss_matrix = trainer:train_step(input, target)

```

\subsection*{14.2.8.2 validate_step}
mu, matrix = trainer:validate_step(input, target, loss)
This method executes one validate step, using the given data:
- input is a token with a bunch (mini-batch) of data. It can be a matrix instance.
- target is a token with a bunch (mini-batch) of data. It can be a matrix instance.
- loss is a ann.loss function object. It is optional, if not given it uses the loss function object instantiated at the trainer object.

The method returns two values:
- mu is the mean of the loss function at the given batch of patterns.
- matrix is a one-dimensional matrix with the loss of every pattern.

The validate step evaluates the performance of the ANN component using the given loss function, but it doesn't train the parameters.
```

> mean,loss_matrix = trainer:validate_step(input, target)

```

\subsection*{14.2.8.3 compute_gradients_step}
```

g, mu, mat = trainer:compute_gradients_step(i, t, l [, g ])

```

This method compute the gradients of the given data, but doesn't train the parameters. The given gradients could be used to perform a manual training or gradient checking.

The arguments are:
- input is a token with a bunch (mini-batch) of data. It is usually a matrix instance.
- target is a token with a bunch (mini-batch) of data. It is usually a matrix instance.
- loss is a ann.loss function object. It is optional, if not given it uses the loss function object instantiated at the trainer object.
- gradients is a dictionary with the gradient matrices of every connection weights object. It is optional, if not given, the matrices will be allocated, if given, the allocation could be avoided.

The method returns three values:
- gradients the gradients dictionary.
- mu is the mean of the loss function at the given batch of patterns.
- matrix is a one-dimensional matrix with the loss of every pattern.
```

> gradients,mean,loss_mat = trainer:compute_gradients_step(input, target)

```

\subsection*{14.2.8.4 grad__check_step}
boolean = trainer:grad_check_step(i, t [, boolean [, loss ] ] )
This method compute the gradients of the given data, and executes a gradient checking algorithm using numerical differentiation. The arguments are:
- input is a token with a bunch (mini-batch) of data. It is usually a matrix instance.
- target is a token with a bunch (mini-batch) of data. It is usually a matrix instance.
- boolean, if true, it indicates high verbosity. It is optional, by default is false.
- loss is a ann.loss function object. It is optional, if not given it uses the loss function object instantiated at the trainer object.

The method returns a boolean indicating if the gradient checking algorithm success or fails.
```

> trainer:grad_check_step(input, target) or error("Gradients checking fails")

```

\subsection*{14.2.9 Dataset methods training, validation and gradients check}

This methods perform a traversal over a dataset with a large number of patterns, training or evaluating the model. The dataset is divided into batches of bunch_size size.

\subsection*{14.2.9.1 train_dataset}
loss_mu,loss_var = trainer:train_dataset\{ ... \}
This method is used to train by using a given dataset. Different training schedules are possible, depending on the parameters given to the method. In any case, this methods return two values:
- The mean of the loss function over all the patterns.
- The variance of the loss function over all the patterns.

The following training schedules are available:
- Training with all the patterns, in sequential way: the fields of the given table are:
- input_dataset a dataset with the data for input of ANN components.
- output_dataset a dataset with the data for target outputs of ANN components (supervision).
- bunch_size the mini-batch size, optional parameter. If not given, the bunch size instantiated at the trainer will be used.
- loss a loss function object, optional parameter. If not given, the loss instantiated at the trainer will be used.
- optimizer an optimizer object, optional parameter. If not given, the optimizer instantiated at the trainer will be used.
- Training with all the patterns in shuffled way: the fields of the given table are:
- input_dataset a dataset with the data for input of ANN components.
- output_dataset a dataset with the data for target outputs of ANN components (supervision).
- random a random object instance, used to shuffle the patterns.
- bunch_size the mini-batch size, optional parameter. If not given, the bunch size instantiated at the trainer will be used.
- loss a loss function object, optional parameter. If not given, the loss instantiated at the trainer will be used.
- optimizer an optimizer object, optional parameter. If not given, the optimizer instantiated at the trainer will be used.
- Training with replacement: the fields of the given table are:
- input_dataset a dataset with the data for input of ANN components.
- output_dataset a dataset with the data for target outputs of ANN components (supervision).
- random a random object instance, used to shuffle the patterns.
- replacement a given number with the size of the replacement.
- bunch_size the mini-batch size, optional parameter. If not given, the bunch size instantiated at the trainer will be used.
- loss a loss function object, optional parameter. If not given, the loss instantiated at the trainer will be used.
- optimizer an optimizer object, optional parameter. If not given, the optimizer instantiated at the trainer will be used.
- Training with distribution: the fields of the given table are:
- distribution is an array of tables, where each table contains:
* input_dataset a dataset with the data for input of ANN components.
* output_dataset a dataset with the data for target outputs of ANN components (supervision).
* prob a number with the probability of taken a pattern from this data source.
- random a random object instance, used to shuffle the patterns.
- replacement a given number with the size of the replacement.
- bunch_size the mini-batch size, optional parameter. If not given, the bunch size instantiated at the trainer will be used.
- loss a loss function object, optional parameter. If not given, the loss instantiated at the trainer will be used.
- optimizer an optimizer object, optional parameter. If not given, the optimizer instantiated at the trainer will be used.

\subsection*{14.2.9.2 validate_dataset}
loss_mu,loss_var = trainer:validate_dataset\{ ... \}
This method is used to validate the model by using a given dataset. Different validation schedules are possible, depending on the parameters given to the method. In any case, this method returns two values:
- The mean of the loss function over all the patterns.
- The variance of the loss function over all the patterns.

The following validation schedules are available:
- Validate with all the patterns, in sequential way: the fields of the given table are:
- input_dataset a dataset with the data for input of ANN components.
- output_dataset a dataset with the data for target outputs of ANN components (supervision).
- bunch_size the mini-batch size, optional parameter. If not given, the bunch size instantiated at the trainer will be used.
- loss a loss function object, optional parameter. If not given, the loss instantiated at the trainer will be used.
- Validate with replacement: the fields of the given table are:
- input_dataset a dataset with the data for input of ANN components.
- output_dataset a dataset with the data for target outputs of ANN components (supervision).
- random a random object instance, used to shuffle the patterns.
- replacement a given number with the size of the replacement.
- bunch_size the mini-batch size, optional parameter. If not given, the bunch size instantiated at the trainer will be used.
- loss a loss function object, optional parameter. If not given, the loss instantiated at the trainer will be used.

\subsection*{14.2.9.3 use_dataset}
output_ds = trainer:use_dataset\{ ... \}
This method receives a table with a one or two datasets and computes the output of the ANN component for every pattern. Note that this method has a large use of memory, because it needs a dataset where to store the ANN output for every pattern. Please, be careful when using it.

It receives a table with fields:
- input_dataset a dataset with the input data for the ANN component.
- output_dataset a dataset with enough space to store the output of the ANN component for every pattern in the input_dataset. If not given, the output_dataset will be allocated automatically with the required size.

This method returns the output_dataset with the produced data.
```

14.2.9.4 grad__check_dataset
boolean = trainer:grad_check_dataset{ ... }

```

\subsection*{14.3 Training function loop classes}

This two classes are useful to build a training loop with a default stopping criterion.

\subsection*{14.3.1 train__wo__validation}
trainable.train_wo_validation class
This class implements the training function without validation, using a stopping criterion based on percentage of improvement in training or in number of epochs. The following methods are defined.

\subsection*{14.3.1.1 Constructor}
```

train_func = trainable.train_wo_validation{ ... }

```

The constructor, which receives a table with the following fields:
- min_epochs=1: the minimum number of epochs of the training. It is optional.
- max_epochs: the maximum number of epochs of the training, if min_epochs==max_epochs then stopping criteria will be number of epochs.
- percentage_stopping_criterion=0.01: a number in range [0,1] indicating the threshold for the percentage of improvement in training loss between two consecutive epochs. If the train loss improvement is less than this number, the training will stops. It is an optional field.
- first_epoch=1: indicates the number of the first epoch. It is optional.
```

> -- instance using percentage_stopping_criterion=0.01 (default value)
> train_func = trainable.train_wo_validation{ max_epochs = 100 }

```

\subsection*{14.3.1.2 execute}
```

boolean = train_func:execute(epoch_function)

```

This method executes one epoch step. It is the most important method. It receives an epoch function, which is a closure with the responsibility of perform training with one epoch, and it must returns two values: the trained model and the training loss. The method returns true or false depending in if the stopping criterion is satisfied or not.
```

> while train_func:execute(function()
local tr = trainer:train_dataset(datosentrenar)
return trainer,tr
end) do
print(train_func:get_state_string())
end

```

\subsection*{14.3.1.3 set_param}
```

train_func:set_param(name,value)

```

This method modifies the value of a parameter previously given at the constructor (or used with its default value).

\subsection*{14.3.1.4 get_param \\ value = train_func:get_param(name)}

This method returns the value of a parameter previously given at the constructor (or used with its default value).
```

14.3.1.5 get_state
epoch,tr_loss,tr_improvement,last=train_func:get_state()

```

This method returns the internal state of the object. last is the trained model returned by the last call to epoch function.

\subsection*{14.3.1.6 get_state_table}
state \(=\) train_func: get_state_table()
This method returns a table with the following fields:
- state.current_epoch: the current epoch.
- state.train_error: the train loss at last epoch.
- state.train_improvement: the train loss relative improvement.
- state.last: the trained model returned by the last call to epoch function.

\subsection*{14.3.1.7 get__state_string \\ string = train_func: get_state_string()}

This method returns a string for printing purposes, with the following format:
```

string.format("%5d %.6f %.6f",
state.current_epoch,
state.train_error,
state.train_improvement)

```

\subsection*{14.3.1.8 Code example}

Finally, here is a code example showing how to use this class:
```

> trainer = trainable.supervised_trainer(thenet, ann.loss.mse(), 64)
> train_func = trainable.train_wo_validation{ max_epochs = 100 }
> while train_func:execute(function()
local tr = trainer:train_dataset(training_data)
return trainer,tr
end) do
print(train_func:get_state_string())
util.serialize({ train_func, training_data.shuffle }, "training.lua")
end

```

The following is an example of loading previously saved object:
```

> train_func,shuffle = util.deserialize("training.lua")
> trainer = train_func:get_state_table().last
> thenet = trainer:get_component()
> training_data.shuffle = shuffle
> while train_func:execute(function()
local tr = trainer:train_dataset(training_data)
return trainer,tr
end) do
print(train_func:get_state_string())
util.serialize({ train_func, training_data.shuffle }, "training.lua")
end

```

\subsection*{14.3.2 train__holdout_validation}
trainable.train_holdout_validation class
This class implements the training function with a holdout validation set, using a stopping criterion based on validation or error in number of epochs. This object follows the Pocket Algorithm, so, it keeps the model which has the best validation loss during the training. A tolerance in the relative error could be used to decided a minimum improvement to take the model as the best. The following methods are defined.

\subsection*{14.3.2.1 Constructor}
train_func = trainable.train_holdout_validation\{ ... \}
The constructor, which receives a table with the following fields:
- min_epochs=1: the minimum number of epochs of the training. It is optional.
- max_epochs: the maximum number of epochs of the training, if min_epochs==max_epochs then stopping criteria will be number of epochs.
- epochs_wo_validation=0: the number of epochs where validation loss is ignored, so the best model is the last given. It is optional.
- stopping_criterion=function() return false end: a stopping criterion function. It will be used to determine when the training must be stopped. The given function is called given it a table with the output of get_state_table() method. It is optional. Basic criterion functions are defined in trainable table, and described below this section.
- first_epoch=1: indicates the number of the first epoch. It is optional.
- tolerance \(=0\) : the tolerance \(>=0\) is the minimum relative difference to take the current validation loss as the best. It is optional.
```

> criterion = trainable.stopping_criteria.make_max_epochs_wo_imp_relative(2)
> train_func = trainable.train_holdout_validation{
stopping_criterion = criterion,
max_epochs = max_epochs
}

```

\subsection*{14.3.2.2 execute}
```

boolean = train_func:execute(epoch_function)

```

This method executes one epoch step. It is the most important method. It receives an epoch function, which is a closure with the responsibility of perform training with one epoch, and it must returns three values: the trained model, the training loss and the validation loss. The method returns true or false depending in if the stopping criterion is satisfied or not.
```

> while train_func:execute(function()
local tr = trainer:train_dataset(training_data)
local va = trainer:validate_dataset(validation_data)
return trainer,tr,va
end) do
print(train_func:get_state_string())
local state = train_func:get_state_table()
if state.best_epoch == state.current_epoch then
util.serialize({ train_func, training_data.shuffle }, "training.lua")
end
end

```

\subsection*{14.3.2.3 set__param}
```

train_func:set_param(name,value)

```

This method modifies the value of a parameter previously given at the constructor (or used with its default value).

\subsection*{14.3.2.4 get_param}
value = train_func: get_param(name)
This method returns the value of a parameter previously given at the constructor (or used with its default value).

\subsection*{14.3.2.5 get_state}
epoch,tr_loss,va_loss,...=train_func:get_state()
This method returns the internal state of the object: epoch, training loss, validation loss, best epoch, best validation loss, best model clone, last given model.

\subsection*{14.3.2.6 get_state_table}
state \(=\) train_func: get_state_table()
This method returns a table with the following fields:
- state.current_epoch: the current epoch.
- state.train_error: the train loss at last epoch.
- state.validation_error: the validation loss at last epoch.
- state.best_epoch: the epoch where the best validation loss where found.
- state.best_val_error: the validation loss at the best epoch.
- state. best: the trained model which achieves the best validation error.
- state.last: the trained model returned by the last call to epoch function.

\subsection*{14.3.2.7 get_state_string \\ string = train_func: get_state_string()}

This method returns a string for printing purposes, with the following format:
```

string.format("%5d %.6f %.6f %5d %.6f",
state.current_epoch,
state.train_error,
state.validation_error,
state.best_epoch,
state.best_val_error)

```

\subsection*{14.3.2.8 Code example}

Finally, here is a code example showing how to use this class:
```

> trainer = trainable.supervised_trainer(thenet, ann.loss.mse(), 64)
> criterion = trainable.stopping_criteria.make_max_epochs_wo_imp_relative(2)
> train_func = trainable.train_holdout_validation{
stopping_criterion = criterion,
max_epochs = max_epochs
}
> while train_func:execute(function()
local tr = trainer:train_dataset(training_data)
local va = trainer:validate_dataset(validation_data)
return trainer,tr,va
end) do
print(train_func:get_state_string())
local state = train_func:get_state_table()
if state.best_epoch == state.current_epoch then
util.serialize({ train_func, training_data.shuffle }, "training.lua")
end
end

```

\subsection*{14.4 Stopping criteria}

For holdout-validation scheme, exists two predefined stopping criteria, which are function builders (they return the function used as criterion):
- trainable.stopping_criteria.make_max_epochs_wo_imp_absolute: which receives a constant indicating the maximum number of epochs without improve validation. A tipical value is between 10 and 20, depending in the task.
- trainable.stopping_criteria.make_max_epochs_wo_imp_relative: which receives a constant indicating the maximum value for current_epoch/best_epoch. A tipical value for this is 2 .

This two criteria could be used as this:
```

train_func = trainable.train_holdout_validation{
stopping_criterion = trainable.stopping_criteria.make_max_epochs_wo_imp_relative(2),
}

```

Also you can create your own stopping criterion, which is a function which receives a table:
```

train_func = trainable.train_holdout_validation{
stopping_criterion = function(t)
-- t contains this fields:
-- * current_epoch
-- * best_epoch
-- * best_val_error
-- * train_error
-- * validation_error
return true IF STOPPING CRITERIA(t) IS TRUE
end,
}

```

\subsection*{14.5 Dataset iterator functions}

The class trainable.supervised_trainer uses some generic dataset iterator functions, available for the user if needed. Two functions are available: trainable.dataset_pair_iterator and trainable.dataset_multiple_iterator. The first is a wrapper around the second one. This iterators could perform different traverse methods, depending in the given parameters.

\subsection*{14.5.1 dataset__pair_iterator}

Lua iterator \(=\) trainable.dataset_pair_iterator\{ ... \}
This iterator performs a synchronized traversal of two given datasets (normally it is a pair input/output). The function returns a Lua iterator which returns three values every time it is called: input pattern (a token, usually a matrix instance), output pattern (a token, usually a matrix instance), and a Lua table with the indexes of the patterns taken in the bunch.

The available traversal modes are:
- Traverse all the patterns, in sequential way: the fields of the given table are:
- input_dataset a dataset with the data for input of ANN components.
- output_dataset a dataset with the data for target outputs of ANN components (supervision).
- bunch_size the mini-batch size.
- Traverse all the patterns in shuffled way: the fields of the given table are:
- input_dataset a dataset with the data for input of ANN components.
- output_dataset a dataset with the data for target outputs of ANN components (supervision).
- shuffle a random object instance, used to shuffle the patterns.
- bunch_size the mini-batch size.
- Traverse with replacement: the fields of the given table are:
- input_dataset a dataset with the data for input of ANN components.
- output_dataset a dataset with the data for target outputs of ANN components (supervision).
- shuffle a random object instance, used to shuffle the patterns.
- replacement a given number with the size of the replacement.
- bunch_size the mini-batch size.
- Traverse with distribution: the fields of the given table are:
- distribution is an array of tables, where each table contains:
* input_dataset a dataset with the data for input of ANN components.
* output_dataset a dataset with the data for target outputs of ANN components (supervision).
* prob a number with the probability of taken a pattern from this data source.
- shuffle a random object instance, used to shuffle the patterns.
- replacement a given number with the size of the replacement.
- bunch_size the mini-batch size.
```

> ds_params = { input_dataset = my_input_ds, output_dataset = my_output_ds }
> for input,output,idxs in trainable.dataset_pair_iterator(ds_params) do
-- you can give the input/output to an ANN and loss function
print(input,output,idxs)
end

```

\subsection*{14.5.2 dataset__multiple__iterator}

Lua iterator \(=\) trainable.dataset_multiple_iterator\{ ... \}
This iterator performs a synchronized traversal of any number given datasets (normally it is a pair input/output). The function returns a Lua iterator which returns as many values as the number of given datasets plus one: one pattern for each dataset, plus a Lua table with the indexes of the patterns taken in the bunch.

The available traversal modes are:
- Traverse all the patterns, in sequential way: the fields of the given table are:
- datasets: a Lua table with the list of dataset for traversal.
- bunch_size the mini-batch size.
- Traverse all the patterns in shuffled way: the fields of the given table are:
- datasets: a Lua table with the list of dataset for traversal.
- shuffle a random object instance, used to shuffle the patterns.
- bunch_size the mini-batch size.
- Traverse with replacement: the fields of the given table are:
- datasets: a Lua table with the list of dataset for traversal.
- shuffle a random object instance, used to shuffle the patterns.
- replacement a given number with the size of the replacement.
- bunch_size the mini-batch size.
- Traverse with distribution: the fields of the given table are:
- distribution is an array of tables, where each table contains:
* datasets: a Lua table with the list of dataset for traversal.
* prob a number with the probability of taken a pattern from this data source.
- shuffle a random object instance, used to shuffle the patterns.
- replacement a given number with the size of the replacement.
- bunch_size the mini-batch size.
```

> ds_params = { datasets = { my_ds1, my_ds2, my_ds3 } }
> for token1,token2,token3,idxs in trainable.dataset_multiple_iterator(ds_params) do
-- you can give the token1,token2,token3 to an ANN or a loss function
print(token1,token2,token3,idxs)
end

```

\section*{Chapter 15}

\section*{random package}

\subsection*{15.1 Introduction}

Package random could be loaded via the standalone binary, or in Lua with require("aprilann.random).
The random class is useful to generate pseudo-random numbers, and is widely used by ANN components and other classes of APRIL-ANN. It is based on Mersenne Twister, basically it is a binding of the original C++ code of Mersenne Twister.

\subsection*{15.2 Methods of random class}
random contains the following methods:

\subsection*{15.2.1 Constructor}
obj \(=\) random ( [seed] )
A constructor of the object. The parameter is optional, if not given, it is taken from the current time of the machine. If given, it could be:
- a seed number for the initialization of the random generator;
- a table with seeds for the initialization of the random generator.

\subsection*{15.2.2 rand}
number = obj:rand ( [number] )
Returns a double random number in the interval [ \(0, \mathrm{n}\) ], being n the given parameter. If not given any parameter, by default \(n=1\).

\subsection*{15.2.3 randExc}
```

number = obj:randExc( [number] )

```

Returns a double random number in the interval \([0, \mathrm{n})\), being n the given parameter. If not given any parameter, by default \(n=1\).

\subsection*{15.2.4 randDblExc}
number = obj:randDblExc ( [number] )
Returns a double random number in the interval \((0, n)\), being \(n\) the given parameter. If not given any parameter, by default \(n=1\).

\subsection*{15.2.5 randInt}
```

number = obj:randInt( [x, [ y ] ] )

```

Returns an integer random number in the interval \([x, y]\). If only one argument is given, then the interval will be \([0, x]\). If zero argument are given, the interval will be \([0,2 \wedge 32-1]\).

\subsection*{15.2.6 shuffle}
table = obj:shuffle( N )
Returns a table with size N , which is a permutation of the indices of an N -sized array.
```

table = obj:shuffle(table)

```

Returns a random permutation of the given table array.

\subsection*{15.2.7 choose}
number = obj:choose(size)
\$eturns a random element for an array of the given size. It is equivalent to obj:randInt(1,size).

\subsection*{15.2.8 randNorm}
number \(=\) obj:randNorm(mean, variance)
Returns a random number sampled from a Gaussian with the given mean and variance parameters.

\subsection*{15.2.9 seed}
obj:seed(number)
Modifies the seed, see the constructor.
obj: seed (table)
Modifies the seed, see the constructor.

\subsection*{15.2.10 clone}
another \(=\) obj:clone()
Returns a deep copy of the caller object.

\section*{Chapter 16}

\section*{autodiff package}

\subsection*{16.1 Introduction}

Related with package require("aprilann.autodiff").
The autodiff package is an in-development package, which adds automatic differentiation to APRIL-ANN toolkit. It is inspired into Theano, but, in this case, using Lua and APRIL-ANN matrix library instead of tensors in Python.

This packages works over three main data types: constants, scalars, matrices. For example, the addition of two scalars will need the following code:
```

> AD = autodiff -- for simplicity
> a,b = AD.scalar('a b')
> c = a + b
> = c
(+ a b)

```

Every expression is stored as a graph of dependencies between operations and its arguments. Every symbol (like a, b or c) is a special Lua table. Symbols has a name, in the case of ground symbols (like a or b), its name is the symbol itself. In the case of operations (like c), the name is what you see when you do print (c).
```

> = a.name,b.name,c.name
a b (+ a b)

```

A symbol only exists once, so, if you declare another symbol with the same name, or the same operation, it will be a reference to the first symbol declaration. They are exactly the same variable. In this way, the computation is performed in a symbolic graph, and the use of memoization allows to ensures that every operation is only computed once, even if it is repeated several times.

However, depending in the declaration order, the same operation could be represented in different ways. It is possible to optimize the graph applying basic arithmetic properties.
```

> d = c + b + a
> = d
(+ (+ (+ a b) b) a)
> e = AD.optimize(d)
> = e
(+ (* 2 a) (* 2 b))

```

It is possible to operate with Lua numbers, which are automatically coerced into autodiff.constant symbol:
```

> f = 4*b*a/b + 2
> = f
(+ (* (* (* 4 b) a) (~ b -1)) 2)
> = AD.optimize(f)
(+ (* 4 a) 2)

```

Math operators are overloaded using Lua metamethods, so it is possible to do use math operators in a standard way: addition, subtraction, multiplication, division, power, unary minus. Nevertheless, this operations are defined as functions in autodiff package.
```

> op = AD.op -- for simplicity
> c = AD.op.div( AD.op.add(a,b), 4)
> = c
(* (+ a b) 0.25)

```

Constants are automatically folded, performing constant operations. Subtraction is transformed in addition with multiplication by -1 . Division is transformed into multiplication with power by -1 . This reduces a lot the simplification effort.
```

> c = a/b - a
(+ (* (~ b -1) a) (* -1 a))

```

But this transformations makes difficult to follow the printed string. It is possible to produce a graph in dot format.
```

> AD.dot_graph(c, "mygraph.dot")

```

The most interesting thing is the automatic differentiation procedure, which receives a list of variables w.r.t differentiate. The function returns a variable number of arguments, one graph for each differentiated variable.
```

> c = a * b
> da,db = AD.diff(c, {a,b})
> = da
b
> = db
a

```

Any graph could be evaluated with a given instantiation of its internal ground variables.
```

> c = a * b
> = c:eval{ a=5, b=2 }
10
> = da:eval{ a=3, b=2 }
2
> = db:eval{ a=3, b=2 }
3

```

Additionally, it is possible to compile several graphs together, sharing the computation of equal operations. The compilation procedure automatically applies the optimization function to the given graphs. It receives the list of graphs (symbols) which you want to compile together, and a list of input variables (in order). Optionally it is possible to give a dictionary Lua table with values which will be shared between the compiled function and the caller Lua virtual machine.
```

> -- AD.func does the compilation
>my_func1 = AD.func({ c, da, db }, { a,b })
> = my_func1 (2,5)
10 5 2
> shared = { b=4 }
> my_func2 = AD.func({ c, da, db }, { a }, shared)
> = my_func2(2) -- 2 * 4
8 4 2
> shared.b = 10
> = my_func2(2) -- 2 * 10
20 10 2

```

\subsection*{16.2 Basic functionality}

The most important concept is the symbol, which could be a ground variable (with a declared type) or a computational graph. Every symbol has a name which identifies it univocally. Every symbol has overloaded basic math operations (addition, subtraction, multiplication, division, unary minus, power), allowing to use standard math symbols to produce complex operations. Computational graph symbols represent operations. Every symbol implements a generic interface. Depending in the type, symbols are constructed in different ways:
```

> AD = autodiff -- for simplicity
> a,b = AD.scalar('a b') -- scalar constructor
> c = a + 4*b -- 4 is casted to AD.constant type
>m = AD.matrix('m') -- matrix constructor
>d}=m*

```

The type of computational graph symbols (operations) depends in the arguments of the operation. Inference rules are declared in order to decide when an operation is over matrices, scalar, constants, or any of the possible symbol types.

\subsection*{16.2.1 eval}
value = s:eval ( table [, cache] )
Evaluates the caller symbol by using the given table of ground variables. All the ground variables need to be defined (except constants).


An optional table could be given as second argument, which will be used as cache table (for memoization), allowing to share computations between different symbols evaluation. In this case, it is not necessary to give all the ground variables, as far as all the needed partial operations where computed and moemoized in the given cache table.
```

> cache = {}
> = c:eval({ a=10, b=2 }, cache) -- computes c=a + 4*b
18
> = d:eval({ m=matrix(3,3):linear() }, cache) -- computes d = m * 18
0

# Matrix of size [3,3] in row_major [0x2b6cd60 data= 0x293e4a0]

```

\subsection*{16.2.2 func}
```

function = autodiff.func(symbols, args, shared [, optimize=true])

```

This function compiles together the given set of symbols, producing as result a Lua function which receives as arguments the ground variables indicated in the args table (ordered), and shares the given table of shared ground variables. Additionally, an optional fourth argument could be given, indicating with a boolean if optimization needs to be performed or not. If not given, this fourth argument will be considered true.

The symbols list (first argument) could be a table of symbols or a symbol. The returned Lua function will receive as many arguments as the size of args table array, and will produce as many values as size of symbols list.
```

> f = AD.func(d, {a,b}, {m = matrix(3,3):linear()})
> = f(10, 2)
$0 \quad 18 \quad 36$
54 72 90
108 126 144

# Matrix of size [3,3] in row_major [0x1cddcdO data= 0x1c86b20]

```

\subsection*{16.2.3 diff}
```

ds1,ds2,... = autodiff.diff(symbol, { s1, s2, ... } [, seed] )

```

This function differentiates the given symbol w.r.t. all the given array of ground variables (second argument). It returns multiple outputs, as many as the size of the ground variables array.
```

> dm,da = autodiff.diff(d, { m, a })
> = dm
(.* (+ (* 4 b) a) (fill (.* m (+ (* 4 b) a)) 1))
> = da
(.* m (fill (.* m (+ (* 4 b) a)) 1))
> = d
(.* m (+ (* 4 b) a))

```

Looking to the produced computations, they have one thing in common: both uses a fill operation which receives as input the original d computational graph and the number 1. The fill operations produces a symbol with the same shape and type of the given first argument, but replacing all its components with the given second argument, 1 in this case. This is the seed needed to implement reverse accumulation algorithm for
automatic differentiation. This seed forces to compute the output produced by the original computation. It is possible to avoid this computation using the optional third argument of the diff function, given a seed symbol which will be treated as a new ground variable. When compiling or evaluation the differentiated symbols, you will need to give the value of the seed. The shape and type of the seed must be exactly the same as the non-differentiated symbol (in this case d), and normally filled with 1 s , but it could be a seed produced as derivative by other function.
```

> seed = AD.matrix('seed')
> dm,da = AD.diff(d, { m, a })
> = dm
(.* (+ (* 4 b) a) seed)
> = da
(.* m seed)

```

\subsection*{16.3 Symbol advanced methods}

\subsection*{16.3.1 diff}
```

table = s:diff(seed, table)

```

\subsection*{16.3.2 compile}
s:compile(compiler)

\subsection*{16.3.3 arg_ipairs}

Lua iterator = s:arg_ipairs()
This method returns a Lua iterator which traverses using ipairs all the arguments received by the given symbol. If it is a ground variable, this method returns an empty iterator.

\subsection*{16.3.4 replace}
symbol = s:replace(new_symbol)
This method is used in optimization procedures. It allows to replace the caller symbol by the given symbol. It returns the caller symbol.

\subsection*{16.3.5 clear__var__name}
symbol = s:clear_var_name()
This method removes the variable name associated with compilation. It returns the caller symbol.

\subsection*{16.3.6 set_dims}
```

symbol = s:set_dims(d1, d2, ...)

```

This method indicates the shape of the caller symbol. It is useful with matrix type, allowing to check if matrices fit the declared operations. It returns the caller symbol.
```

> a,b = AD.matrix('a b')
> a:set_dims(2,4)
> b:set_dims(4,3)
c c = a * b
> = table.unpack( c.dims )
2 3
> a:set_dims(2,2)
> c = a * b
[string "luaopen_aprilann_autodiff"]:5: Incorrect matrix dims for multiplication: 2x2 * 4x3
stack traceback:
[C]: in function 'assert'
[string "luaopen_aprilann_autodiff"]:5: in function < [string "luaopen_aprilann_autodiff"]:5>
(...tail calls...)
stdin:1: in main chunk
[C]: in ?

```

\subsection*{16.3.7 set__broadcast}
symbol = s:set_broadcast(b1, b2, ...)
The term broadcasting describes how matrices with different shapes are treated during operations. Some mathematical operators allow to work with matrices with not fitted shapes, replicating one of the matrices over broadcasted dimensions. This concept is similar to numpy broadcast. As example, broadcasting is used in ANNs when you add bias vector, allowing to compute operations with several samples at the same time (mini-batch or bunch-mode):
```

> x,w,b = AD.matrix('x w b')
> x:set_dims(20, 4) -- 20 features, 4 samples
> w:set_dims(10, 20) -- 10 outputs, 20 inputs
> b:set_dims(10, 1) -- 10 bias components
> b:set_broadcast(false, true)
> output = w*x + b -- bias is broadcasted to fit the addition operation
> = output:eval{ x=matrix(20,4):uniformf(),
w=matrix (10, 20):uniformf(),
b=matrix(10,1):uniformf() }

| 4.92572 | 6.4316 | 5.24994 | 5.73787 |
| :--- | :--- | :--- | :--- |
| 5.13588 | 5.06926 | 4.93599 | 5.89694 |

5.82963 6.1323 6.2065 7.06305
4.51586 5.76797 5.27805 6.3306
4.17794 5.31377 4.05488 4.4576
4.20612 5.04744 4.77355 5.41917
5.74113 6.56931 5.7724 6.52165
6.00033 6.34304 5.77687 7.40072
7.1957 8.11042 7.12002 8.2262
5.53413 6.22189 5.72926 6.46156

# Matrix of size [10,4] in row_major [0x29c1750 data= 0x2979e00]

```

If you don't indicate true in the corresponding broadcasting dimension, an error will occur. By default, all the dimensions has a false broadcasting property.
```

> b:set_broadcast(false, false)
> output = w*x + b -- bias is broadcasted to fit the addition operation
> = output:eval{ x=matrix(20,4):uniformf(),

```
```

w=matrix(10,20):uniformf(),
b=matrix(10,1):uniformf() }
[string "luaopen_aprilann_autodiff"]:5: Not broadcasted dimensions must be equal, found broadcasted_dim
stack traceback:
[C]: in function 'assert'
[string "luaopen_aprilann_autodiff"]:5: in function 'eval_func'
[string "luaopen_aprilann_autodiff"]:1: in function <[string "luaopen_aprilann_autodiff"]:1>
(...tail calls...)
[C]: in ?

```

\subsection*{16.4 Symbols}

\subsection*{16.4.1 Constants}

\subsection*{16.4.2 Scalars}

\subsection*{16.4.3 Matrices}

\subsection*{16.4.4 Other data types}

\subsection*{16.5 Gradient descent learning}

\section*{Chapter 17}

\title{
autodiff.ann package
}

\subsection*{17.1 Introduction}

Related with package require("aprilann.autodiff.ann").

\section*{Chapter 18}

\section*{matlab package}

\subsection*{18.1 Introduction}

Package matlab could be loaded via the standalone binary, or in Lua with require("aprilann.matlab).
The MAT-file format belongs to Matlab software. We follow this documentation to implement this loader. Saving is not available.

Currently, only Cell Arrays, Structures, and Numeric Matrices could be loaded, all of them only in binary format. Compression is allowed. All the data must follow the guidelines described at the documentation.

\subsection*{18.2 Test files}

We use three test files (test1.mat, test2.mat, and test3.mat) produced by the following Matlab commands:

\subsection*{18.2.1 test 1}
```

> x = [ -1.34187 -1.77726 -1.73478 ...
> -0.932328 0.59467 0.332692 ...
> ...
> ];
> save("test1.mat", "x")

```

\subsection*{18.2.2 test 2}
```

>A = [ 1 2 3; 4 5 6 ];
> B = [ 7 8 9; 10 11 12 ];
> C = { A, B };
> save("test2.mat", "C")

```

\subsection*{18.2.3 test 3}
```

> X.w = 1
>X.y = 2

```
```

> X.z = 3
> save("test3.mat", "X")

```

\subsection*{18.3 Basic operations}

The MAT-file could be loaded using the function matlab.read. This function shows at the screen commented lines which indicates the kind of data loaded and the name of the variables. All the Matlab variables will be allocated at a Lua table, indexed by the name of the variable.
```

> a_table = matlab.read("test1.mat")
> print(a_table.x)
$1.34187-1.77726-1.73478$...
-0.932328 0.59467 0.332692 ...
-0.254006 -2.86238 0.877438 ...

```

It is also possible to print fields of the table using the print or tostring functions. The following example shows the print function for a Cell Array.
```

> a_table = matlab.read("test2.mat")
> print(a_table)
C : matlab.cell_array dims [1,2]
> print(a_table.C:get(1,1))
1 2 3
4 5 6

# MatrixDouble of size [2,3] stride [3,1] ref [0x22bebe0 data= 0x2206400]

> print(a_table.C:get (1,2))
7 8 9
10 11 12

# MatrixDouble of size [2,3] stride [3,1] ref [0x239f120 data= 0x2379ed0]

```

\subsection*{18.4 Loading matrices}

When a MAT-file with MAT-matrix variables is loaded, every MAT-matrix is converted to APRIL-ANN matrix objects. Five matrices are available, depending on the MAT-matrix data-type: matrix for float, matrixDouble for double, matrixInt32 for int32, matrixComplex for float complex numbers, and matrixChar for char.

\subsection*{18.5 Loading Cell Arrays}

If any of the variables is a Cell Array, it becomes a Lua object (a table with methamethods) which has the following methods:
- \(\operatorname{table}=c: \operatorname{dim}()\) returns a table with the size of each dimension of the array.
- number \(=\mathrm{c}: \operatorname{dim}\) (number) returns the size of the given dimension (starging in 1 )
- element \(=c: \operatorname{get}(\mathrm{p} 1, \mathrm{p} 2, \ldots, \mathrm{pn})\) returns the element at the position ( \(\mathrm{p} 1, \mathrm{p} 2, \ldots, \mathrm{pn}\) ), where element could be a matrix, matrixChar, matrixInt32, cell_array, or structure, depending on the class of data.
```

> a_table = matlab.read("test2.mat")
> print(a_table.C:get(1,1))
1 2 3
4 5 6

# Matrix of size [2,3] in row_major [0x27a0340 data= 0x26cf9c0]

> print(a_table.C:get (1,2))
7 8 9
10 11 12

# Matrix of size [2,3] in row_major [0x283c6a0 data= 0x26e4a40]

```

The following methods are for low-level access, which could be useful to do a loop over all the elements:
- number \(=c: s i z e()\) returns the number of elements at the array.
- element = c:raw_get (number) returns the element at row_major sorted position number, being number between 0 and \(c: \operatorname{size}()-1\). The number is the position of the element if all elements where sorted as a continuous array.
- table \(=c:\) compute_coords (number) returns the coordinate position of a given raw position number. As previous method, the number must be between 0 and \(\mathrm{c}:\) size()-1.
```

> a_table = matlab.read("test2.mat")
> print(a_table)
C : matlab.cell_array dims [1,2]
> C = a_table.C
> for i=0,C:size()-1 do e=C:raw_get(i)print("COORDS",unpack(C:compute_coords(i)))print(e)end
COORDS 1
1 2 3
4 5 6

# Matrix of size [2,3] in row_major [0x1904b20 data= 0x18c90f0]

COORDS 1 2
7 8 9
10 11 12

# Matrix of size [2,3] in row_major [0x19054e0 data= 0x18caed0]

```

\subsection*{18.6 Loading Structures}

The Structures are transformed in Lua tables (as dictionaries), indexed by the name of the fields, and as values the corresponding elements. As before, the elements could be any kind of matrix, cell_array, or structure.
```

> a_table = matlab.read("test3.mat")
> print(a_table)
X : table
> print(a_table.X)
y : matrixDouble
z : matrixDouble
w : matrixDouble
> print(a_table.X.y)
2

# Matrix of size [1,1] in row_major [0xd999c0 data= 0xd99690]

> print(a_table.X.w)

```
\# Matrix of size [1,1] in row_major [0xd99b60 data= 0xd99c20]
> print(a_table.X.z)
    3
\# Matrix of size [1,1] in row_major [0xd99d30 data= 0xd99df0]

\section*{Chapter 19}

\section*{stats package}

\subsection*{19.1 Introduction}

Package stats could be loaded via the standalone binary, or in Lua with require("aprilann.stats). This package contains utilities for statistical purposes.

\subsection*{19.2 Matrix functions}
19.2.1 stats.hist
19.2.2 stats.ihist
19.2.3 stats.amean
result \(=\) stats.amean \((m[, \operatorname{dim}])\)
19.2.4 stats.gmean
result \(=\) stats.gmean(m[, dim])
19.2.5 stats.hmean
result \(=\) stats.hmean(m[, dim])
19.2.6 stats.var
result \(=\) stats. \(\operatorname{var}(\mathrm{m}[\), dim] \()\)
19.2.7 stats.std
result \(=\) stats.std(m[, dim])

\subsection*{19.2.8 stats.acf}
result,lags \(=\) stats.acf( \(m[,\{\) lag_max, lag_step, cor \}])

\subsection*{19.2.9 stats.cov}
result \(=\) stats. \(\operatorname{cov}(x[, y[,\{\) centered, true_mean \}]])
19.2.10 stats.cor
result \(=\) stats. \(\operatorname{cor}(x[, y[,\{\) centered \}]])

\subsection*{19.2.11 stats.percentile}
r1,r2,... = stats.percentile(m, p1, p2, ...)

\subsection*{19.2.12 stats.center}
```

result,center = stats.center(m[, center])

```

\subsection*{19.2.13 stats.standardize}
```

result,center,scale = stats.standardize(m[,{ center, scale }])

```

\subsection*{19.2.14 stats.summary}
```

tbl = stats.summary(m)

```

\subsection*{19.3 Statistical distributions}

\subsection*{19.3.1 stats.dist.uniform}

\subsection*{19.3.2 stats.dist.normal}

\subsection*{19.3.3 stats.dist.lognormal}

\subsection*{19.3.4 stats.dist.binomial}

\subsection*{19.3.5 stats.dist.bernoulli}

\subsection*{19.3.6 stats.dist.beta}

\subsection*{19.3.7 stats.dist.exponential}

\subsection*{19.4 Running measures}

\subsection*{19.4.1 Mean and variance class}
stats.running.mean_var*
This class is useful to compute mean and variance over a large number of elements in an efficient way, following (this method)[http://www.johndcook.com/standard_deviation.html] to avoid instability. This class has the following methods:
- obj=stats.running.mean_var() it is a constructor which builds an instance.
- \(\quad\) obj \(=\) obj: add(number) a method for adds a number to the set. It returns the caller object.
- obj = obj:add(iterator) a method which adds the sequence of numbers returned by the given iterator function. It returns the caller object.
- obj \(=\) obj: add (table) a method which adds all the elements of the given table (as array) to the set. The elements could be numbers or functions. It returns the caller object.
- mean, variance \(=\) obj:compute() computes and returns the accumulated mean and variance from all the calls to add method.
- number \(=\) obj:size() returns the number of elements added.
- obj = obj:clear() re-initializes the object.
```

> obj = stats.running.mean_var()
obj:add(4)
obj:add(10)
print(obj:compute())
18
obj:add({2,8,6,24})
print(obj:compute())
62
> obj:add( pairs({ a=2, b=10 }) )
> print(obj:compute())
8.25 50.785714285714
> print(obj:size())
8

```

\subsection*{19.5 Combinatorial}

\subsection*{19.5.1 stats.comb}
result \(=\) stats. \(\operatorname{comb}(n, k)\)

\subsection*{19.5.2 stats.log_comb}
result \(=\) stats. \(\log _{-} \operatorname{comb}(\mathrm{n}, \mathrm{k})\)

\subsection*{19.6 Bootstrapping and confidence intervals}

\subsection*{19.6.1 boot}
table \(=\) stats.boot \{ ... \}
This function receives a data sample, performs a random resampling of the data and gives it to a statistic function. The procedure is repeated several times (bootstrapping technique), and the function returns a matrix with the statistics computed for all the repetitions.

The function receives a table with this fields:
- size=number or table the sample population size, or a table with several sample population sizes.
- \(R=\) number the number of repetitions of the procedure.
- \(\mathrm{k}=\) number the number of results returned by statistic function. By default it is 1 .
- statistic=function a function which receives a matrixInt32 with a list of indices for resampling the data. The function can compute a number of k statistics (with \(\mathrm{k}>=1\) ), being returned as multiple results.
- verbose=false an optional boolean indicating if you want or not a verbose output. By default it is false.
- seed=1234 an optional number indicating the initial seed for random numbers, by default it is 1234 .
- random an optional random number generator. Fields seed and random are forbidden together, only one can be indicated.
- ncores=1 an optional number indicating the number of CPU cores to use for the computation. It allows to speed-up large bootstraps. By default it is 1.

The following example takes 1000 random values and performs bootstrap resampling over them, computing the mean of the resampled population:
```

-- the random population
> errors = stats.dist.normal():sample(random(567),1000)
> -- executes the bootstrap resampling function
> resampled_data = stats.boot{
size = errors:size(), R = 1000, seed = 1234, k=2,
statistic = function(sample)
local s = errors:index(1, sample)
local var,mean = stats.var(s)

```
```

    -- this function returns two results, the mean and the variance (k=2)
        return mean,var
    end,
    }
> -- the 95% confidence interval is computed, being the range [a,b]
> a,b = stats.boot.ci(resampled_data, 0.95, 1)
> print(a,b)
-0.073265952430665 0.051443199906498

```

\subsection*{19.6.2 boot.ci}
```

a,b = stats.boot.ci(data [, confidence=0.95 [, pos=1 ]])

```

This function receives a matrix with data computed by stats.boot and returns the confidence interval for the given confidence value and the given statistic function position. It returns two numbers, the left limit, and the right limit, being the interval \([\mathrm{a}, \mathrm{b}]\).
```

-- the 95% confidence interval [a,b] of sample mean
local a,b = stats.boot.ci(resampled_data, 0.95, 1)
-- the 95% confidence interval [a,b] of sample variance
local a,b = stats.boot.ci(resampled_data, 0.95, 2)

```

\subsection*{19.7 Principal Components Analysis}

\subsection*{19.7.1 pca.center_by__pattern}
```

matrix = stats.pca.center_by_pattern(matrix)

```

This function modifies in-place the given matrix, centering all the patterns to have zero-mean. The patterns must be ordered by rows, and the features by columns. The function returns the same matrix as given.
```

> -- four patterns, 6 features
> m = matrix(4,6):uniformf(1,2)
> = m
1.10795 1.55917 1.35379 1.22971 1.38055 1.81201
1.1907 1.58711 1.38786 1.55067 1.01365 1.6242
1.94076 1.33665 1.28377 1.72529 1.26619 1.60847
1.64965 1.65704 1.55421 1.80517 1.68546 1.92166

# Matrix of size [4,6] in row_major [0x2575340 data= 0x249c490]

> stats.pca.center_by_pattern(m)
> = m
-0.299245 0.151974 -0.0534089 -0.177485 -0.0266466 0.404811
-0.201669 0.194743 -0.00450444 0.15831
0.413907 -0.190203 -0.243086 0.198439 -0.260668
-0.0625433 -0.0551615 -0.15799 0.0929705 -0.0267389 0.209462

# Matrix of size [4,6] in row_major [0x2575340 data= 0x249c490]

> = m:sum(2):scal(1/m:dim(2)) -- each pattern is centered
-3.97364e-08
-1.58946e-07
-1.19209e-07
-1.39078e-07

# Matrix of size [4,1] in row_major [0x2519460 data= 0x2491bd0]

```

\subsection*{19.7.2 pca}
\(\mathrm{U}, \mathrm{S}, \mathrm{VT}=\) stats.pca(matrix)
This function implements standard PCA algorithm, based on covariance matrix computation, and Singular Values Decomposition (SVD). The function receives a matrix, where features are columns, and data samples are by rows, that is, for M patterns and N features, the matrix will be of MxN size. The function needs that input matrix was normalized, normally by centering the mean of each pattern (for example, using stats.pca.center_by_pattern(...) function, or other normalization depending in the task, see UFLDL Tutorial for more information about data normalization).

The function return three matrix objects, where:
- \(U\) is an orthogonal matrix which contains the eigen-vectors of the covariance matrix, with one eigen-vector per column, sorted in decreasing order.
- \(S\) is a vector (diagonal matrix) which corresponds with the singular values of the covariance matrix, sorted in decreasing order.
- VT is equivalent to \(U\), and can be ignored.
```

> -- 10000 patterns, 100 features
> m = matrix(10000,100):uniformf(1, 2, random(1234))
> m = stats.pca.center_by_pattern(m)
> U,S,VT = stats.pca(m)

```

\subsection*{19.7.3 pca.threshold}
```

i,s_i,s_mass = stats.pca.threshold(S [,mass=0.99] )

```

This function computes the cutting threshold for a given \(S\) vector with the singular values sorted in decreasing order. It receives the matrix, and an optional number with the probability mass which you want to retain, by default it is mass=0.99. The function computes three values:
- \(i\) is the index where you need to cut.
- \(s_{-} i\) is the singular value at the index \(i\), that is \(S: g e t(i)\).
- s_mass is the mass accumulated until this index.
```

> = stats.pca.threshold(S, 0.5)
4 5 ~ 0 . 0 8 4 3 9 2 0 1 1 1 6 5 6 1 9 ~ 0 . 4 9 5 7 5 7 1 3 4 6 3 8 5 5 ~
> = stats.pca.threshold(S, 0.7)
65 0.079482264816761 0.69391569135546
> = stats.pca.threshold(S)
97 0.06935129314661 0.98337004707581

```

\subsection*{19.7.4 pca.whitening}
matrix \(=\) stats.pca.whitening(X, U, S [, epsilon=0.0] )
This function implments PCA whitening, given a data matrix \(X\) (patterns by rows, features by columns), the \(U\) and \(S\) matrix objects returned by stats.pca(X), and an optional regularization value epsilon which by default is epsilon=0.0. The function returns a new allocated matrix, result of applying the whitening process.
```

> -- loading digits from TEST/digitos/digits.png
> img = ImageIO.read("TEST/digitos/digits.png")
> m = img:to_grayscale():matrix()
> ds = dataset.matrix(m, { patternSize={16,16}, stepSize={16,16},
numSteps={100,10} })
> data_matrix = ds:toMatrix():clone()
> data_matrix = stats.pca.center_by_pattern(data_matrix)
> -- PCA computation
> U,S,VT = stats.pca(data_matrix)
> -- PCA whitening
> data_whitened = stats.pca.whitening(data_matrix, U, S, 0.02)
> = data_whitened
Large matrix, not printed to display

# Matrix of size [1000,256] [0x1be71b0 data= 0x1b23540]

```

If you want, it is possible to do dimension reduction by given \(U\) and \(S\) matrix slices, instead of the whole matrices.
```

> -- PCA whitening and dimensionality reduction (256 => 100)
> out = stats.pca.whitening(data_matrix, U(':','1:100'), S('1:100'), 0.02)
> = out
Large matrix, not printed to display

# Matrix of size [1000,100] [0xe5c070 data= 0xe5c140]

```

See also documentation of ann.components.pca_whitening (when available).

\subsection*{19.7.5 zca.whitening}
\(X=\) stats.zca.whitening( \(X, U, S\), epsilon)
This function receives the same arguments as stats.pca.whitening, but instead of do a PCA whitening, it computes a ZCA whitening. In this case, the output is the given matrix X , so, the computation is done in-place.
```

> -- ZCA whitening
> data_whitened = stats.zca.whitening(data_matrix:clone(), U, S, 0.02)
> -- write to disk
> aux = data_whitened:clone("row_major")
> for sw in aux:sliding_window():iterate() do sw:adjust_range(0,1) end
> ImageIO.write(Image(aux), "digits-whitened.png")

```

\subsection*{19.7.6 pca.gs_pca}

T, P, R = stats.pca.gs_pca\{ ... \}
WARNING this implementation is in experimental stage.
Implementation of PCA-GS algorithm, an iterative efficient algorithm for PCA computation. This code is translated from GSL CBLAS implementation of the paper Parallel GPU Implementation of Iterative PCA Algorithms, M. Andrecut. The function receives a table with the following fields:
- X=matrix: a MxN matrix, M number of patterns, N pattern size.
- \(\mathrm{K}=\) number: the number of components that you want to compute, \(\mathrm{K}<=\mathrm{N}\).
- max_iter=number: the maximum number of iterations computing every component. It is an optional parameter, by default it is max_iter=10000.
- epsilon=number the convergence criterion. It is an optional parameter, by default it is epsilon=1e-07.

The function returns three matrices:
- The T scores matrix, with size MxK.
- The P loads matrix, with size NxK.
- The R residuals matrix, with size MxN.

\section*{19.8 confusion_matrix}
```

stats.confusion_matrix

```

\section*{Chapter 20}

\section*{stats.MI package}

\subsection*{20.1 Introduction}

Package stats.MI could be loaded via the standalone binary, or in Lua with require("aprilann.stats.MI).
The table stats.MI contains functions useful to compute the Mutual Information between matrices of data. It has the following functions:
- number \(=\) stats.MI.entropy (matrix, histogram, levels=256) this function receives three optional arguments. The first two are related to the set of data from computing the entropy. One of them must be given, the other must be nil. The third argument is by default 256 , and is only useful if the matrix is given, and indicates the number of levels for the histogram computation.
- If the matrix argument is given, a histogram is computed to estimate the probability distribution of the data, using the given number of levels, 256 by default.
- If the histogram argument is given, the function takes this histogram as the source for the probability distribution estimation.
- MI,NMI = stats.MI.mutual_information(matrix1, matrix2, levels=256) this function computes the amount of information mutually shared by the given two matrices of data, using levels for the histogram computation. The two matrices will be reinterpreted as a linear sequence of data, so the must have exactly the same size, and is recommended both matrices to being a vector of data, so multi-dimensional feature vectors are not allowed. The function returns the Mutual Information, and the Normalized Mutual Information.
```

> m1 = matrix(1,10):linear(1)
> m2 = matrix(1,10)
> m2:slice({1,1},{1,5}):linear(2)
> m2:slice({1,6},{1,5}):linear(2)
> print(m1)
1 2 3 4 4 4 % 5

# Matrix of size [1,10] in row_major [0x260dae0 data= 0x260dbc0]

> print(m2)
2 \# Matrix of size [1,10] in row_major [0x260e280 data= 0x260de70]
> print(stats.MI.mutual_information(m1,m2))
2.321927794305 1.6989699041453

```

\section*{Chapter 21}

\section*{complex package}

\subsection*{21.1 Introduction}

Package complex could be loaded via the standalone binary, or in Lua with require("aprilann.complex).
The complex is a new kind of data added binded from \(\mathrm{C}++\), which could be used with matrixComplex and has available math operations in Lua and using CBLAS interface.

IMPORTANT as the complex data-type is a \(\mathrm{C}++\) object, it is available via a reference pointer, be careful because the assignation is done by reference, not by content.

\subsection*{21.2 Construction}

Exists two possible constructors:
```

> c = complex(2,-1) -- 2 is real part, -1 is imaginary part
> print(c)
2-1i
>
> -- the string is parsed in C++, worst performance than previous constructor
> c = complex("2+4i")
> print(c)
2+4i

```

\subsection*{21.3 Math operations}

The opreators ' \(==\) ', ' ','/','+','-' are defined to work with complex objects. If the other operand is a number, it is converted to a complex with only real part. If the other operand is a string*, it will be converted to a complex number using the constructor from string.

Besides previous operations, the following math methods are available:
- \(\operatorname{self}=\mathrm{c}: \operatorname{conj}()\) conjugates the given object. It is done in-place, so the object will be modified. Returns the caller object (self).
- real,imaginary \(=c: p l a n e()\) returns the real and imaginary part.
- number \(=c: r e a l()\) returns the real part of the number.
- number \(=c: i m g()\) returns the real part of the number.
- abs,angle \(=c: p o l a r()\) returns the abs and angle of its polar form.
- number \(=\mathrm{c}: \mathrm{abs}()\) returns the 2-norm of the caller complex number.
- number \(=c: a n g l e()\) returns the angle of its polar form.
- other_complex \(=c: \exp ()\) returns the exponential ( \(\left.e^{\wedge} z\right)\) of the caller complex number.
- number \(=c: s q r t()\) returns the square-root of the caller complex number.
```

>c1 = complex (1,2)
> c2 = complex (-4,-5)
> print(c1+c2)
-3-3i
> print(c1*c2)
6-13i
> print(c1-c2)
5+7i
> print(c1:exp(), c2:exp())
1.46869+2.47173i -0.0119719+0.0175633i
> print(c1:abs(), c2:abs())
2.2360680103302 6.403124332428

```

\subsection*{21.4 Other methods}
- other \(=c: c l o n e()\) produces a new complex instance which has the same content as the caller.

\section*{Chapter 22}

\section*{util package}

\subsection*{22.1 Introduction}

Package util could be loaded via the standalone binary, or in Lua with require("aprilann.util). This package is the most important and dangerous. It extends standard Lua tables with new functionalities, and adds several utilities at GLOBALs table.

List of utilities added to Lua for scripting purposes.

\subsection*{22.2 Functions}

Package util could be loaded via the standalone binary, or in Lua with require("aprilann.util).

\subsection*{22.2.1 Serialization and deserialization of objects}
22.2.1.1 util.serialize
```

str = util.serialize(obj)
util.serialize(obj, filename)
util.serialize(obj, stream)

```

\subsection*{22.2.1.2 util.deserialize}
```

obj = util.deserialize(str)
obj = util.deserialize(filename)
obj = util.deserialize(stream)

```
22.2.1.3 util.to_lua_string
```

str = util.to_lua_string(obj, format)

```

\subsection*{22.2.2 Functional programming extensions}

Lua ha been extended by the addition of new functions which works on the top of Lua iterators. Basic concepts as map, reduce, and filter has been implemented.

\subsection*{22.2.2.1 bind}
```

func = bind(function, ...)

```

Allow to freeze any of the positional arguments of any function. The arguments of bind can be nil, and the returned function would merge its arguments with the list given to bind filling nil gaps adequately.
```

> f = bind(math.add, 2)
> = f(4)
6
> f = bind(math.div, nil, 3)
> = f(6)
2

```

\subsection*{22.2.2.2 reduce}
```

whatever = reduce(function, initial_value, iterator)

```

The reduce function applies a function operator by pairs of values, the first argument is the accumulated value of the reduction until current iteration, and the second argument is value at current iteration. If the iterator returns two or more elements every time it is called, the second will be taken.
```

> value = reduce(math.min, math.huge, ipairs({4, 2, 1, 10}))
> print(value)
1
> value = reduce(function(acc,v) return acc*2+v end, 0, string.gmatch("01101", "." ))
> print(value)
13

```

\subsection*{22.2.2.3 apply}
```

apply(func, iterator)

```

Applies a function to all the elements produced by the iterator. The function is called passing all the elements returned by one iterator call.
```

> t = { "a", "c", 3, 2 }
> apply(function(i,v1,v2) print(i,v1,v2) end, multiple_ipairs(t,t))
a a
c c
3 3 3
4 2

```

\subsection*{22.2.2.4 map}
table = map(func, iterator)
Returns a table which is the result of apply the given function over all the items of the given iterator function.
```

> tmapped = map(bind(math.mul, 2), ipairs({1, 2, 3, 4}))
> print(table.concat(tmapped, " "))
2468

```

\subsection*{22.2.2.5 map2}
```

table = map2(func, iterator)

```

The same as the previous, but given the function the pair key, value.
```

> tmapped = map2(function(k,v) return k+v*2 end, ipairs({1, 2, 3, 4}))
> print(table.concat(tmapped, " "))
36912

```

\subsection*{22.2.2.6 mapn}
```

table = mapn(func, iterator)

```

The same as the previous, but given the function all the elements returned by the iterator at each iteration.
```

> tmapped = mapn(function(idx, ...) return table.pack(...) end,
>> multiple_ipairs({1, 2, 3, 4},{5, 6, 7, 8}))
> for i,v in ipairs(tmapped) do print(i, table.concat(v, " ")) end
1 15
2 26
3 37
4 8

```

\subsection*{22.2.2.7 filter}
table \(=\) filter (func, iterator)
Returns a table which contains only the elements produced by the iterator which were evaluated with true by the given func function. The function receives only one value.
```

> t = filter(function(v) return v%2 == 0 end, ipairs{1,2,3,4,5,6,7})
> print(table.concat(t, " "))
246

```

\subsection*{22.2.2.8 iterable_map}
```

another_iterator = iterable_map(func, iterator)

```

Returns an iterator which every time is called maps the given function func using the given iterator. It allows multiple returned values from the given iterator (map and map2 only allow pairs key,value).

Additionally, using coroutine.yield(...), the mapping function could return more than one set of values at each iteration, allowing the implementation of ConcatMap iterators.
```

> -- standard map using iterable_map
> t = { Lemon = "sour", Cake = "nice", }
> for ingredient, modifier, taste in iterable_map(function(a, b)
> return a:lower(),"slightly",b:upper()
> end, pairs(t)) do
> print(ingredient .." is ".. modifier .. " " .. taste)
> end
lemon is slightly SOUR
cake is slightly NICE
>
> -- ConcatMap iterator using iterable_map
t = { Lemon = "sour", Cake = "nice", }
> for ingredient, modifier, taste in iterable_map(function(a, b)
>> coroutine.yield(a:lower(),"very",b:upper())
>> return a, "slightly", b
>> end, pairs(t)) do
>> print(ingredient .." is ".. modifier .. " " .. taste)
>> end
cake is very NICE
Cake is slightly nice
lemon is very SOUR
Lemon is slightly sour

```

The following example uses this function to extract all the words contained in a file:
```

> for str in iterable_map(function(line)
>> for _,str in ipairs(string.tokenize(line)) do
>> coroutine.yield(str)
>> end
>> end, io.lines("AUTHORS.txt")) do
>> print(str)
> end
In
this
project
has
been
worked:
-
Salvador
España
Boquera
-
Jorge
Gorbe
Moya
-
Adrián
Palacios
Corella
-
Joan
Pastor
Pellicer

```
```

- 

Francisco
Zamora
Martínez

```

This function is taken from http://www.corsix.org/content/mapping-and-lua-iterators.
```

22.2.2.9 iterable_filter
another_iterator = iterable_filter(func, iterator)

```

Returns an iterator which every time is called filters using the given function func the elements produced by the given iterator. It allows multiple returned values from the given iterator.
```

> for v in iterable_filter(function(key,value) return value% %==0 end,
>> ipairs{1,2,3,4,5,6,7}) do
>> print(v)
>> end
2
4
6

```

\subsection*{22.2.2.10 iterator class}

The iterator class is developed to provide an easy and natural interface with previous and newer functions. The most important advantage is that iterator class relies always in Lua iterators, so, it is lazy in the way that the code is not executed until the iterator is traversed. iterator class is a wrapper of Lua iterators.

The following methods returns an iterator object or a Lua iterator:
- obj = iterator (Lua iterator): the constructor receives an iterator, as for example the output of ipairs function, and returns an instance of iterator class.
```

> it = iterator(ipairs{ 1, 2, 3})

```
- Lua iterator \(=\) obj \(: \operatorname{get}():\) returns the current state of the underlying Lua iterator.
- Lua iterator \(=\operatorname{obj}():\) the same as previous method.
```

> it = iterator(ipairs{ 1, 2, 3})
> for k,v in it() do print(k,v) end
1
2
3

```
- iterator \(=\) obj:map (func): this method is a wrapper of iterable_map function, and returns an instance of iterator class.
```

> it = iterator(ipairs{ 1, 2, 3}):map(function(k,v) return v*2 end)
> for v in it() do print(v) end

```
2
4
6
- iterator = obj:filter (func): this method is a wrapper of iterable_filter function, and returns an instance of iterator class.
```

it = iterator(range(1,50)):filter(function(n) return (n%10)==0 end)
> for v in it() do print(v) end
10
20
30
40
5 0

```
- iterator \(=\) obj:field(...): this method receives a list of keys. It expects the underlying iterator to produce a list of tables. It returns an iterator which filters all the tables in the list taken the values at given keys, and returns a flatten list of values. There is an example below the following method.
- iterator \(=\) obj:select(...): this method receives a list of numbers. It returns an iterator which selects only the output variables produced by the iterator at the given position numbers.
```

> layers = { { size=10 }, { size=100 } }
> iterator(ipairs(layers)):select(2):field("size"):apply(print)
10
100

```
- iterator \(=\) obj: enumerate(): enumerates the returned values, adding at first position a number.
```

> iterator(pairs{ a=4, b=3 }):enumerate():apply(print)
1 a 4
2 b 3

```
- iterator \(=\) obj:iterate (func): this method is an specialization of map method for applying Lua iterator functions to each element of obj. The given func is expected to return an iterator over the given element. It is useful to do things like word counting:
```

> out = iterator(io.lines("AUTHORS.txt")):
>> iterate(function(line) return string.gmatch(line, "[^\r\n\t ]+") end):
>> reduce(function(acc,w) acc[w] = (acc[w] or 0) + 1 return acc end,{})
> iterator(pairs(out)):apply(print)
has 1
Pastor 1
In 1
worked: 1
Palacios 1

- 5
España 1
Boquera 1
Joan 1
Francisco 1
Adrián 1
Martínez 1
been 1
Pellicer 1
Jorge 1

```
```

Zamora 1
Corella 1
this 1
Moya 1
Gorbe 1
Salvador 1
project 1

```
- iterator \(=\) obj:call (funcname, ...): this method is a map over all the values by calling the method funcname (a string) using the given arguments. Because it is a method, the first argument of funcname will be each iterator value.
```

> for k in iterator(ipairs({ "h", "w" })):select(2):call("toupper"):get() do
print(k)
end
H
W

```

The following methods are finalizers, so, they return a value, not an iterator:
- whatever = obj:reduce(func, initial_value): this method is a wrapper of reduce function.
```

> = iterator(range(1,50)):reduce(function(acc,a) return acc+a end, 0)
1275
> = iterator(range(1,50)):reduce(math.add, 0)
1275

```
- obj:apply(func): this method is a wrapper of apply function.
```

> iterator(range(1,50)):filter(function(n) return (n%10)==0 end):apply(print)

```
10
20
30
40
50
- string = obj: concat (sep1,sep2): concats all the elements using sep1 and sep2 strings. sep1 is used to concat the elements of one iterator call. sep2 is used to concat the elements between different iterations. By default, empty string will be used when sep1 and sep2 are nil. If only sep1 is given, therefore sep2=sep1.
```

> = iterator(range(1,50)):filter(function(n) return (n%10)==0 end):concat(" ")
10 20 30 40 50

```
- table \(=\) obj:table(): returns a table with all the iterator values, using as key the first produced value, and the rest as value. If only one value is produced, the table will be indexed as an array.
```

> t = { "one", "two", "three" }
> p = iterator(ipairs(t)):map(function(k,v) return v,k end):table()
> iterator(pairs(p)):apply(print)
one 1
two 2
three 3

```

Using objects of this class, it is possible to produce code like this:
```

-- This example computes the dot product of two array tables. math.mul and math.sum are
-- auxiliary functions implemented in APRIL-ANN for the fast development of reductions.
> v = iterator(multiple_ipairs({1,2,3},{4,5,6})):select(2,3):
>> map(math.mul):
>> reduce(math.add, 0)
> print(v)
32
>
> -- The following code is equivalent without using iterator class
> v = reduce(function(a,b) return a+b end, 0,
>> iterable_map(function(k,a,b) return a*b end,
>> multiple_ipairs({1,2,3},{4,5,6})))
> print(v)
32

```

\subsection*{22.2.3 Basic functions}

\subsection*{22.2.3.1 april_list}
```

april_list(table)

```

This function is this piece of code: for \(i, v\) in pairs(table) do print(i,v) end

\subsection*{22.2.3.2 april_help}
april_help(obj)
Shows the documentation of the object given as argument. If the object is a class, you can access to instance methods by using . . operator:
```

> -- using .. operator to access instance method get_state_table
> april_help(trainable.train_holdout_validation.."get_state_table")
method Returns the state table of the training
description: Returns the state table of the training

```
outputs:
            best Best trained model
            best_epoch Best epoch
        best_val_error Best epoch validation loss
        current_epoch Current epoch
            last Last trained model
        train_error Train loss
        validation_error Validation loss
> -- showing help of the given class
> april_help(trainable.train_holdout_validation)
ID: trainable.train_holdout_validation
class Training class using holdout validation
description: This training class defines a train_func which follows a training
```

schedule based on validation error or in number of epochs. Method
execute receives a function which trains one epoch and returns the
trainer object, the training loss and the validation loss. This
method returns true in case the training continues, or false if the
stop criterion is true.

```

\subsection*{22.2.3.3 april_dir}
```

april_dir(string)

```

This is a the same has april_help, but less verbose.

\subsection*{22.2.3.4 luatype}
luatype(whatever)
The original type function is replaced by APRIL-ANN with a new function which returns the object id if it is a class instance. If you need to know the exact type given by Lua, this function is what you need.

\subsection*{22.2.3.5 check__version}
```

boolean = check_version(major,minor,commit)

```

Checks if the version of the software is major.minor with the given commit, returning true if success, and returning false and showing a message in stderr otherwise.

\subsection*{22.2.3.6 april__print__script__header}
```

april_print_script_header(arg, file=stdout)

```

This function writes at the given file (or stdout if not given) the given arg table (normally the arg received by the script), besides information about the HOST where the script is executed and the current DATETIME:
```

> april_print_script_header({ [0]="hello" })

# HOST: django

# DATE: dv jul 5 14:16:53 CEST 2013

# CMD: hello

```

\subsection*{22.2.3.7 multiple_ipairs}
```

iterator,s,v = multiple_ipairs(...)

```

Returns an iterator which traverses a several number of tables. If they don't have the same size, the remaining elements will be nil, ensuring that in all the iterations the number of returned elements is equals to the maximum size of given tables.
```

> for i,a,b,c in multiple_ipairs({1,2,3,4},{1,2},{3,4,5}) do print(i,a,b,c) end
1 1 1 3
2 2 2 4
3 3 nil 5
4 4 nil nil

```

\subsection*{22.2.3.8 multiple__unpack}
```

... = multiple_unpack( [table1, [table2, [...]]] )

```

Allow to unpack multiple tables together, one at a time, and in a sequential fashion.
```

> print( multiple_unpack( {1,2,3}, {4,5}, {6,7,8,9} ) )
1

```

\subsection*{22.2.3.9 glob}
table = glob(...)
Returns a list of filenames which match all the wildcard arguments received by the function.
```

> -- prints the name of all the files which have.lua or .h extensions
> for i,filename in ipairs(glob("*.lua", "*.h")) do print(filename) end

```

\subsection*{22.2.3.10 parallel_foreach}
```

results = parallel_foreach(num_processes, iterator or array or number, func)

```

Executes a function over the given iterator (instance of class iterator), array table or the given number of repetitions, but forking the calling process in num_processes, improving the performance of the operation. NOTE that the parallelization is performed forking the caller process, so all child processes could access to the memory variables assigned and allocated before the fork, but they don't share the memory, it will be copied on write.
```

> t = map(function(v)return v end, 10)
> parallel_foreach(2, t, function(value) print(value*100) end)
200
4 0 0
6 0 0
800
1000
100
300
5 0 0
7 0 0
900

```

Additionally, if the function returns any value, this function would serialize the output of each process to a temporal file, and at the end, deserialize the content to the original process. This is useful when the overhead of serialization-deserialization procedure is less than the computing power needed by the processes.
```

> ret = parallel_foreach(2, 10, function(value) return value*100 end)
> print(table.concat(ret, "\n"))
100
200
300
400
5 0 0
600

```

700
800
900
1000

You can use iterators to control which data receives the called function:
```

> ret = parallel_foreach(2, iterator(ipairs{4,3,2,1}),
function(key,value) return key+value*100 end)
> print(table.concat(ret, "\n"))
4 0 1
302
203
104
>
> ret = parallel_foreach(2, iterator(ipairs{4,3,2,1}),
function(key,value) return key,key+value*100 end)
> print(table.tostring(ret))
{{1,401,["n"]=2},{2,302,["n"]=2},{3,203,["n"]=2},{4,104,["n"]=2}}

```

\subsection*{22.2.3.11 clrscr}
clrscr ()
Clears the screen.

\subsection*{22.2.3.12 printf}
printf(...)
Equivalent to C printf function.

\subsection*{22.2.3.13 fprintf}
fprintf(file,...)
Idem, but for the C fprintf function.

\subsection*{22.2.3.14 range}
range(inf,sup, step=1)
This function returns an iterator which starts at inf, ends at sup, and performs steps of the given step size.
```

> for i in range(10,20,2) do print(i) end

```
10
12
14
16

\subsection*{22.2.3.15 util.version}
major, minor, commit = util.version()
Returns the version numbers.
22.2.3.16 util.omp__set__num_threads
util.omp_set_num_threads(number)
Modifies the number of threads for OMP.
> util.omp_set_num_threads(8)
22.2.3.17 util.omp_get_num_threads
```

number = util.omp_get_num_threads()

```

Returns the number of threads used by OMP.
```

> print(util.omp_get_num_threads())

```
8

\subsection*{22.2.4 Math table extensions}

\subsection*{22.2.4.1 math.add}
```

number = math.add( a ,b )

```

Returns the result of \(\mathrm{a}+\mathrm{b}\).
```

> = math.add(2,3)
5

```

\subsection*{22.2.4.2 math.sub}
```

number = math.sub( a, b )

```
Returns the result of \(\mathrm{a}-\mathrm{b}\).
\(>=\) math \(\cdot \operatorname{sub}(2,3)\)
-1

\subsection*{22.2.4.3 math.mul}
```

number = math.mul( a, b )

```

Returns the result of \(\mathrm{a} * \mathrm{~b}\).
```

> = math.mul(2,3)
6

```

\subsection*{22.2.4.4 math.div}
```

number = math.div( a, b )

```

Returns the result of \(\mathrm{a} / \mathrm{b}\).
```

> = math.div(2,3)
0.66666666666667

```

\subsection*{22.2.4.5 math.eq}
number \(=\) math.eq( \(\mathrm{a}, \mathrm{b})\)
Returns the result of \(\mathrm{a}==\mathrm{b}\).

\subsection*{22.2.4.6 math.lt}
number \(=\) math.lt ( \(\mathrm{a}, \mathrm{b}\) )
Returns the result of \(\mathrm{a}<\mathrm{b}\).

\subsection*{22.2.4.7 math.le}
```

number = math.le( a, b )

```

Returns the result of \(\mathrm{a}<=\mathrm{b}\).

\subsection*{22.2.4.8 math.gt}
```

number = math.gt( a, b )

```

Returns the result of \(\mathrm{a}>\mathrm{b}\).

\subsection*{22.2.4.9 math.ge}
number \(=\) math.ge( \(\mathrm{a}, \mathrm{b})\)
Returns the result of \(\mathrm{a}>=\mathrm{b}\).

\subsection*{22.2.4.10 math.land}
number \(=\) math. \(\operatorname{land}(\mathrm{a}, \mathrm{b})\)
Returns the result of \(a\) and \(b\).

\subsection*{22.2.4.11 math.lor}
number = math. \(\operatorname{lor}(\mathrm{a}, \mathrm{b})\)
Returns the result of a or b .

\subsection*{22.2.4.12 math.lnot}
```

number = math.lnot( a )

```

Returns the result of not a.

\subsection*{22.2.4.13 math.round}
```

number = math.round(number)

```

Returns the rounding integer number for the given real number.
```

> = math.round(4/3)
1

```

\subsection*{22.2.4.14 math.clamp}
```

number = math.clamp(value,lower,upper)

```

Clamp the given value to be between [lower, upper], if it is out of the range, it is forced to be at the limit.
```

> print(math.clamp(15,3,6), math.clamp(0,3,6), math.clamp(4,3,6))
6 3 4

```

\subsection*{22.2.5 String table extensions}

\subsection*{22.2.5.1 Operator \%}

Inspired in penlight library, a Python-like operator \% has been defined. It allows to produce formatted strings, and implements map-like substitutions:
```

> = "$obj1 = %.4f\n$obj2 = %.4f" % {20.4, 12.36, obj1="cat", obj2="dog"}
cat = 20.4000
dog = 12.3600

```

\subsection*{22.2.5.2 truncate}
```

string = str:truncate(columns, prefix)

```

\subsection*{22.2.5.3 basename}
```

string = path:basename()

```

Returns the basename (the last filename) of a given path.
```

> print(("/a/path/to/my/file.txt"):basename())
file.txt

```

\subsection*{22.2.5.4 dirname}

Returns the path, removing the basename.
```

> print(("/a/path/to/my/file.txt"):dirname())
/a/path/to/my/

```

\subsection*{22.2.5.5 remove__extension}
```

string,string = path:remove_extension()

```

Removes the extension of the filename in the given path, and returns the path without the extension and the extension string.
```

> print(("/a/path/to/my/file.txt"):remove_extension())
/a/path/to/my/file txt

```

\subsection*{22.2.5.6 get_extension}
string = path:get_extension()

Returns only the extension of the given path string.
```

> print(("/a/path/to/my/file.txt"):get_extension())
txt

```

\subsection*{22.2.5.7 get_path}
```

string = path_with_filename:get_path(sep)

```

Synonim of dirname().

\subsection*{22.2.5.8 lines_of}
string = str:lines_of()
Returns an iterator function which traverses the given string splited by newline character.
```

> for line in ("one\ntwo"):lines_of() do print(line) end
one
two

```

\subsection*{22.2.5.9 chars_of}
iterator = str:chars_of()
Returns an iterator function which traverses the given string splited by chars.
```

> for i,ch in ("one two"):chars_of() do print(i,ch) end
|
2 n
3 e
4
t
w
0

```

\subsection*{22.2.5.10 tokenize}
```

table = str:tokenize(sep=' \t\n\r')

```

Returns a table with the string tokenized using the given sep set of characters.
```

> for i,token in ipairs((" one\ntwo\tthree four"):tokenize("\t\n ")) do print(i,token) end
1 one
2 two
3 three
4 four
> for i,token in ipairs(string.tokenize(" one\ntwo\tthree four", "\n ")) do print(i,token) end
1 one
2 two three
3 four

```

\subsection*{22.2.5.11 tokenize__width}
```

table = str:tokenize_width(width=1)

```

\subsection*{22.2.5.12 join}

The string.join function is equivalent to Lua table. concat function.

\subsection*{22.2.6 Table table extensions}

\subsection*{22.2.6.1 table.insert}
```

table = table.insert(table,value)

```

The original table.insert function was replaced with a new one which returns the table given as first argument. It is combinable with reduce function.

\subsection*{22.2.6.2 table.luainsert}
table.luainsert(table,value)
The original Lua table.insert function.

\subsection*{22.2.6.3 table.clear}
```

table.clear(table)

```

Removes all the elements of a table, but it doesn't forces Lua to deallocate the memory. This function is useful if you want to reuse a table variable several times inside a loop, it is better to clear the table than to allocate a new one table.
```

> t = {}
> for i=1,1000 do table.clear(t) STUFF USING t end

```

\subsection*{22.2.6.4 table.unpack_on}
```

table.unpack_on(table, dest_table)

```

This function puts the fields of the given table at the table dest_table. It is useful to put table fields on the global scope of Lua.
```

> print(a, b, c)
nil nil nil
> t = { a=1, b=2, c=3 }
> table.unpack_on(t, _G)
> print(a, b, c)
1 2 3

```

\subsection*{22.2.6.5 table.invert}
```

table = table.invert(table)

```

Returns the table resulting from the inversion of key,value pairs of the given table argument.
```

> t = { "a", "b", "c" }
> t_inv = table.invert(t)
> for i,v in pairs(t_inv) do print(i,v) end
a 1
c 3
b 2

```

\subsection*{22.2.6.6 table.slice}
```

table = table.slice(t, ini, fin)

```

Returns from the given table the slice of elements starting at ini and finishing at fin.
```

> t = { 1, 2, 3, 4, 5, 6, 7, 8, 9 }
> print(unpack(table.slice(t, 2, 4)))
2 3 4

```

\subsection*{22.2.6.7 table.search__key_from__value}
```

key = table.search_key_from_value(table,value)

```

This function searchs a value at the given table and returns its key. If the value is repeated (obviously using different keys), any of the possible keys will be returned, but it is not possible to determine which one.
```

> print(table.search_key_from_value({ a=15, b=12 }, 12))
b

```

\subsection*{22.2.6.8 table.reduce}
```

whatever = table.reduce(table,function,initial_value)

```

Equivalent to reduce(function, initial_value, pairs(table)).

\subsection*{22.2.6.9 table.imap}
table = table.imap(table,function)
Equivalent to map(function, ipairs(table)).

\subsection*{22.2.6.10 table.map}
```

table = table.map(table,function)

```

Equivalent to map(function, pairs(table)).

\subsection*{22.2.6.11 table.imap2}
```

table = table.imap2(table,function)

```

Equivalent to map2(function, ipairs(table)).

\subsection*{22.2.6.12 table.map2}
table \(=\) function table.map2(table,function)
Equivalent to map2(function, pairs(table)).

\subsection*{22.2.6.13 table.ifilter}
table = table.ifilter (table,function)
This functions traverses the given table as an array (using ipairs function), and returns a new table which contains only the elements where the given function returns true. The function is called passing the pair key, value as two arguments.

\subsection*{22.2.6.14 table.filter}
```

table = table.filter(table,function)

```

Idem as the previous one but for general tables (using pairs functions).

\subsection*{22.2.6.15 table.join}
table = table.join(t1, t2)
Returns a table which is the concatenation of the two given tables.
```

> t = table.join({1,2,3}, {10,11,12})
> print(table.concat(t, " "))
123101112

```

\subsection*{22.2.6.16 table.deep_copy}
```

table = table.deep_copy(table)

```

Returns a table which is a deep copy of the Lua data-values contained at the given table, and a shallow copy (copied by reference) of its C++ references.

\subsection*{22.2.6.17 table.linearize}
```

table = table.linearize(table)

```

Converts an unsorted dictionary in an array, throwing away the keys. The order of the array is not determined.

\subsection*{22.2.6.18 table.tostring}
string = table.tostring(table)
This function converts the given table to a string which contains the table values, and which could be loaded as a Lua chunk. It only works with tables which doesn't contain \(\mathrm{C}++\) references.
```

> t = { 1, 2, a={ ["foo"] = "bar" } }
> print(table.tostring(t))
{
[1]=1,[2]=2,["a"]=
{
["foo"]="bar"
}
}

```

\subsection*{22.2.6.19 table.max}
```

number,index = table.max(table)

```

This function returns the maximum value and the index of the key which contains it. The table is traversed using pairs function.

\subsection*{22.2.6.20 table.min}
```

number,index = table.min(table)

```

This function returns the minimum value and the index of the key which contains it. The table is traversed using pairs function.

\subsection*{22.2.6.21 table.argmax}
index \(=\) table. \(\operatorname{argmax}(t a b l e)\)
This function is equivalent to table.max returning only the index.

\subsection*{22.2.6.22 table.argmin}
index = table.argmin(table)
This function is equivalent to table.min returning only the index.

\subsection*{22.2.7 Io table extensions}
22.2.7.1 io.uncommented_lines
iterator = io.uncommented_lines( [filename] )
Returns a function iterator which traverses the given filename (if not given, it uses io.stdin), removing the lines which begins with \# symbol.
```

> for line io.uncommented_lines() do STUFF end

```

\subsection*{22.3 Miscellaneous classes}

\subsection*{22.3.1 util.stopwatch}
util.stopwatch

\subsection*{22.3.2 util.vector_uint}
util.vector_uint

\subsection*{22.3.3 util.vector_float}
util. vector_float

\section*{Chapter 23}

\section*{gzio package}

\subsection*{23.1 Introduction}

Package gzio could be loaded via the standalone binary, or in Lua with require("aprilann.gzio).

\section*{23.2 gzio class, GZip files}

NOTE that io.open is overwritten by APRIL-ANN to automatically open gzipped files by using gzio class, if the filename has .gz extension.

The gzio class is compatible with standard Lua file. See Lua documentation for more details
- obj \(=\) gzio.open(path, mode="r") constructs the object and opens the given path using the given mode.
- obj = io.open(path,mode="r") opens the given path using the given mode, and returns a gzio object if the file has .gz extension, otherwise it returns a Lua file.
- obj:close() closes the file.
- obj:flush() flushes the file.
- position = obj:seek(whence="cur",offset=0) moves the cursor from the given base position whence plus the given offset. The whence could be "cur" or "set", the "end" value is forbidden in ZLib. It returns the position of the cursor at the file.
- value,... = obj:read(format="*l", ...) reads a sequence of values from the file, following the given format strings.
- "*l" reads a line.
- "* \(\mathrm{n} "\) reads a number.
- "*a" reads the whole file.
- NUMBER reads a string with a maximum of NUMBER bytes.
- obj:write(value, ...) write the given sequence of values to the file. A valid value is a string or a number.
- iterator \(=\) obj:lines (...) returns an iterator which read by lines following the given values, by default "*l". The file is not closed at end.
- iterator \(=\) io.lines (path, . .) returns an iterator which traverse the given path by lines, following the given values, by default "*l". Read Lua documentation for details. This function uses gzio object if the file has .gz extension, otherwise it uses the standard io.lines.

\section*{23.3 tar class, TAR files}

\section*{Chapter 24}

\section*{Image package}

\subsection*{24.1 Introduction}

This package is available with require("aprilann.Image").
Two globals are declared in this package: Image and ImageRGB. Both classes represent its internal data using floats, in the case of Image with one float, in the case of ImageRGB with 3 floats (Red, Green, Blue). So, usually 8 bits per color images will be transformed to be the color \(0=0.0\) and the color 255=1.0.

\subsection*{24.2 Serialization and deserialization}

Images cannot be serialized as a Lua object into a .lua filename using util.serialize() and util. deserialize() functions. Instead of that, it is possible to write images into png, tiff or jpeg files by using the package ImageIO. This package allows to write Image or ImageRGB images.

\subsection*{24.3 Visualization}

A tool module has been deployed to facilitate visualization of images and matrices. It depends on lgi binding library for Lua 5.2 , and uses the GTK binding. In order to do the require "tools.lgi.gtk" you need to have the APRIL-ANN ROOT directory in your package. path Lua variable, or in your LUA_PATH environment variable. By default, the current directory is included, so if you execute the require being your working directory the APRIL-ANN GIT root directory, it will work. In any case, NEVER add the april_tools directory to the LUA_PATH, because the lgi module will collide with the tools.lgi module.
```

> gtk = require "tools.lgi.gtk"
> gtk.show("sheared.png")

```

If it doesn't work, try add the APRIL-ANN ROOT directory to the package. path variable.
```

> package.path = "YOUR_APRIL_ANN_PATH/?.lua;" .. package.path
> gtk = require "tools.lgi.gtk"
> gtk.show("sheared.png")

```

\subsection*{24.3.1 gtk.show(img1, img2, ...)}

This function allows to visualize images using GTK library. It receives a variable number of arguments, and every argument will be displayed in a different window. Every argument could be:
- A filename, opening the contained image.
- A matrix, which needs to be bi-dimensional. It will be converted to an Image and then showed.
- An Image or ImageRGB.

Note that the Lua command shell will be blocked after executing GTK main loop. Any of the created windows has an exit button to allow closing the GTK main loop.

\subsection*{24.4 Image class}

The Image class allows to work with gray-scale images. Every image contains an underlying matrix instance (floats).

\subsection*{24.4.1 Constructor: img = Image(matrix)}

The constructor receives a matrix where the image is contained. This matrix must be simple, that is, contiguous in memory, and in row_major. Given a matrix with data, it is possible to load an Image with:
```

> m = matrix(100,100)
> -- make a gradient
> for sw in m:sliding_window():iterate() do sw:linear():adjust_range(0,1) end
> -- constructor for Image
> img = Image(m)
> = img

# Image 100x100+0+0 [0x2490810 data= 0x25843e0]

> -- you can see the image writing it with ImageIO or using the gtk module
> ImageIO.write(img, "gradient.png")

```

\subsection*{24.4.2 Image \(=\) img:crop(string)}

This method allows to select a portion of an Image, and returns a new instance which references the given portion. The crop is given by using a string (like in convert command), with the following format: <width>x<height>\{+-\}<x>\{+-\}<y>.
```

> img2 = img:crop("20x20+10+10")
> = img2

# Image 20x20+10+10 [0x2490810 data= 0x25843e0]

```

\subsection*{24.4.3 Image = img:crop(width, height, offsetx, offsety)}

Similar to previous one, but given the crop using four arguments.
```

> img2 = img:crop(20, 20, 10, 10)
> = img2

# Image 20x20+10+10 [0x2490810 data= 0x25843e0]

```

\subsection*{24.4.4 matrix = img:matrix()}

This method returns the underlying matrix. Be careful with this method, the memory is shared between the Image object and the returned matrix object.
```

> m2 = img:matrix()
> m

# Matrix of size [100,100] in row_major [0x2490810 data= 0x25843e0]

> = m -- the matrix references the original

# Matrix of size [100,100] in row_major [0x2490810 data= 0x25843e0]

```

\subsection*{24.4.5 width, height, offsetx, offsety = img: geometry()}

This method returns the geometry information of the image.
```

> = img2:geometry()
20 20 10 10

```

\subsection*{24.4.6 number \(=\) img:getpixel ( \(\mathrm{x}, \mathrm{y}\) )}

This method returns the given position ( \(\mathrm{x}, \mathrm{y}\) ) pixel value.

\subsection*{24.4.7 img:putpixel(x,y,number)}

This method assigns the given value at the given ( \(\mathrm{x}, \mathrm{y}\) ) pixel position.

\subsection*{24.4.8 Image \(=\) img:clone()}

This method returns a deep-copy of the caller object.

\subsection*{24.4.9 matrix = img:projection_h()}

This method returns the horizontal projection of the caller object.

\subsection*{24.4.10 matrix = img:projection_v()}

This method returns the vertical projection of the caller object.

\subsection*{24.4.11 Image = img:shear_h(angle, [, units="rad" [, WHITE=0.0] ] )}

This method returns an Image which is a shear transformation with the given angle. Optionally, a second argument could be given indicating with the string rad, deg or grad the angle unit, by default it is rad. The thrird argument is also optional, and it indicates which pixel value is taken as white color, by default is 0.0 .
```

> img_sh = img:shear_h(0.1)
> ImageIO.write(img_sh, "sheared.png")

```

\subsection*{24.4.12 img:shear_h_inplace(angle, [, units="rad" [, WHITE=0.0 ] ] )}

This method applies the same transformation as the img:shear_h(...), but instead of returning a new Image, the transformation is performed in-place.

\subsection*{24.4.13 w,h,x,y = img:min_bounding_box(threshold)}

This method returns the bounding box of the caller object, using threshold for deciding when a value is considered as background or not.

\subsection*{24.4.14 img: copy (Image, dest_x, dest_y)}

This method copies the given Image in the given (dest_x, dest_y) position of the caller object.

\subsection*{24.4.15 Image \(=\) img:substract(Image)}

This method applies image substraction.

\subsection*{24.4.16 img:threshold(low, high)}

This method transforms in-place the caller object with the given range for black/white thresholding.

\subsection*{24.4.17 Image \(=\) img:rotate 90 cw(param)}

This method returns a new Image which is a rotation of \(90^{\circ}\) in clock-wise direction (if param=1) or in counter-clock-wise (if param=-1) of the caller object.

\subsection*{24.4.18 Image \(=\) img:invert_colors()}

This method returns an image with the colors inverted.
```

24.4.19 Image = img:remove_blank_columns()
24.4.20 Image = img:add_rows(top, bottom, value)
24.4.21 Image = img:convolution5x5(table [, default_value ])
24.4.22 Image = img:resize(x,y)
24.4.23 Image,x,y = img:affine_transform(AffineTransform2D, default_value)
24.4.24 ImageRGB = img:to_RGB()
24.4.25 matrix = img:comb_lineal_forward(x, y, w, h, w2, h2, LinearCombConFloat)

```

\subsection*{24.5 ImageRGB class}

This class is an instantiation of the same C++ template used for Image class. Both classes has similar methods.

\subsection*{24.5.1 Constructor: ImageRGB = ImageRGB(matrix)}

ImageRGB class could be loaded from a matrix with 3 dimensions. The last dimension of the matrix has size 3 for the componentes Red, Green, Blue. Be careful with this constructor, the memory is shared between the ImageRGB object and the given matrix object.
```

> img_rgb = ImageRGB(matrix(100,100,3):linear())
> = img_rgb

# ImageRGB 100x100+0+0 [0x2535700 data= 0x251fc40]

```

\subsection*{24.5.2 Methods shared with Image class}

The following methods are shared between both classes, and their has the same interface:
- ImageRGB = img_rgb:crop(string)
- ImageRGB = img_rgb:crop(width, height, offsetx, offsety)
- width, height, offsetx, offsety = img_rgb:geometry()
- \(\mathrm{r}, \mathrm{g}, \mathrm{b}=\) img_rgb:getpixel( \(\mathrm{x}, \mathrm{y})\)
- img_rgb:putpixel(x,y, r,g,b)
- ImageRGB = img_rgb:clone()
- ImageRGB = img_rgb:shear_h(angle, [, units="rad" [, WHITE=0.0 ] ] )
- img_rgb:shear_h_inplace(angle, [, units="rad" [, WHITE=0.0] ] )
- img_rgb:copy (ImageRGB, dest_x, dest_y)
- ImageRGB = img_rgb:rotate90cw(param)
- ImageRGB = img_rgb:invert_colors()
- ImageRGB = img_rgb:convolution5x5(table [, r,g,b ])
- ImageRGB = img_rgb:resize(x,y)
- ImageRGB, \(\mathrm{x}, \mathrm{y}=\) img_rgb:affine_transform(AffineTransform2D, \(\mathrm{r}, \mathrm{g}, \mathrm{b}\) )

\subsection*{24.5.3 matrix = img_rgb:matrix()}

This method returns the underlying matrix. Be careful with this method, the memory is shared between the ImageRGB object and the returned matrix object.

\subsection*{24.5.4 Image = img_rgb:to_grayscale()}

This method returns an instance of Image, transforming the 3 color components into a gray component.

\subsection*{24.6 Useful examples}

A usual situation is to load a matrix from a PNG image (in RGB color, with \(0=\) BLACK, and \(1=\) WHITE), but transform it to train ANNs in gray-scale with \(1=\) BLACK and \(0=\) WHITE. This could be done by the following code:
```

> img_matrix = ImageIO.read(filename):to_grayscale():invert_colors():matrix()

```

\section*{Chapter 25}

\section*{ImageIO package}

\subsection*{25.1 Introduction}

This package is avaialable as require ("aprilann.ImageIO").
ImageIO package implement functions for read/write of images in any supported format. Currently PNG and TIFF formats are supported.

\subsection*{25.2 Functions}

\subsection*{25.2.1 ImageRGB = ImageIO.read ( filename [, img_format] )}

This function allows to read an image from a given filename. It returns an instance of Image class. The img_format is optional, if not given, it will be extracted from the extension of the given filename. If given, it must be a string like png, tiff or tif. More formats will be supported in the future.

\subsection*{25.2.2 ImageIO.write( Image|ImageRGB, filename [, img_format] )}

This function allows to write an image into a given filename. The img_format is optional, if not given, it will be extracted from the extension of the given filename. If given, it must be a string like png, tiff or tif. More formats will be supported in the future.

\section*{Chapter 26}

\section*{AffineTransform2D package}

\subsection*{26.1 Introduction}

This package is avaialable as require("aprilann.AffineTransform2D").

\subsection*{26.2 AffineTransform2D class}

\subsection*{26.2.1 Constructor}
> AffineTransform2D()
> AffineTransform2D(matrix)
26.2.2 obj = obj:accumulate(other)
26.2.3 obj = obj:rotate (angle [, center_x, center_y ])
26.2.4 obj = obj:scale(sx, sy)
26.2.5 obj = obj:translate(x, y)
26.2.6 obj = obj:shear (angle_x, angle_y)
26.2.7 dstx, dsty \(=\) obj:transform(x, y)

\section*{Chapter 27}

\section*{class package}

\subsection*{27.1 Introduction}

Package class is a copy of the code avaiable at Lua OOP-iter for deploying OOP to Lua. It could be loaded by using require "aprilann.class", or if you have installed the Lua OOP-iter module, by doing class = require "oop-iter.class".

See test-class.lua file for an example of how to use this package. More updated version of this documentation is in Lua OOP-iter README.md, at class module section.

\subsection*{27.2 Description}

The class module implements OOP for Lua in a similar way as luabind does for \(\mathrm{C}++\) classes. So, the class module functions are compatible with it. The OOP is implemented by defining several tables for each desired class. Every class has a name, which allow to store it into a weak table in order to retrieve the class by its name in any moment. A class is defined by doing:
```

class_table, methods_table = class('myClassName'[, parent_class_table[, class_table]])

```

Two tables are returned as result of this call, the class_table which allows to construct instances by using the class_table as a function (it has implemented the __call metamethod), and a methods_table where instance methods must be defined. Class methods will be defined into class_table, and special names constructor/destructor allow to define the behavior of the object at these specific stages. So, the first is to define a constructor and a destructor (NOTE: both are optional):
```

class_table:constructor(whatever) self.blah = whatever end
class_table:destructor() free_resource(self.blah) end

```

In the same way, instance methods will be defined in methods_table:
methods_table:my_method() return self.blah end

Additionally, instance metamethods can be defined using the class.extend_metamethod function. Be carefule, __gc and __index metamethods are defined by default and them cannot be modified, any change will produce an unexpected behavior:
```

class.extend_metamethod(class_table, "__tostring", function() print("foo") end)

```

Looking with more detail inside the architecture, the class (. . .) function call defines the following hierarchy of tables:
```

class_table = {
constructor = default_constructor, -- it does nothing
destructor = default_destructor, -- it does nothing
-- the meta_instance table contains the metatable of instance objects
meta_instance = {
id = class_name_string,
cls = class_table_reference,
__tostring = default_tostring_metamethod, -- it is safe to be overwritten
__index = methods_table, -- the table where instance methods are defined
__gc = default_gc_metamethod,
}
}
-- class_table metatable contains:
{
id = class_name .. " class",
parent = parentclass, -- if given any
__tostring = default_tostring_metamethod,
__concat = default_concat_metamethod,
__call = constructor_call,
}

```

The class (. . .) function call returns first the class_table and second the class_table.meta_instance.__index field, letting the user to define class methods and instance methods there. By default constructor and destructor functions does nothing, and they are implemented at class_table.constructor and class_table.destructor fields. class_table.meta_instance table can be safety modified by calling to class.extend_metamethod(...), or writing non-safety manual changes into class_table.meta_instance.

\subsection*{27.2.1 Simple inheritance}

Simple inheritance has been implemented by defining a metatable for the class_table.meta_instance.__index table. Having a class table myClass1, you can define the class myClass2 as a child of previous one by writing:
```

> -- parent class
> myClass1,myClass1Methods = class("myClass1")
> myClass1:constructor(...) whatever stuff here end
> -- derived or child class
> myClass2,myClass2Methods = class("myClass2", myClass1)
> myClass2:constructor(...) myClass1.constructor(self, ...) more stuff here end

```

Note that parent constructor call is not made by default, and myClass2:constructor calls explicitly myClass1.constructor function passing the self reference. In this way, whatever construction stuff done in myClass1 will be done for myClass2. It is not mandatory to do this, but in many cases it will be helpful. However, you can build myClass2 instances in whatever way you want if the result is compatible with the methods inherited from myClass1.
myClass2Methods can overwrite or not methods defined at myClass1Methods. Non overwritten methods will be delegated calling myClass1 implementation, so be careful to ensure both objects are compatible.

Destructors are called following the hierarchy, first child destructor and after the parent class.

\subsection*{27.3 Reference}

The following public functions are available:

\subsection*{27.3.1 object \(=\) class \((\) name \([\), parent__class[, class__table]] \()\)}

Creates a class table with a given class_name. It receives an optional parent class to implement simple inheritance. It returns the class table; another table which will contain the methods of the object. Constructor and destructor methods will be declared into the class table as class_name:constructor(...) and class_name:destructor(). Additionally, a third optional argument is given, which allows to give a predefined class_table, useful is you want to make global instead of local variables, or to convert into a class an existent table.
```

> -- a simple class with name cls1
> cls1,cls1_methods = class("cls1")
> -- a derived class from cls1
> cls2,cls2_methods = class("cls2")
> -- a nested class defined into cls2 table
> cls2.nested1 = {}
> nested1,nested1_methods = class("cls2.nested1", nil, cls2.nested1)
> -- a derived nested class
> cls2.nested2 = {}
> nested2,nested2_methods = class("cls2.nested2", cls2.nested1, cls2.nested2)

```

A class_name cannot be used two times, that is, a class can't be redefined. If you need to redefine a class, use class.forget (class_name) before. Otherwise the following error message will be displayed:
```

> class("cls1")
> class("cls1")
./oop-iter/class.lua:40: cls1 class name exists
stack traceback:
[C]: in function 'assert'
./oop-iter/class.lua:40: in function 'register_class_table'
./oop-iter/class.lua:289: in function 'class'
stdin:1: in main chunk
[C]: in ?

```

\subsection*{27.3.2 boolean \(=\) class.is_a(object, class_table)}

Predicate which returns true if a given object instance is a subclass of a given Lua class table.
```

> cls1,cls1_methods = class("cls1")
> cls2,cls2_methods = class("cls2")
> cls3,cls3_methods = class("cls3", cls1)
> cls3 = cls3()
> = class.is_a(o1, cls1)
true
> = class.is_a(o1, cls2)
false
> = class.is_a(o1, cls3)
true

```

\subsection*{27.3.3 super_class_table \(=\) class.super(class_table)}

Returns the super class table of a given derived class table. Throws an error if the given class has not a super class.
```

> cls1,cls1_methods = class("cls1")
> cls2,cls2_methods = class("cls2", cls1)
> = ( class.super(cls2) == cls1 )
true

```

\subsection*{27.3.4 class_table \(=\) class.of(object)}

Returns the class table of the given object instance. In case the given parameter is a Lua value but not an object, it returns nil. So, this method can be used also to ask if a Lua value is or not an object.
```

> cls1,cls1_methods = class("cls1")
> o = cls1()
> = ( class.of(o) == cls1 )
true
> = class.of( {} )
nil
> = class.of( 5 )
nil

```

\subsection*{27.3.5 class.extend(class_table, key, value)}

Extends the given class table with the addition of a new key=value pair into the object instance table. It throws an error if the 1st parameter is not a class table.
```

> cls1,cls1_methods = class("cls1")
>oo = function() end
> class.extend(cls1, "foo", foo)
> ( cls1_methods.foo == foo )
true

```

\subsection*{27.3.6 class.extend_metamethod(class_table, key, value)}

Extends the given class table with the addition of a new key=value pair into the object meta_instance table, where metamethods are stored. It throws an error if the 1st parameter is not a class table. Be careful, several metamethods (__index, __gc) and keys (id, cls) are defined by default in order to implement OOP, overwritten them will produce unexpected errors. The call will throw an error if you try to overwrite any of them. However, __tostring metamethod is also defined but it is totally safe to overwrite it.
```

> cls1,cls1_methods = class("cls1")
>foo = function() return "Hello world!" end
> class.extend_metamethod(cls1, "__concat", foo)
> o = cls1()
> = o .. o
Hello world!

```

\subsection*{27.3.7 value \(=\) class.consult(class_table, key)}

Returns the value associated with the given key at the given class_table. Throws an error if the 1st parameter is not a class table.
```

> cls1,cls1_methods = class("cls1")
> cls1_methods.foo = function() end
> = ( class.consult(cls1, "foo") == cls1_methods.foo )
true

```

\subsection*{27.3.8 value \(=\) class__table .. key}

Equivalent to previous one.
```

> cls1,cls1_methods = class("cls1")
> cls1_methods.foo = function() end
> = ( cls1.."foo" == cls1_methods.foo )
true

```

\subsection*{27.3.9 value \(=\) class.consult_metamethod(class_table, key)}

Returns the value associated with the given key at the given class_table meta_instance (instance metatable). Throws an error if the 1st parameter is not a class table.
```

> cls1,cls1_methods = class("cls1")
>foo = function() return "Hello world!" end
> class.extend_metamethod(cls1, "__concat", foo)
> = ( class.consult_metamethod(cls1, "__concat") == foo )
true

```

\subsection*{27.3.10 value \(=\) class.call(class_table, method, ...)}

Calls a method in a given class_table using the given vararg arguments. It throws an error if the 1st parameter is not a class table or if the given method doesn't exist.
```

> cls1,cls1_methods = class("cls1")
> cls1_methods.foo = function(self) print(self.n) end
> class.call(cls1, "foo", { n=5 })
5

```

\subsection*{27.3.11 boolean \(=\) class.is_class(class__table)}

Returns true/false if the given Lua value is a class table.
```

> cls1,cls1_methods = class("cls1")
> = class.is_class(cls1)
true

```

\subsection*{27.3.12 boolean \(=\) class.is_derived(object)}

Returns true/false if the given instance object is an instance of a derived class.
```

> cls1,cls1_methods = class("cls1")
> cls2,cls2_methods = class("cls2", cls1)
> o1 = cls1()
> o2 = cls2()
> = class.is_derived(o1)
false
> = class.is_derived(o2)
true

```

\subsection*{27.3.13 class_table,methods_table \(=\) class.find(class_name)}

Returns the class table associated with the given class_name.
```

> cls1,cls1_methods = class("cls1")
> aux_cls1,aux_cls1_methods = class.find("cls1")
> = ( cls1 == aux_cls1 and cls1_methods == aux_cls1_methods )

```

\subsection*{27.3.14 class.forget(class__name)}

Removes the given class_name from the auxiliary table of classes, allowing to redifine this class. Notice that the class can't be removed at all because your scripts can have taken the class tables as upvalue, and the instantiated objects will continue working as expected.
```

> cls1 = class("cls1")
> cls1 = class("cls1")
./oop-iter/class.lua:40: cls1 class name exists
stack traceback:
[C]: in function 'assert'
./oop-iter/class.lua:40: in function 'register_class_table'
./oop-iter/class.lua:289: in function 'class'
stdin:1: in main chunk
[C]: in ?
> class.forget("cls1")
> second_cls1 = class("cls1")
> = ( cls1 == second_cls1 )
false

```

\section*{Chapter 28}

\section*{clustering package}

\subsection*{28.1 Introduction}

Package clustering.kmeans.matrix, available in Lua with require("aprilann.clustering.kmeans.matrix"). The package clustering is developed to contain different clustering implementations. Currently, only one is available.

\subsection*{28.2 Package clustering.kmeans.matrix}

This package contains an implementation of k-means clustering designed to be very efficient with large databases (as large as it could be contained in your main memory), but with a small number of clusters.

\subsection*{28.2.1 distortion, centroids = clustering.kmeans.matrix\{ ... \}}

This is the main function of the clustering algorithm. It receives a table with different input arguments, and depending on them, the algorithm could be specialized. The function returns a number with the distortion of the clustering result, and a matrix with the centroids (ordered by rows).

\subsection*{28.2.1.1 Starting from a set of known centroids}

In this case, the function receives a matrix with the initial set of centroids. The given table argument must contain the following fields:
- data: it is a matrix where the data points are ordered by rows.
- centroids: it is a matrix with the initial value of the centroids, oredered by rows.
- max_iter=100: the maximum number of clustering iterations, by default it is max_iter=100.
- threshold=1e-05: the threshold for stopping clustering algorithm, by default it is threshold=1e-05.
- verbose=false: a boolean indicating verbosity.

The algorithm is executed and the given centroids matrix will be updated with the newer centroids, resulting from the clustering algorithm.
```

> data = matrix(5,2):linear()
> clusters = matrix(2,2,{0,0, 1,1})
> = clusters
0
1 1

# Matrix of size [2,2] in row_major [0x1131c30 data= 0x1131d00]

> res, C = clustering.kmeans.matrix{
data = data,
centroids = clusters
}
> = res
3.999998196261
> = C
1 2
6 7

# Matrix of size [2,2] in row_major [0x1131c30 data= 0x1131d00]

```

\subsection*{28.2.1.2 Starting from scratch}

In this case, the algorithm is implemented in two parts, first the refine algorithm published by P.S. Bradley and U.M. Fayyad is used to initialize the centroids matrix. After that, the standard clustering algorithm will be used. The given table argument must contain the following fields:
- data: it is a matrix where the data points are ordered by rows.
- K: a number indicating how many clusters you want to compute using refine algorithm.
- random: a random object used by the refine algorithm.
- subsamples=10: how many random subsamples of the data will be used in the refine algorithm, by default it is subsamples=10.
- percentage=0.01: a percentage of the data used by refine algorithm, by default it is percentage \(=0.01\), that is, a \(1 \%\).
- max_iter=100: the maximum number of clustering iterations, by default it is max_iter=100.
- threshold=1e-05: the threshold for stopping clustering algorithm, by default it is threshold=1e-05.
- verbose=false: a boolean indicating verbosity.

The algorithm is executed and a centroids matrix will be returned.
```

> data = matrix(5,2):linear()
> res,C = clustering.kmeans.matrix{
data = data,
K = 2,
random = random(1234),
}
> = res
3.999998196261
> = C
2 3
7 8

# Matrix of size [2,2] in row_major [0x25d1180 data= 0x25d1250]

```

\subsection*{28.2.2 score, T=clustering.kmeans.matrix.find_clusters(X,C [,T [,verbose]])}

This function classifies \(X\) (a matrix with data) in the closest centroid \(C\) (a matrix with the centroids), and returns the score of the classification and the tags T (a matrixInt32). The function receives positional arguments:
1. X : a matrix with the data ordered by rows ( N rows, D columns).
2. C: a matrix with the centroids ordered by rows (K centroids).
3. T : a matrixInt32 with size Nx 1 , which contains for every row of X the number of its closest centroid. This argument is optional, if not given, a new martrixInt32 will be allocated.
4. verbose=false: a boolean indicating if verbosity is desired. By default it is false
```

> = data
0 1
2 3
4 5
6 7
8 9

# Matrix of size [5,2] in row_major [0x1717960 data= 0x1714f10]

> score,T = clustering.kmeans.matrix.find_clusters(data,C)
> score
-51.4
> = T

```
        1
        1
        1
        2
        2
\# MatrixInt32 of size [5,1] in row_major [0x2862a70 data= 0x282e830]

\section*{Chapter 29}

\section*{knn package}

\subsection*{29.1 Introduction}

The package knn contains algorithms to deal with K-Nearest-Neighbors algorithm. Currently, an implementation based on k -d tree is available, allowing to work with large databases (as far as it could be loaded into main memory), but with low dimensionality.

\subsection*{29.2 Class knn.kdtree}

This class is the basic implementation of the k-d tree for KNN classification. It allows to work with matrices of data (as many matrices as you want). After all the data is given, the tree is built. No insertion or remove operations are implemented, but it is possible to insert new data and build it again if needed. After the tree is ready, it is possible to query for the nearest-neighbor or the K-nearest-neighbors.

\subsection*{29.2.1 Constructor: kdt = knn.kdtree(D,random)}

The constructor receives two values, a number \(D\) with the number of dimensions (columns) of your data, and a random object (used at build method).
```

>D = 6
> kdt = knn.kdtree(D,random(9248))
> = kdt
instance 0x214ad70 of knn.kdtree

```

\subsection*{29.2.2 kdt = kdt:push(matrix)}

This method receives a matrix with data ordered by rows, and returns the caller kdtree object. The matrix pointer is retained by the kdtree, but it is not inserted into the structure, the build method is who will perform the insertion.
```

> rnd = random(1234)
> m1 = matrix(100,D):uniformf(-1,1,rnd)
> m2 = matrix(200,D):uniformf(-1,1,rnd)
> kdt:push(m1)
> kdt:push(m2)

```

\subsection*{29.2.3 kdt = kdt:build()}

This method processes all the given data matrices, and builds the k-d tree structure.
```

> kdt:build() -- after that, it is ready to queries

```

\subsection*{29.2.4 id,distance \(=\) kdt:searchNN(matrix)}

This method allows to query a built kdtree object for the nearest-neighbor. It receives a bi-dimensional matrix with size 1 xD , and returns two values:
- id is the position of the nearest-neighbor. If you take all the pushed matrices ordered by rows, this number is the row corresponding to the sample in the concatenated data.
- distance is a number with the square of the euclidean distance.
```

> id,dist = kdt:searchNN(matrix(1,D):uniformf(-1,1,rnd))
> = id
26
> -- the 26 is located at the first matrix
> = dist
0.49883383064235
> id,dist = kdt:searchNN(matrix(1,D):uniformf(-1,1,rnd))
> = id
178
> -- the 178 is located at the second matrix
> = dist
0.3402419188674

```

\subsection*{29.2.5 point,matrix = kdt:get_point_matrix(id)}

This method receives a number id of a point in the kdtree object (as returned by kdt:searchNN(...) method), and returns a point which is a matrix of size 1 xD with the corresponding point data, and the matrix object where the point is contained. Be careful, this method returns a reference to the original data, any change in the data will led to unexpected behavior of the kdtree object.
```

> NN = kdt:get_point_matrix(id)
> = NN
0.657501 -0.604099 0.426221 -0.421949 -0.32904 0.75809

# Matrix of size [1,6] in row_major [0xc80410 data= 0xc754b0]

> = m2(id-100,':')
0.657501 -0.604099 0.426221 -0.421949 -0.32904 0.75809

# Matrix of size [1,6] in row_major [0xc7ceb0 data= 0xc754b0]

```

\subsection*{29.2.6 result = kdt: searchKNN(K,matrix)}

This method performs the K-Nearest-Neighbors search, using the given K as number of neighbors and the given matrix (with size 1 xD ) as data point. The method returns a table with pairs id, distance.
```

> result = kdt:searchKNN(4,matrix(1,D):uniformf(-1,1,rnd))
> = result
table: 0x197caa0
> for i=1,\#result do print(result[i][1], result[i][2]) end
1520.42534565841526
40 0.54756417013329
101 0.5931407024824
166 0.66157509210318

```

\subsection*{29.2.7 class = knn.kdtree.classifyKNN(result, get_class_function)}

This method receives the result of kdt:searchKNN (...) method and a function which transforms a pattern id in a class. All the result pairs are traversed, computing the corresponding class from each id. The majority vote class will be returned. Normally, the get_class_function will be a function which looks into a dataset, a Lua table, or a matrix, looking for the class of the corresponding id number. In some tasks, because of the order of the data, it is possible to compute the class with a math operation. It depends on your data and your experiment framework how to implement this function.
```

> best_class = knn.kdtree.classifyKNN(result,
function(id) return id%10 end)
> = best_class
2

```

\subsection*{29.2.8 table,cls,best = knn.kdtree.posteriorKNN(result, get_cls_func)}

This method receives the result of kdt:searchKNN(...) method and a function get_cls_func which transforms a pattern id in a class. All the result pairs are traversed, computing the class posterior probability. A table with pairs of \{class,log posterior\} is returned. The posterior is computed considering the negative of euclidean squared distances as log-scores, and normalizing over all the log-scores in the result table. In theory, as more K neighbors were taken, the better posterior will be obtained. However, in practice, with values of K between 10 and 20 could be enough. Note that the posteriors table is traversed using pairs, not ipairs, because two reasons: first, the class identifier could be anything, not only a number, it depends in your get_class_function; and second, even with numeric class, identifiers not all the classes has to be present in the result table, so the posteriors table is not an array, it could contains gaps.

Additionally to the posteriors table, this function returns the maximum posterior cls class and its value best.
```

result = kdt:searchKNN(20,matrix(1,D):uniformf(-1,1,rnd))
posteriors,bestcls,best = knn.kdtree.posteriorKNN(result,
function(id) return id%10 end)
> for c,p in pairs(posteriors) do print(c,p) end
-3.3052420168408
-2.7092774252334
-2.289865236587
-2.4045060888367
-1.8979527591223
-2.0151971414884
-2.0497985519464
-2.2390630830692
-1.6785405659992
-- in this example, the best class is 9, has the maximum posterior
print(bestcls,best)
-1.6785405659992

```

\subsection*{29.2.9 predicted,logp = knn.kdtree.regressionKNN(result, get_tgt_func)}

This function receives a result table and a get_tgt_func, and computes a prediction which is a weighted mean of the neighbors in result, weighted by the posteriors computed in a similar fashion as posteriorsKNN function, but ignoring the marginalization over classes.
The get_tgt_func is a Lua function which receives a training pattern id and returns the target (predicted) value associated with it. The returned value must be an instance of matrix, a Lua table or a Lua number. In any case, the predicted value will be a matrix.

Additionally, this functions returns the the logp with the log-posterior of every neighbor.
```

> function price(id)
-- DO_STUFF
return price_of_id
end
> predicted = knn.kdtree.regressionKNN(result, price)

```

\section*{Chapter 30}

\section*{Hyperparameter Optimization tool}

\subsection*{30.1 Introduction}

Currently, the most widely used hyperparameter optimization technique is grid search. Recently, random search is proposed as an easy method which could obtain interesting good results (competitive with grid search, even better in some tasks) 2012 Bergstra and Bengio.

\subsection*{30.2 Random search hyperparameter optimization}

In APRIL-ANN it is possible to do random search hyperparameter optimization using the script located at:
```

tools/trainable/random-search-hyperparemeter-optimization.lua

```

This scripts receives a configuration Lua file like this:
```

return {
hyperparams = {
{ option="--o1=", value=10, tag="o1", sampling="fixed", hidden=true },
{ option="--o2=", value=20, tag="o2", sampling="fixed" },
{ option="--r1", tag="r1", sampling = "log-uniform",
type="real", prec=3,
values= { { min=0.001, max=1 }, },
filter = function(hyperparams) hyperparams["r1"] = "200" return true end },
{ option="--r2=", tag="r2", sampling = "uniform", values= { 1, 2, 3, 4, 5 } },
{ option="--r3=", tag="r3", prec=3,
sampling = "gaussian", values= { mean=0, variance=0.1 } },
{ option="--r4=", tag="r4", sampling = "random",
filter = function(hyperparams)
if hyperparams["r2"] == "1" then hyperparams["r4"] = "0" end return true
end },
{ option=nil, tag="r5", sampling="random" }
},
filter = function(hyperparams) hyperparams['r5'] = '0.4' return true end,
script = "",
exec = "echo",
working_dir = "/tmp/",
-- seed = ANY_SEED_VALUE (if not given, take random from bash)
n = 50 }

```

The configuration file returns a Lua table which contain some prior knowledge about each hyperparameter (a fully random optimization is unreliable). The table has this major fields:
- hyperparams: a table which describes the prior knowledge of each random searched hyperparameter (note that some of them could be 'fixed' instead of random). Each random hyperparemter is identified by a tag string, a unique option and fields which describe different prior distributions of hyperparameters. The sampling="fixed|uniform|log-uniform|gaussian|random" field indicates if the sampling distribution will be fixed (always the same value), uniform, log-uniform, gaussian, or totally random (this last one is not contrained). The fixed distribution needs a value=SOMETHING field which contains the value of this hyperparameter. The uniform distribution needs a values field which contains a table of values (values \(=\{1,4,8\}\) ) or an array of tables with min/max/step constrains (values=\{ \(\{\min =0\), \(\max =10\), step=2\}, \(\{\min =20, \max =30\), \(s t e p=4\}\}\) ). The log-uniform distribution needs a table with \(\min / \max\) constrains (not step). The field type="real|integer" is only useful for min/max/step values. The field prec=3 indicates the number of precission digits needed. All of them could be hidden=true, indicating that this hyperparameter won't be at the output filename string, but yes at the arguments list. Besides, the 'option' field could be option=nil, indicating that this hyperparameter is a metaparameter which won't be passed as argument to the script, but yes to the filter functions of each hyperparameter and the global filter function. The filter field is a function which returns true or false indicating if this set of hyperparameters is valid, and receives a table indexed by TAGs which contains all top hyperparameter values (it is possible to modify any value at this table).
- filter: is a function which received a dictionary table which associates each tag with its value (a string in all cases, even for integer or real numbers). This function is called just before run an experiment. It checks the validity of hyperparameters returning true, otherwise, the experiment won't be executed, and it modifies any hyperparameter value. NOTE that is recommended to write filter functions which use 'string' type for their modified hyperparameters.
- exec: the executable file, normally an april-ann binary file, but others are possible.
- script: it will be an script given as first argument of the executable.
- working_dir: where to store stdout of each experiment. Each experiment is stored at a filename "WORKING_DIR/output-TAG1:VALUE1_TAG2:VALUE2_TAG3:VALUE3_..._TAGM:VALUEM.log". Hyperparamteres marked as hidden=true won't be used to form this filename.
- seed: an optional random number generator seed.
- n : the number of experiments which will be executed.

The random search executes a script which receives non positional command line options. The option field indicates the string which will be concatenated as prefix of the value. So, if the script needs an option like this: --blah=NUMBER, the field may be: option="--blah=".

An option field could be nil, indicating that this hyperparameter is not used at the script, but it is needed in filter functions.

WARNING!!! variable params of each filter funtion always has string type, in order to ensure that the required number of precission digits is correct. So, you need to use tonumber (hyperparam[TAG]) in order to compare two numbers, and also is recommended to modify hyperaparams using string type values.

\subsection*{30.2.1 Command line execution}

The execution of the procedure follows this syntax:
where ARGS follows this syntax:
ARGS : ARGS [ "all_hyperparams.TAG.value='blah'" | "global_vars.working_dir='blah'" | "global_vars.n=blah" ... ]
where all_hyperparams is a Lua table (associates tag names with hyperparmeter fields) which contains the fixed and randomized parameters of configuration-script.lua, so it is possible to modify any parameter field (option, value/s, sampling, prec, tag, values.min, values.max, ...) from the command line, and global_vars is a Lua table which contains the rest parameters of configuration-script.lua (seed, n, exec, script, working_dir, filter). All this command line arguments must be valid Lua code.

\section*{Chapter 31}

\section*{FAQ}
1. Is it possible to use a larger bunch_size at validation step?
2. Why is SDAE training stopping after the first layer showing an error output of incorrect matrix dimensions?
31.0.1.0.1 Is it possible to use a larger bunch_size at validation step? Yes, it is. A field bunch_size could be defined at the table received by train_dataset and validate_dataset methods of trainable.supervised_trainer objects:
```

trainer:train_dataset{
input_dataset = in_ds,
output_dataset = out_ds,
shuffle = random_object,
bunch_size = 32, -- TRAINING BUNCH SIZE
}
trainer:validate_dataset{
input_dataset = in_ds,
output_dataset = out_ds,
bunch_size = 1024, -- VALIDATION BUNCH SIZE
}

```
31.0.1.0.2 Why is SDAE training stopping after the first layer showing an error output of incorrect matrix dimensions? It is a common mistake, probably you forget to use the parameter which is received by noise_pipeline functions. See this example:
```

INPUT_DATASET = whatever...
noise_pipeline = { function(GIVEN_DS)
return dataset.salt_noise{
ds=INPUT_DATASET, ....
}
end }

```

This example will produce the error, because the INPUT_DATASET is used inside the function defined for noise_pipeline table, and this variable is taken as closure of the function. However, the SDAE procedure
exepcts that you use the GIVEN ARGUMENT ds, which has been prepared to contain the data after training the first Auto-Encoder. So, the code must be like this:
```

    noise_pipeline = { function(GIVEN_DS)
    ```
                        return dataset.salt_noise\{
                            ds=GIVEN_DS, ....
                            \}
    end \(\}\)

\section*{Chapter 32}

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```

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